

## 't Hooft operators in the boundary

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We consider a topologically twisted maximally supersymmetric Yang-Mills theory on a four-manifold of the form  $V = W \times \mathbb{R}_+$ . 't Hooft disorder operators localized in the boundary component at finite distance of  $V$  are relevant for the study of knot theory on the three-manifold  $W$  and have recently been constructed for a gauge group of rank one. We extend this construction to an arbitrary gauge group  $G$ . For certain values of the magnetic charge of the 't Hooft operator, the solutions are obtained by embedding the rank-one solutions in  $G$  and can be given in closed form.

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### I. INTRODUCTION

Maximally supersymmetric Yang-Mills theory in four dimensions admits a topological twisting<sup>1</sup> which leads to localization equations of the form

$$F - \phi \wedge \phi + *d_A \phi = 0 \quad d_A(*\phi) = 0, \quad (1.1)$$

together with<sup>2</sup>

$$d_A \sigma = 0 \quad [\phi, \sigma] = 0 \quad [\sigma, \bar{\sigma}] = 0. \quad (1.2)$$

Here,  $d_A$  is the covariant exterior derivative associated with a connection  $A$  with field strength  $F = dA + A \wedge A$  on the gauge bundle  $E$  (a principal  $G$ -bundle over the four-manifold  $V$  on which the theory with gauge group  $G$  is defined). The other bosonic fields are a one-form  $\phi$  and a complex zero-form  $\sigma$  with values in the vector bundle  $\text{ad}(E)$  associated to  $E$  via the adjoint representation of  $G$ . There is a Lie product understood in the  $\phi \wedge \phi$  term, and  $*$  denotes the Hodge duality operator induced from the Riemannian structure on  $V$ .

As described in Ref. [2], on an open four-manifold  $V$  of the form

$$V = W \times \mathbb{R}_+, \quad (1.3)$$

these equations are relevant to the theory defined on a stack of coincident  $D3$ -branes terminating on a  $D5$ -brane. They must then be supplemented by suitable boundary conditions at both ends of  $V$ . These have been described in Ref. [2] and further elaborated in Ref. [6]. With  $0 < y < \infty$  a linear coordinate on  $\mathbb{R}_+$ , the boundary conditions at infinity state that

$$A + i\phi \rightarrow \rho \quad (1.4)$$

as  $y \rightarrow \infty$ , where  $\rho$  is a fixed flat connection on the complexification  $E_{\mathbb{C}}$  of  $E$ . The boundary conditions at

finite distance are related to an embedding of the tangent frame bundle of  $W$  as a sub-bundle of  $\text{ad}(E)$  via a ‘‘principal embedding’’ of  $\text{SO}(3)$  in  $G$  [7]. Denoting the corresponding images of the vielbein and the spin connection of  $W$  as  $e$  and  $\omega$ , respectively, we have the ‘‘Nahm-pole’’ behavior

$$A \rightarrow \omega \quad \phi - \frac{1}{y}e \rightarrow 0 \quad (1.5)$$

as  $y \rightarrow 0^+$ .

For a generic closed curve  $\gamma$  in  $V = W \times \mathbb{R}_+$ , it is not possible to construct a line operator supported on  $\gamma$  and invariant under the topological supersymmetry. But such operators do exist for  $\gamma$  of the form

$$\gamma = K \times \{0\}, \quad (1.6)$$

where  $K$  is a closed curve in  $W$ . 't Hooft operators of that kind are relevant for the gauge-theory approach to knot theory developed in Ref. [2] and aimed at making contact with the invariants given by the Jones polynomial [8] and Khovanov homology [9]. These operators are labeled by the highest weight  $w$  of a representation of the Langlands dual  $G^{\vee}$  of  $G$ . On the complement of  $K$  in  $W$ , the solution is equivalent to the solution in the absence of the 't Hooft operator up to a ‘‘large’’ gauge transformation. The topological class of this gauge transformation is determined by  $w$ , and for nontrivial  $w$ , it cannot be extended over  $K$ . Together with the requirement that the solution be non-singular in the interior of  $V$ , this determines the asymptotic boundary behavior completely.

For the case when  $G$  is of rank one, i.e.  $G = \text{SU}(2)$  or  $G = \text{SO}(3)$ , explicit model solutions with these properties were determined in Ref. [2] for arbitrary weights  $w$ . The purpose of this paper is to analyze the case of a general  $G$ . We hope that this may be useful for performing explicit calculations along the lines of Ref. [3].

In the next section, we will describe an Ansatz that respects the symmetries of the problem, and in Sec. III, we will discuss how the required boundary behavior determines a particular solution. We will arrive at a fairly good qualitative understanding, although it is only for

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<sup>1</sup>This particular twisting is an element of a  $\mathbb{C}P^1$  family of inequivalent twistings [1,2]; the generalization has also been used in Ref. [3]. There are also two further unrelated possible twistings [4,5].

<sup>2</sup>This second set of equations (1.2) typically forces  $\sigma$  to vanish identically and will not be considered further in this paper.

certain special weights  $w$  that exact solutions (obtained by embedding of the rank-one solutions) can be given in closed form.

## II. THE ANSATZ

We take  $W = \mathbb{C} \times \mathbb{R}$  so that

$$V = \mathbb{C} \times \mathbb{R} \times \mathbb{R}_+, \quad (2.1)$$

which we endow with the standard metric

$$ds^2 = |dz|^2 + dx^2 + dy^2. \quad (2.2)$$

(Here  $z$ ,  $x$ , and  $y$  are standard coordinates on the three factors.) The 't Hooft operator will be localized along

$$K = \{0\} \times \mathbb{R} \times \{0\}, \quad (2.3)$$

i.e. at  $z = y = 0$ .

By a choice of gauge and a certain vanishing theorem [1,2,10], the components of  $A$  and  $\phi$ , respectively, in the direction of  $\mathbb{R}_+$  vanish. Furthermore, we make the Ansatz that the component of  $A$  in the direction of  $\mathbb{R}$  vanishes and that the solution is invariant under translations along  $\mathbb{R}$ . The remaining variables are thus

$$A = A_z dz + A_{\bar{z}} d\bar{z} \quad \phi = \phi_z dz + \phi_{\bar{z}} d\bar{z} + \phi_x dx \quad (2.4)$$

and depend on  $z$ ,  $\bar{z}$ , and  $y$  only. In terms of the components of  $A$  and  $\phi$ , Eqs. (1.1) read

$$\partial_y A_{\bar{z}} = D_{\bar{z}} \phi_x \quad D_{\bar{z}} \phi_z = 0 \quad \partial_y \phi_z = -[\phi_x, \phi_z], \quad (2.5)$$

together with

$$-\partial_y \phi_x = 2F_{z\bar{z}} + \frac{1}{2}[\phi_z, \phi_{\bar{z}}]. \quad (2.6)$$

We postpone the treatment of the ‘‘moment-map’’ equation (2.6) for a while, and start by considering the ‘‘holomorphic’’ equations (2.5). They can be solved by temporarily interpreting  $\phi_x$  as the component of the gauge field in the  $y$  direction and are then invariant under gauge transformations with a parameter valued in the complexification  $G_{\mathbb{C}}$  of  $G$ . Their content is that the covariant derivatives in the  $y$  and  $\bar{z}$  directions annihilate  $\phi_z$  and commute with each other, so the general solution is

$$\phi_z = g \varphi g^{-1} \quad \phi_x = -\partial_y g g^{-1} \quad A_z = -\partial_{\bar{z}} g g^{-1}. \quad (2.7)$$

Here,  $\varphi = \varphi(z)$  is an arbitrary holomorphic function with values in the Lie algebra of  $G_{\mathbb{C}}$ , and the gauge transformation parameter  $g = g(z, \bar{z}, y)$  is an arbitrary function with values in  $G_{\mathbb{C}}$ .

Away from the locus  $z = 0$ , the Nahm-pole boundary condition (1.5) corresponding to a principal embedding requires  $\varphi$  to lie in the ‘‘regular nilpotent orbit’’ (see, e.g Ref. [11]). At  $z = 0$ ,  $\varphi$  must then lie in the closure of the regular nilpotent orbit, but it may define a more special nilpotent conjugacy class. To describe the possibilities, we choose a Cartan torus  $T$  with Lie algebra  $\mathfrak{t}$  in  $G$  and a principal embedding of  $\text{SO}(3)$  in  $G$  with standard generators  $J^1, J^2, J^3$  such that  $J^3 \in \mathfrak{t}$ . The commutation relations of  $J^+ = J^1 + iJ^2, J^- = J^1 - iJ^2$ , and  $J^3$  are

$$[J^3, J^+] = J^+ \quad [J^3, J^-] = -J^- \quad [J^+, J^-] = 2J^3. \quad (2.8)$$

We now take

$$\varphi = h J^+ h^{-1}, \quad (2.9)$$

where

$$h : \mathbb{C}^* \rightarrow T_{\mathbb{C}} \quad (2.10)$$

is a holomorphic homomorphism such that  $\varphi$  has no pole at  $z = 0$ . (Here,  $T_{\mathbb{C}}$  is the complexification of  $T$ .) This means that

$$h = \exp(w \log z), \quad (2.11)$$

where  $w$  is an element of the weight lattice of the Langlands dual group  $G^{\vee}$  (normalized so that  $\exp(2\pi i w) = 1$ ) subject to a certain non-negativity condition. In fact, there is a one-to-one correspondence (up to conjugation) between such  $w$  and highest-weight representations of  $G^{\vee}$ . A solution with this  $\varphi$  defines what we mean by a 't Hooft operator in the corresponding representation inserted at  $z = 0$  in the boundary  $y = 0$ .

As an example, we consider the case where  $G = \text{SU}(n)$  so that  $G_{\mathbb{C}} = \text{SL}(n, \mathbb{C})$ . We choose  $T$  and  $T_{\mathbb{C}}$  to consist of diagonal unimodular  $n \times n$  matrices with complex entries that are of unit modulus or just nonzero, respectively. An arbitrary holomorphic homomorphism  $h : \mathbb{C}^* \rightarrow T_{\mathbb{C}}$  is then of the form

$$h = \begin{pmatrix} z^{w_1} & 0 & \dots & 0 \\ 0 & z^{w_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & z^{w_n} \end{pmatrix} \quad (2.12)$$

with integers  $w_1, w_2, \dots, w_n$  subject to

$$w_1 + w_2 + \dots + w_n = 0. \quad (2.13)$$

Defining the principal embedding by

$$J^3 = \frac{1}{2} \begin{pmatrix} n-1 & 0 & \dots & 0 \\ 0 & n-3 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & -(n-1) \end{pmatrix} \quad J^+ = \begin{pmatrix} 0 & \sqrt{1(n-1)} & 0 & \dots & 0 \\ 0 & 0 & \sqrt{2(n-2)} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \sqrt{(n-1)1} \\ 0 & 0 & 0 & \dots & 0 \end{pmatrix} \quad J^- = (J^+)^\dagger, \quad (2.14)$$

we get

$$\varphi = \begin{pmatrix} 0 & \sqrt{1(n-1)}z^{w_1-w_2} & 0 & \dots & 0 \\ 0 & 0 & \sqrt{2(n-2)}z^{w_2-w_3} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \sqrt{(n-1)1}z^{w_{n-1}-w_n} \\ 0 & 0 & 0 & \dots & 0 \end{pmatrix}, \quad (2.15)$$

so regularity at  $z = 0$  amounts to the non-negativity conditions

$$w_1 \geq w_2 \geq \dots \geq w_n. \quad (2.16)$$

The number of saturated inequalities in Eq. (2.16) determines precisely which nilpotent orbit appears at  $z = 0$ ; the trivial case when  $w_1 = w_2 = \dots = w_n = 0$  gives the regular nilpotent orbit and of course corresponds to a trivial 't Hooft operator.

We now return to the general case and turn our attention to the remaining moment-map equation (2.6). Together with the boundary conditions, this will determine  $g$  uniquely up to an ordinary  $G$ -valued gauge transformation. By exploiting this gauge symmetry, it is sufficient to consider  $g$  of the form

$$g = e^{u-(w+J^3)\log|z|}, \quad (2.17)$$

where  $u = u(z, \bar{z}, y)$  is an element of the Lie algebra  $\mathfrak{t}$  of the Cartan torus  $T$  of  $G$ .<sup>3</sup> We then have

$$\begin{aligned} \phi_x &= -\partial_y u \\ \phi_z &= |z|^{-1} e^{u+(w/2)\log(z/\bar{z})} J^+ e^{-u-(w/2)\log(z/\bar{z})} \\ A_{\bar{z}} &= -\partial_{\bar{z}} u + \frac{1}{2}(w + J^3)\bar{z}^{-1}, \end{aligned} \quad (2.18)$$

and the moment-map equation (2.6) reads<sup>4</sup>

$$(4\partial_z \partial_{\bar{z}} + \partial_y^2)u = |z|^{-2} \frac{1}{2} [e^u J^+ e^{-u}, e^{-u} J^- e^u]. \quad (2.19)$$

This equation is invariant under rotations of the  $z$ -plane around the origin and also under scaling of  $y$  and  $z$  by a

<sup>3</sup>Since there is no factor of  $i$  in the exponent,  $g$  is not an element of  $T$  or even of  $G$  but only of  $G_{\mathbb{C}}$ .

<sup>4</sup>Note that the right hand side is an element of  $\mathfrak{t}$  and, in particular, commutes with the element  $e^{(w/2)\log(z/\bar{z})}$  of  $T$ .

common real positive factor<sup>5</sup>. We seek a model solution that is invariant under such transformations, which means that  $u$  may only depend on  $z$ ,  $\bar{z}$ , and  $y$  in the combination

$$s = |z|/y. \quad (2.20)$$

With this Ansatz, the moment-map equation is equivalent to a system of ordinary differential equations:

$$\left( \left( s \frac{d}{ds} \right)^2 + \left( s^2 \frac{d}{ds} \right)^2 \right) u = \frac{1}{2} [e^u J^+ e^{-u}, e^{-u} J^- e^u]. \quad (2.21)$$

There is clearly a  $2r$ -dimensional space of bulk solutions, where  $r$  is the rank of  $G$ . In the next section, we will discuss the relevant solution picked out by the boundary conditions.

### III. THE SOLUTION

In the vicinity of the two-dimensional surface in  $V$  right above the locus of the 't Hooft operator, we have  $s \rightarrow 0^+$ . In that limit, the general solution to Eq. (2.21) behaves as

$$u = \alpha \log s + \beta + \mathcal{O}(s), \quad (3.1)$$

for some parameters  $\alpha$  and  $\beta$  in  $\mathfrak{t}$ , that must be chosen such that

$$e^u J^+ e^{-u} = \mathcal{O}(s). \quad (3.2)$$

In fact, regularity of  $g$  in this limit requires, according to (2.17), that

$$\alpha = w + J^3 \quad (3.3)$$

so that

<sup>5</sup>These transformations generate the subgroup of the conformal group of  $V$  that leaves the boundary and the locus of the 't Hooft operator invariant.

$$e^u J^+ e^{-u} = s e^{w \log s + \beta} J^+ e^{-w \log s - \beta} = \mathcal{O}(s) \quad (3.4)$$

by the non-negativity condition on the weight  $w$ . For a given  $w$ , the boundary condition as  $s \rightarrow 0^+$  thus leaves us with a codimension  $r$  space of solutions to Eq. (2.21) parametrized by  $\beta$ .

In the vicinity of the boundary of  $V$ , we have  $s \rightarrow \infty$ . In that limit, the Nahm-pole boundary condition requires that

$$u = J^3 \log s + \mathcal{O}(s^{-1}). \quad (3.5)$$

Linearizing Eq. (2.21) around such a solution gives the equation

$$\begin{aligned} & \left( \left( s \frac{d}{ds} \right)^2 + \left( s^2 \frac{d}{ds} \right)^2 \right) \tilde{u} \\ &= s^2 \left( \frac{1}{2} [J^-, [J^+, \tilde{u}]] + \frac{1}{2} [J^+, [J^-, \tilde{u}]] + \mathcal{O}(s^{-1}) \tilde{u} \right) \end{aligned} \quad (3.6)$$

for the first order deviation  $\tilde{u}$ . To analyze this equation, we note that

$$\begin{aligned} & \frac{1}{2} [J^-, [J^+, \tilde{u}]] + \frac{1}{2} [J^+, [J^-, \tilde{u}]] \\ &= [J^3, [J^3, \tilde{u}]] + \frac{1}{2} [J^-, [J^+, \tilde{u}]] + \frac{1}{2} [J^+, [J^-, \tilde{u}]] \end{aligned} \quad (3.7)$$

is given by the adjoint action of the SO(3) quadratic Casimir operator

$$C = J^3 J^3 + \frac{1}{2} J^+ J^- + \frac{1}{2} J^- J^+ \quad (3.8)$$

on  $\tilde{u}$ . The eigenvalues of this action of  $C$  are of the form  $j(j+1)$ , where the  $r$  possible integer values of the spin  $j$  are those that appear in the decomposition of the adjoint representation of  $G$  under the principally embedded SO(3). These possible  $j$ -values (known as the exponents) are given in Table I for all simple Lie groups  $G$ . The spin  $j$  component  $\tilde{u}_j$  of  $\tilde{u}$  should thus obey

$$\left( \left( s \frac{d}{ds} \right)^2 + \left( s^2 \frac{d}{ds} \right)^2 \right) \tilde{u}_j = s^2 (j(j+1) + \mathcal{O}(s^{-1})) \tilde{u}_j. \quad (3.9)$$

Two linearly independent solutions behave as  $s^j$  and  $s^{-j-1}$ , respectively, for large  $s$ . Only the latter is acceptable in view of Eq. (3.5), which leaves us with a codimension  $r$  space of solutions of Eq. (2.21).

Taking the conditions in both limits  $s \rightarrow 0^+$  and  $s \rightarrow \infty$  into account should generically give a discrete set of solutions to Eq. (2.21). Indeed, for a given weight  $w$ , we expect to find a unique solution. The singular behavior of this scale and rotationally invariant model solution defines

TABLE I. Dimensions and exponents of simple Lie algebras.

algebra	dimension	exponents
$A_r$	$r^2 + 2r$	$1, \dots, r$
$B_r$	$2r^2 + r$	$1, 3, \dots, 2r - 1$
$C_r$	$2r^2 + r$	$1, 3, \dots, 2r - 1$
$D_r$	$2r^2 - r$	$1, 3, \dots, 2r - 3, r - 1$
$E_6$	78	$1, 4, 5, 7, 8, 11$
$E_7$	133	$1, 5, 7, 9, 11, 13, 17$
$E_8$	248	$1, 7, 11, 13, 17, 19, 23, 29$
$F_4$	52	$1, 5, 7, 11$
$G_2$	14	$1, 5$

the 't Hooft operator, but further nonsingular terms are allowed to appear when the 't Hooft operator is inserted in a more complicated configuration.

When  $w$  is a multiple of  $J^3$ , i.e. when

$$w = kJ^3 \quad (3.10)$$

for some non-negative integer  $k$ , the model solution is given by embedding the rank-one solution of Eq. [2] in  $G$  and can be given in closed form: We then have

$$u = fJ^3, \quad (3.11)$$

where the real function  $f$  obeys

$$\left( \left( s \frac{d}{ds} \right)^2 + \left( s^2 \frac{d}{ds} \right)^2 \right) f = e^{2f}. \quad (3.12)$$

This ordinary differential equation has a two-dimensional space of solutions, but imposing that

$$f = (k+1) \log s + \text{finite} \quad (3.13)$$

as  $s \rightarrow 0^+$  and

$$f = \log s + \mathcal{O}(s^{-1}) \quad (3.14)$$

as  $s \rightarrow \infty$  determines  $f$  uniquely:

$$f = \log \frac{2(k+1)s^{k+1}}{(\sqrt{1+s^2}+1)^{k+1} - (\sqrt{1+s^2}-1)^{k+1}}. \quad (3.15)$$

For a more general weight  $w$ , it appears that the model solution can only be determined numerically.

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