



Implementing a PCI-Express AMBA interface controller on a Spartan6 FPGA

Master of Science Thesis in Integrated Electronic System Design

Anandhavel Sakthivel

Chalmers University of Technology Department of Computer Science and Engineering Göteborg, Sweden, February 2013 The Author grants to Chalmers University of Technology and University of Gothenburg the non-exclusive right to publish the Work electronically and in a non-commercial purpose make it accessible on the Internet.

The Author warrants that he/she is the author to the Work, and warrants that the Work does not contain text, pictures or other material that violates copyright law.

The Author shall, when transferring the rights of the Work to a third party (for example a publisher or a company), acknowledge the third party about this agreement. If the Author has signed a copyright agreement with a third party regarding the Work, the Author warrants hereby that he/she has obtained any necessary permission from this third party to let Chalmers University of Technology and University of Gothenburg store the Work electronically and make it accessible on the Internet.

Implementing a PCI-Express AMBA interface controller on a Spartan6 FPGA

ANANDHAVEL SAKTHIVEL

© ANANDHAVEL SAKTHIVEL, February 2013.

Examiner: ARNE LINDE

Chalmers University of Technology Department of Computer Science and Engineering SE-412 96 Göteborg Sweden Telephone + 46 (0)31-772 1000

Cover: The cover shows Xilinx Spartan6 FPGA SP605 board

Department of Computer Science and Engineering Göteborg, Sweden February 2013

Abstract

The Purpose of this Master thesis is to integrate the Xilinx PCI-Express interface core to the GRLIB framework. Xilinx Spartan6 Endpoint block for PCI-EXPRESS is generated using Coregen and integrated with the GRLIB framework. The design accounts for crossing clock domains as it is inevitable in a system of chip design with multiple components running at different frequencies. The implementation satisfies the Specification provided by AMBA and PCI-EXPRESS. The performance and area requirement are taken into consideration and different forms of the design is implemented in order to address it. The communication between PC and GRLIB memory environment and the other way around is performed and verified. Simple C codes are developed in order to initiate transfers and also to verify the design. Debugging tools like GRMON, LSPCI and drivers provided by Xilinx are used for analysing and verifying the design. Using GRMON the PCI-EXPRESS debug environment could transfer data at the rate of 120 Mbits/second from PC to the memory of GRLIB. The complete design work was carried out at Aeroflex Gaisler AB.

Keywords: AMBA, LEON3, FPGA, VHDL, Two Process Methodology, DMA, GRLIB, IP core, PCI-EXPRESS, Xilinx, Spartan6.

Contents

1	Intr	oduc	ction	10
	1.1	Bac	kground	10
	1.2	Pur	pose	10
	1.3	Met	hodology	10
	1.4	Out	line	10
2	Haı	dwa	re and Software Tools	11
	2.1	GR	LIB	11
	2.2	AM	BA	11
	2.3	Two	o-process design method	14
	2.4	PCI	-EXPRESS	15
	2.4	.1	Posted and Non-posted	15
	2.4	.2	PCI Configuration Space	15
	2.5	Dev	velopment Platform	16
	2.5	.1	Key Features	16
	2.6	Xili	nx CORE Generator Systems	16
	2.7	Spa	rtan®-6 FPGA Integrated Endpoint Block for PCI Express®	17
	2.7	.1	Core settings for PCI Express wrapper	17
	2.7	.2	Maximum payload size	18
	2.7	.3	Maximum Read Request Size	18
	2.7	.4	Read Completion Boundary	18
	2.7	.5	Bus Mastering	19
	2.7	.6	Error Detection	19
	2.7	.7	Flow control	19
	2.8	Des	igning with the core	20
	2.8	.1	Receiving Packets	20
	2.8	.2	Receive packet throttling	21
	2.8	.3	Transmitting Packets	22
	2.8	.4	Transmit source throttling	23
	2.8	.5	Transmit Destination Throttling	23
3	Imp	olem	entation	25
	3.1	Con	nmon Design techniques	25
	3.1	.1	Endpoint Inputs/outputs	25
	3.1	.2	Clock Synchronisation	25
	3.2	PCI	-EXPRESS Target	25
	3.2	.1	Core settings	26

	3.2.2	Design Details	27
3	.3 PCI	-EXPRESS Master/Target	28
	3.3.1	Design Details	28
3	.4 PCI	-EXPRESS Master Burst Transfer (With FIFO and optional DMA)	30
	3.4.1	Design Details	30
4	Verifica	ition	33
4	.1 Sim	nulation	33
	4.1.1	Simulation libraries	33
	4.1.2	Verification	33
4	.2 Har	dware Verification	34
	4.2.1	PCI-EXPRESS debug interface	34
	4.2.2	Xilinx driver	34
	4.2.3	JTAG and Ethernet for bus mastering and burst transfers	34
5	Discuss	ion	35
6	Conclus	sion	35
7	Future V	Work	36
8	Referen	ces	37
App	endix A	- Transaction Level Packets (TLPs)	38

Acknowledgement

I like to thank my supervisor Jiri Gaisler for giving this opportunity and setting up a wonderful work environment. I like to thank the staffs of Aeroflex Gaisler AB for their technical support and friendly behaviour towards me. Finally, I like to thank my Examiner in Chalmers Arne Linde for his constant support throughout the thesis.

List of Figures

Figure 1 : Example LEON3 system designed with GRLIB [1]	11
Figure 2 : A typical AMBA-based microcontroller [4]	12
Figure 3: AMBA AHB/APB conceptual view [1]	12
Figure 4: AHB inter-connection view page [1]	13
Figure 5 : APB inter-connection view [1]	
Figure 6 : Generic two-process circuit [5]	
Figure 7: Layering Diagram	15
Figure 8: Xilinx SP605 Board Features [2]	
Figure 9: TLP 3-DW Header without Payload [7]	21
Figure 10: TLP 3-DW Header with Payload [7]	
Figure 11 : User Application Throttling Receive TLP [7]	22
Figure 12: TLP with 3-DW Header with Payload [7]	22
Figure 13: Source throttling on the Transmit Data path [7]	23
Figure 14: Destination throttling on the Transmit Data path [7]	24
Figure 15: Interfacing PCI-EXPRESS to the GRLIB	26
Figure 16: Address translation from PCI-EXPRESS bus address to AMBA Address	27
Figure 17: PCI-EXPRESS Master/Target implementation	28
Figure 18: Address translation from PCI-EXPRESS bus address to AMBA Address	29
Figure 19: PCI-EXPRESS Master Burst Transfer implementation	30
Figure 20: Two port sync RAM and its interface	31

List of Tables

Table 1: BRAMS required according to performance and MPS selection	17
Table 2: Configuration dcommand [7:5] value	
Table 3 : Configuration dcommand [14:12] value	
Table 4: Configuration lcommand[3] value	19
Table 5: configuration dstatus register and correponding error representation	
Table 6: Available transmit buffers[7]	
Table 7: Required BRAMS corresponding to Performance and MPS selection	
1 1 0 0	

Abbreviations

AHB Advanced High-performance Bus - AMBA standard bus for High-performance AMBA Advanced Microcontroller Bus Architecture - On-Chip Communication Bus APB Advanced Peripheral Bus - AMBA standard bus for Low-power peripherals ASB Advanced System Bus - AMBA standard bus for High-performance ATX Advanced Technology Extended - motherboard form factor specification **BRAM** Block Random Access Memory - Type of memory used in FPGA CPU Central Processing Unit - main component of Computer **DDR** Double Data Rate - Type of memory DMA Direct Memory Access - access system memory independent of CPU. **DW** Double Word - 32 bits FIFO First In First Out - Type of data Access **FMT** Format of TLP - Specifies the TLP type FPGA Field Programmable Gate Array - Integrated circuit configurable by User GRLIB Gaisler Research Library - Library consist of IP cores, scripts for tools etc **GRMON** Gaisler Research Debug Monitor - Debugging GT Giga Transfer - Unit for data transfer GUI Graphical User Interface - Used in tools for providing settings **IP** Intellectual Property - Portable and reusable design cores JTAG Joint Test Action Group - Design Interface MB Mega Bytes - Unit for data transfer MPS Maximum Payload Size - amount of Payload appended in a packet PCI Peripheral Component Interconnect - Design Interface **RCB** Read Completion Boundary - Value significant for receiving data **SRAM** Static Random-Access Memory - type of memory SPARC Scalable Processor Architecture - type of Architecture used by LEON Processor SPI Serial Peripheral Interface Bus - Design Interface TLP Transaction Level Packets - Headers and Data Packets in PCI-EXPRESS transfers **UART** Universal Asynchronous Receiver/Transmitter - Design Interface VHDL Very High Speed Integrated Circuits Hardware Description Language - Description for defining hardware

1 Introduction

1.1 Background

Aeroflex Gaisler AB provides GRLIB IP Library a set of reusable IP cores freely available in open-source. The library consists of LEON3 SPARC V8 processor, PCI, USB host/device controllers, DDR and Ethernet interfaces etc. The library supports different vendors, Synthesis, Simulation tools and target technologies. AMBA on-chip bus is used as the standard communication interface between the GRLIB cores [1].

1.2 Purpose

The Purpose of this thesis is to interface the Xilinx PCI-Express interface core to the GRLIB framework. The Xilinx PCI-Express controller is generated by the Coregen tool, and uses hard macros on the Xilinx FPGA's. The work consists of bridging the custom interface on the PCI-Express core with the AMBA AHB on-chip bus used in GRLIB. The PCI-Express/AMBA interface should be implemented in VHDL and assembled with the PCI-Express core. The interface is connected finally in a complete LEON3/GRLIB system. The board is inserted on a PCI-Express slot of a PC motherboard and communication should be made between the PC and GRLIB framework. The communication between the devices is supported with both single and burst transfers of the AMBA. Two- Process design style is used for implementing the entire system. This style is chosen in order to achieve the benefits associated like efficient simulation, synthesis, maintenance, easy code analysis and debugging[5].

1.3 Methodology

The Work splitted into study, developing specification for wrapper, implementation, analysis and verification and carried out step by step. The study period mainly consist of understanding the functionality of PCI-EXPRESS core, PCI-EXPRESS specifications, AMBA specifications and understanding the GRLIB framework. After the study period the requirements are clear and specifiations for the wrapper is developed. The implementations are made as per the requirement, further they are analysed for improvements and verified for proper functionality.

1.4 Outline

The Hardware and sotware tools details is provided in the section 2, explaining about GRLIB, AMBA plug and play, two-process design method, Xilinx Spartan6, PCI-Express core properties and specification used, section 3 describes implementation details of PCI-Express/AMBA interface controller. Section 4 consists of details about debugging using GRMON and verification in simulation and hardware. Section 5, 6 and 7 are Discussions, Conclusions and Future work respectively.

2 Hardware and Software Tools

This chapter explains the tools used for implementing the design, hardware settings available and designing with the Endpoint core. This chapter also explains different options available from the tools.

2.1 GRLIB

GRLIB consist of reusable IP cores supporting different target technologies and CAD tools. AMBA on-chip bus is used for central communication. GRLIB uses unique plug and play for connecting different components of the system. The library is constructed to be vendor independent. Makefiles are used to create simulation and synthesis scripts for different vendors. *Figure 1* shows an example template design with several components of a systemon-chip.



Figure 1 : Example LEON3 system designed with GRLIB [1]

Some of the Features available in GRLIB are Plug and play (the ability to detect available system hardware through software), Distributed address decoding (to avoid dependencies on a global resource) and Portability (Technology independent). For further details please refer to GRLIB IP Library User's Manual [1].

2.2 AMBA

GRLIB AMBA on-chip bus is in compliance with AMBA specification 2.0. Three different buses are available as per specification Advanced High-performance Bus (AHB), Advanced

System Bus (ASB) and Advanced Peripheral Bus (APB). GRLIB uses AHB for high performance and high clock frequency and APB for low power peripherals. *Figure 2* shows a typical example of AMBA and peripheral system [4].



Figure 2 : A typical AMBA-based microcontroller [4]

Figure 3 below shows how the system is divided into masters, slaves and connected through AMBA. A single AHB slave is used to implement AHB/APB bridge. AHB slave2/APB master represents AHB/APB bridge and it is the only APB master. By placing multiple AHB/APB bridges several APB buses can be achieved.



Figure 3: AMBA AHB/APB conceptual view [1]

Figure 4 shows how masters and slaves are divided and controlled by a global bus control for AHB interconnection, details about input and output signals also provided. The signals in

figure below are composed of record types. Details about the signals are available in GRLIB IP Library User's Manual [1].



Figure 4: AHB inter-connection view page [1]

Figure 5 shows APB interconnection with details about input and output signals. The signals in figure below are composed of record types. Details about the signals are available in GRLIB IP Library User's Manual [1].



Figure 5 : APB inter-connection view [1]

For further details please refer to AMBA specification[4].

2.3 Two-process design method

The dataflow style of coding would result in difficulty for reading and understanding the code because of numerous number of concurrent statements and processes. Low abstraction level and longer simulation time are other difficulties associated with the dataflow method. Two-process coding method helps to overcome these difficulties. Meanwhile to overcome these difficulties some simple measures like using record types in all signal declarations, two-processes per entity and high level sequential statements[5]. *Figure 6* shows two-process design methodology.



Figure 6 : Generic two-process circuit [5]

Only two processes combinational (asynchronous) and sequential (registers) are used. The complete design can be coded sequential in the combinational process and sequential process updates the state using registers.

Following advantages are achieved by two-process design methodology

- Structured and readable VHDL code
- Efficient simulation and synthesis
- Easy code analyses and maintenance
- Higher abstraction level
- Simplified debugging and analysis

For further details please refer to two- process design documentation[5].

2.4 PCI-EXPRESS

PCI-EXPRESS is a computer expansion bus standard which replaces the older PCI and PCI-X bus standards. The standard specifies the architecture in three layers which are transaction, data link and physical layers. *Figure 7* shows the layering arrangement. PCI-EXPRESS uses packets to transfer information between devices. The packets are formed and passes along different layers collecting additional information's, similarly the reverse happens at the receiving end. Some works done by layers are transaction level packets generation and analysis, data protection, flow-control, error detection, serialization and de-serialization. The PCI-EXPRESS is backward compatible with the existing PCI software model [6].



Figure 7: Layering Diagram

2.4.1 Posted and Non-posted

During write operations, the packets are formed and given to the data link layer and the write transaction is completed. This type of transaction is Posted transaction. In read operation, from the requester the packets are formed and given to data link layer. The requester should wait for the respective completions. This type is non-posted transaction.

2.4.2 PCI Configuration Space

From the configuration space for PCI-EXPRESS, important registers like status, command, device status, device control, link control and link status are given to the user application through configuration ports. Apart from those, user application can read the complete configuration space. The user application cannot write into the configuration space. The root port can write and read the entire configuration space.

2.5 Development Platform

The template design used for this thesis is available in GRLIB which is leon3-Xilinx-SP605. The leon3-Xilinx-SP605 template design contains IP cores for memory interface, user interface like JTAG, USB, Ethernet and several other components. *Figure 8* below shows the Xilinx Spartan-6 FPGA SP605 evaluation board used in this thesis. The board has PCI-EXPRESS x1 edge connector (single lane) which is inserted into the PCI-Express slot of the motherboard.



Figure 8: Xilinx SP605 Board Features [2]

2.5.1 Key Features

- Spartan-6 FPGA XC6SLX45T-3C in FGG484 package
- 128 MB DDR3 memory
- 32 MB parallel (BPI) flash memory
- 8Kb IIC EEPROM
- 8 MB Quad SPI flash memory
- 10 Mb/s, 100 Mb/s, 1,000 Mb/s Ethernet
- GTP transceiver port (TX, RX) with four SMA connectors
- PCI Express® x1 edge connector
- 12V wall adapter or ATX power supply

Configuration can be performed using onboard JTAG configuration circuitry, 8 MB Quad SPI flash memory; 32 MB Parallel (BPI) flash memory and 2 GB Compact Flash (CF) memory card [3].

2.6 Xilinx CORE Generator Systems

Xilinx CORE Generator system helps to reduce the design time by providing optimized intellectual properties (IP) for Xilinx FPGAs. Spartan®-6 FPGA Integrated

Endpoint Block for PCI Express® core is generated using Coregen and used in this design to implement the PCI-EXPRESS/AMBA interface controller.

2.7 Spartan®-6 FPGA Integrated Endpoint Block for PCI Express®

Spartan®-6 FPGA Integrated Endpoint Block for PCI Express® core was generated using Coregen and used in this design to implement the PCI-EXPRESS/AMBA interface controller.

2.7.1 Core settings for PCI Express wrapper

The core is configured by appropriately setting in GUI.

Device/Port type: PCI Express Endpoint device

Base Address Registers: Base Address Registers have two purposes. First it specifies the amount of address space required for the device in the system memory map. Secondly the BIOS or OS programmes base address registers with the assigned addresses for the device which gives information to perform address decoding for the device. In this core there are 6 Base Address Registers available for 32 bit BARs, the address range can be as small as 128 bytes for memory or 16 bytes for I/O. 2 gigabytes is the maximum address range [7].

ID values: Vendor ID- Specifies the manufactures of the device. Identifiers are given by PCI Special Interest Group for uniqueness.

Device ID- Identifier for the application can be any value.

Max Payload Size: The maximum data payload that can be appended along with other headers for a write transmission. The maximum data payload can be 128, 256 or 512 bytes. The final value for this is written in the device control registers by the BIOS. The values are explained in section 2.7.2

BRAM configuration options: The performance level can be set to good or high based on the amount of Header and Data credits needed for transmission. The amount of TLP buffers needed for transmission is also depends on performance level. The BRAMs used depends on these performance level settings as well as the Max payload size. The *table 1* shows the BRAMs requirements according to performance and MPS selection

MPS (bytes)	Performance	BRAMs Required
128	Good	2
	High	4
256	Good	4
	High	8
512	Good	8
	High	18

Table 1: BRAMS required according to performance and MPS selection

The core supports link speed of 2.5 GT/s with width single lane (x1). The reference clock frequency used is 125 MHz .The PCI-EXPRESS specification version 1.1 is used for building the core.

2.7.2 Maximum payload size

The device control registers specifies amount of data which can be sent as a payload. The root complex sets the device control registers after the link is trained, even though we requested for a specific maximum payload size using the software GUI. The root complex driven value can be less than or equal to the advertised capacity selected.

Configuration dcommand [7:5] signal which is available to the user application gives the value of MPS as shown in *table 2*.

Configuration dcommand [7:5]	MPS(bytes)
000b	128
001b	256
010b	512

Table 2: Configuration dcommand [7:5] value

2.7.3 Maximum Read Request Size

The amount of data which can be requested by the user as payload is given by the device control registers. The root complex sets the device control registers after the link is trained, even though we requested for a specific maximum read request size using the software GUI. The root complex driven value can be less than or equal to the advertised capacity selected. Configuration dcommand [14:12] signal which is available to the user application gives the value of Maximum Read Request Size as shown in *table 3*.

Configuration dcommand [14:12]	Maximum Read Request Size
	(bytes)
000b	128
001b	256
010b	512

<i>Table 3</i> :	Configuration	dcommand	[14:12] value
------------------	---------------	----------	---------------

2.7.4 Read Completion Boundary

The requested data can be answered with multiple completions. The number of completions depends on the amount of data requested and Read completion boundary. Read completion boundary value is written on the device control register Configuration lcommand (3). *Table 4* shows the valve in configuration lcommand register and associated bytes value.

Cfg_lcommand[3]	Bytes
0	64
1	128

Table 4: Configuration lcommand[3] value

The Completions are quantised in a way the payload starts and end at an aligned RCB length except when completions of starting or ending are serviced. Detailed explanation of RCB is given at section 3.4.1 under Multiple completions for burst read.

2.7.5 Bus Mastering

The endpoints can write and read the CPU memory directly like a Root Complex. For this the bus master bit configuration command (2) should be enabled. This bit is enabled during the link training. The configuration command bit is available for user application to determine whether the bit is enabled or not. If configuration command bit is enabled then memory or I/O requests can be generated.

2.7.6 Error Detection

The configuration dstatus is available for user application to determine the internal state of the system. When any error conditions occurs it is reflected in the device status registers as shown in *table 5*

Configuration dstatus(0)	Correctable Error Detected
Configuration dstatus(1)	Non-fatal Error Detected
Configuration dstatus(2)	Fatal Error Detected
Configuration dstatus(3)	Undefined Request Detected

Table 5: configuration dstatus register and correponding error representation

2.7.7 Flow control

Receive Buffer Credits

The buffers credits available in endpoints are available to the user application from the following signals trn_fc_ph, trn_fc_pd, trn_fc_nph, trn_fc_npd, trn_fc_cplh and trn_fc_cpld[11:0].

As per PCI-EXPRESS specification, Endpoints should advertise infinite credits available for completions. The user application should implement logics not overflowing the available completion credits. The completion credits reduce when a completion is received after read request from the endpoint. The read requests have to be cautiously sent from endpoint without emptying the completion credits and therefore producing an infinite completion possibility.

Transmit Buffer

The number of available transmit buffers is given by the signal trn_tbuf_av. A single buffer can hold a maximum sized TLP which is 4DW of headers and maximum payload size data. The buffers are exclusive for a single transfer i.e. even if there is a single 32 bit memory read request which needs only 3DW header that will occupy a single TLP buffer. The TLP's are not shared. The *table* 6 shows available buffers as per MPS and performance level selection made in the GUI of Coregen.

Maximum Payload Size	Performance Level	
(bytes)	Good	High
128	13	27
256	14	29
512	15	30

Table 6: Available transmit buffers[7] Image: Comparison of the second seco

The trn_tbuf_av can fluctuate without any packet transmission from the user application; the buffers are also shared with configuration management module (CMM). The configuration management module generates completion packets when configuration writes or reads, interrupts and message transfers occurs.

2.8 Designing with the core

The Core generated Sparan6 endpoint device has control and data transfer signals which has to be connected to the user application. The control signals like start of frame, end of frame should be properly given at proper timings along with data to make a successful transmission. Below sections explain about the control and data signal interfacing with the user application.

2.8.1 Receiving Packets

For receiving a packet the headers and payload data should be available at sequences with proper control signals asserted at right time.

The user application should assert trn_rdst_rdy_n when it is ready to accept a new packet. The core asserts trn_rsrc_rdy_n and trn_rsof_n together and provides the initial frame on trn_td. When final frame is sent trn_reof_n is asserted. The *figures 9 and 10* shows read request and write request respectively. The headers are described in *Appendix A*.







Figure 10: TLP 3-DW Header with Payload [7]

2.8.2 Receive packet throttling

When the user application is not ready to process incoming requests, it can throttle the requests by deasserting trn_rdst_rdy_n. The trn_rdst_rdy_n can be deasserted for any length of time and can be desserted any time, even during middle of a TLP reception. The *figure 11* explains throttling using trn_rdst_rdy_n.



Figure 11 : User Application Throttling Receive TLP [7]

2.8.3 Transmitting Packets

The core assert trn_tdst_rdy_n when it is ready to accept a new packet, the user application should asserts trn_tsrc_rdy_n and trn_tsof_n together providing the initial frame on trn_td. During final frame trn_teof_n is asserted. The *figures* 12 shows a write request. The headers are described in *Appendix A*.





Figure 13: Source throttling on the Transmit Data path [7]

2.8.4 Transmit source throttling

The user application can throttle transmitting if it don't have data on the consecutive clock cycles. This is done by deasserting trn_tsrc_rdy_n as shown in *figure 13*.

2.8.5 Transmit Destination Throttling

When the internal transmit buffers (see section 2.7.7 for transmit buffers) are not available the core can throttle the transmission by deasserting trn_tdst_rdy_n as shown in *figure 14*. The trn_tbuf_av gives the number of buffers available for the transmission. By asserting trn_tdst_rdy_n the core accepts start of frame and also it guarantees it will accept the entire TLP with the Payload available in it.



Figure 14: Destination throttling on the Transmit Data path [7]

3 Implementation

This chapter explains implementation of different design versions like Target, Master and Master with FIFO. The implementations are made with emphasis on performance and area. The interfaces associated with AMBA are different in each designs are explained in detail. The chapter also explains about some common design techniques followed for all the different wrappers implemented.

3.1 Common Design techniques

Pin out I/O and timing constraints are given similar to the user constraints available in the example design generated from Coregen, as the design constraints should exactly match the specification given in the GUI of Coregen. The power is obtained by the DC power supply or through 12V ATX power supply, power connections available in PCI-EXPRESS edge connector are not used [8]. The slot clock Configuration is enabled allowing the Endpoint to use platform provided physical reference clock available on the PCI-EXPRESS edge connector.

3.1.1 Endpoint Inputs/outputs

The PCI-EXPRESS cores inputs and outputs are grouped according to the functions they perform as Record types and they are listed below.

- inputs and outputs from user application
- Flow control Gives the amount of buffers available for Posted, completions and nonposted transactions to the user design.
- Configuration Species the user status and command configuration of the device, error control and interrupt handling etc.

3.1.2 Clock Synchronisation

Clock synchronisation is performed using handshaking with double stage synchronizers which provides immunity to the possible meta-stability occurrence. The Generic nsync is set to two for double stage synchronisation.

3.2 PCI-EXPRESS Target

The PCI-EXPRESS Target is the simplest of all the implementation using lesser hardware resources. The design cannot perform burst transfer and it can only act as a slave to the Root Complex. Writes or reads cannot be generated from the endpoint block. The PCI-EXPRESS Target acts as a slave to system Root complex. It accepts the memory read and write request from upstream components through Root complex. The Target generated completions as a response to read requests are sent to the upstream components through Root complex. The user application uses AHB Master Configuration to access the memory space of Leon3 system. AHB Master is interfaced along with the PCI-EXPRESS core to configure a new master in the GRLIB system.

The wrapper consist of Core generated PCI-EXPRESS core and interface to the AMBA onchip bus, along with techniques like clock synchronisation and byte twisting. The implemented design is based on the Two Process design style and Inputs and Outputs are grouped as record types for easy debugging and implementations. The two process technique is explained at section 2.3. The *figure 15* shows different blocks of PCI-EXPRESS Target implementation along with GRLIB components.



Figure 15: Interfacing PCI-EXPRESS to the GRLIB

3.2.1 Core settings

The Core generator can be configured to generate a Spartan6 Endpoint block with the needed settings. The GUI from core generator tool helps to give proper settings for the core to be generated.

Base Address Registers:

Type: Memory 32 bits (For PCIE Target only)

Size: 2 Megabytes (The base address register can be configurable through generics which can be in the range of 128 bytes to 2 Gigabytes)

Max Payload Size: 128 bytes. BRAM configuration Performance option: Good

MPS (bytes)	Performance	BRAMs Required
128	Good	2
	High	4

Table 7: Required BRAMS corresponding to Performance and MPS selection

No user configuration and extended configuration space is implemented.

Details about core settings are explained in section 2.7.1 all other settings apart from the mentioned above are set to default.

3.2.2 Design Details

- The user design uses clock (trn_clk) provided by the PCI-EXPRESS endpoint core Frequency 62.5 Mhz. Similarly trn_reset from the Endpoint is used for user design reset. When main system_reset is asserted for the endpoint or when link disabled it is set asynchronously.
- All top interfaces to the PCI-EXPRESS core like system clock, System reset, data Input and outputs are channelled through this wrapper. Similarly the inputs and outputs needed for the AMBA interface is also accessed.
- The AMBA interface consist of reset, Clock, AHB master input and AHB master output where these are all connected through respective signal's from the top main.
- Byte-Twisting is performed as the PCI-EXPRESS data transfer is in big endian format.
- Address translation: The address space allocated for the PCI-EXPRESS memory is divided into two halves. Access to the upper half writes AHB address register and access to the lower half is forwarded to internal AHB access. The internal access address is formed by taking significant part from the AHB address register and the remaining original address provided for access. The *figure 16* explains the mechanism.

Upper half access writes to the AHB address register

AHB Address[31:abits-1]	Unused (abits -2 to 0)

Lower half access the memory

AHB Address[31:abits-1]	Original Address from Root complex

Figure 16: Address translation from PCI-EXPRESS bus address to AMBA Address

The abits are made as generics in order to account if memory ranges are changed in PCI-EXPRESS bars.

3.3 PCI-EXPRESS Master/Target

The PCI-EXPRESS Master/Target can act as master or slave to the AMBA, corresponding to target or Master to the PCI-EXPRESS interface. The GRLIB system through any of its master can generate memory request using the PCI-EXPRESS master interface, bus mastering should be enabled to perform this communication. The *figure 17* shows different blocks of PCI-EXPRESS Master/Target implementation.





The core settings are similar to PCI-EXPRESS Target implementation.

3.3.1 Design Details

The communication from root port to the GRLIB frame work remains same as explained in section 3.2, all the techniques used like address decoding, clock synchronisation and byte twisting remains the same. The details about ability of the core to generate memory transaction (bus mastering) are explained below.

• The PCI-EXPRESS Master block contains the necessary logic for creating the memory transaction level packets (TLPs). The packets are generated when AHB slave block gets inputs from any of the masters in GRLIB framework.

- The AMBA interface consist of reset, Clock, AHB slave input and AHB slave output. The AHB slave block controls the communication with hresponse, hready and some other signal as per AMBA Protocol.
- The APB registers specified is used for register access associated with PCI-EXPRESS. The PCI-EXPRESS bus address to which the memory transaction has to be performed is given by a register PCIBA. The PCIBA can be accessed through APB and configured with the needed address as shown in *figure 18*.



Accessed through APB Registers

Figure 18: Address translation from PCI-EXPRESS bus address to AMBA Address

The width of PCIBA can be adjustable according to the generics provided in the core which is dependent on the memory space window provided for the PCI-EXPRESS.

- The bus master bit configuration command (2) should be enabled for bus mastering. This bit is enabled during the link training. The configuration command is available for user application to determine whether the bit is enabled or not.
- The availability of transmit buffer is checked before every start of transmission.
- Endpoints are required to advertise an infinite amount of completion space which can be achieved by sending read requests according to the available completion buffers(applicable when Endpoint act as master)[7]. The condition is satisfied by checking availability of completion headers before every new read request.
- The APB access is also used for monitoring internal registers when debugging using GRMON [9].

3.4 PCI-EXPRESS Master Burst Transfer (With FIFO and optional DMA)

The PCI-EXPRESS Master Burst Transfer is capable of generating burst of transfer from GRLIB framework to the upstream root complex. The wrapper has a FIFO to act as buffers for the transfer and an optional DMA. *figure 19* depicts different blocks associated with this design.



Figure 19: PCI-EXPRESS Master Burst Transfer implementation

3.4.1 Design Details

- The core can handle burst transaction generated from GRLIB masters as well as the normal single writes and reads. The difference between burst and single operations are identified using hburst signal from AHB slave inputs.
- The burst transfers are generated when AHB slave block gets requests from any of the masters in GRLIB framework. The resulting datas from the burst transfer are loaded into the FIFOs. The PCI-EXPRESS Master block contains the necessary logic for creating the burst memory transaction level packets (TLPs).

- The DMA controller shown in *figure* 19 can be configured using APB interface to start burst of transfer. The DMA registers can be configured with burst starting address, length, destination address. After configuration when the start is asserted burst transfer occurs. Optional interrupt can also be set to indicate end of communication. When DMA engine is not in work the core can perform burst transfer from other masters, the address translation for these masters are similar to the address translation explained at section 3.3.1 (figure 18) using APB.
- The AMBA interface consist of reset, Clock, AHB slave input and AHB slave output. The AHB slave block controls the communication with hresponse, hready, hburst, htrans and some other signal as per AMBA Protocol.
- The write and read have separate FIFOs where each is split into 2 halves. Syncram 2P Two port RAM from GRLIB is used for the FIFOs. The FIFO is of 32 (double words) depth and separate clocks AMBA and PCI-EXPRESS clocks are used. The *figure 20* shows the interfacing of FIFO which is inbetween the AMBA AHB slave and PCI-EXPRESS Master.



Figure 20: Two port sync RAM and its interface

 Burst write - As soon as first half of FIFO is fully written by AHB slave interface the PCI-EXPRESS master empties it, at the same time AHB slave interface keeps on writing till the second half gets filled. When the second half is also full PCI-EXPRESS master empties everything in the FIFO. When these happens the access to FIFO from AHB slave interface gets retry response.

- Burst read- When AHB slave gets a read burst request it is transformed into PCI-EXPRESS burst read. As soon as first half of FIFO is fully written by PCI-EXPRESS master the AHB slave interface empties it, at the same time PCI-EXPRESS master keep on writing to the second half. After the second half is full AHB slave interface empties it. When AHB slave is waiting for the PCI-EXPRESS master to fill it gives retry response.
- Multiple completions for burst read The number of completions received for a burst read request is based on Read completion boundary value available in control registers (see section 2.7.4). The core is designed for Read completion boundaries of 64 bytes. Every burst read request is of size 128 bytes (32 DW) can be completed either with two 64 bytes completions or 3 completions of variable payload. Two or three completions depends on the address from which the request starts. For example a 128 byte (32 double word) address request start from 0x00000000 the completions are received as two 64 byte (16 double words each) at 0x00000000 and 0x00000040 starting addresses. If the 128 byte (32 double word) address request start from 0x00000004, three completions are received 60 byte (15 DW), 64 byte (16 DW) and 4 byte (1 DW) at 0x00000004, 0x00000040 and 0x00000044 starting addresses. Basically the return completions are quantized according to the Read Completion Boundaries. The core takes care of this multiple completions using the received length and byte count value available with the completion TLPs .
- 4k Address Crossing- The address and length of read or write request should not cross 4k address boundary as per PCI-EXPRESS specification, if this case occurs the TLPs are not processed by the endpoint and not further pass to the root port resulting in malfunction of the system. The core handles this by splitting the burst into before crossing and after crossing whenever an address crossing occurs.

4 Verification

Logic Simulation and Hardware implementation are performed to verify the working of the system. Modelsim is used for simulation and Xilinx Spartan6 is used for hardware implementation. Simulation is performed with the help of simulation environment provided by Coregen generated endpoint block for PCI-EXPRESS, AMBA test framework from GRLIB and using the available testbench in the Xilinx SP605 template design. Hardware analysis is assisted by Debugging tools like GRMON, LSPCI and drivers provided by Xilinx.

4.1 Simulation

The simulation environment provided along with Xilinx endpoint block is integrated to the GRLIB framework to simulate the traffic. The simulation environment provided helps to generate traffic from root port and accept completions associated with it. If the traffic is generated from GRLIB (bus mastering) the simulation environment provided won't respond for any TLPs reaching it.

4.1.1 Simulation libraries

The complete simulation libraries needed for Modelsim environment is generated using Xilinx ISE and stored in the PC. The Modelsim.ini file present in the template design is modified to access the libraries needed for simulation. The secure p and unisim files already available in GRLIB under GRLIB/lib/tech are disabled.

4.1.2 Verification

The functionality of PCI-EXPRESS target is verified by Writing to an address and reading from the same address and comparing weather both of them are same. The other cores which have bus mastering capability the functionality was not completely verified using simulation as the root port don't return any TLP's for request from GRLIB framework. The functionality for PCI-EXPRESS master is only verified partially by generating TLPs and checking whether the datas are channelled through AMBA properly and send it to the PCI-EXPRESS core, the notion of generation of TLP's and possible answers are manually generated and verified. For example instead of sending the read request to the upper layers of PCI-EXPRESS, the completions are manually done and results are given and verified for correctness.

For generating simple single write and read traffic from GRLIB framework prom.s file is modified to generate memory request. Sparc assembly is used for generating the traffic using prom.s. Similarly while generating traffic from DMA, prom file is used for giving fetch, destinations address, length and start. AMBA test framework is used for generating burst transfer, the ATF is instantiated into the GRLIB framework and used for generating AMBA burst read and write traffic.

4.2 Hardware Verification

The descriptions are synthesized and a bitstream is generated using Xilinx tools for testing the system. The bitstream are flashed into the FPGA and analysed. GRMON is used as a debug monitor for the GRLIB framework, which can be used to read/write system memory and registers, downloading, executing LEON applications etc. The debug links like USB, JTAG, RS232, PCI, Ethernet and Space wire are supported by GRMON.

4.2.1 PCI-EXPRESS debug interface

The software features associated with PCI is completely compatible with PCI-EXPRESS, so the supporting features GRMON provides for PCI is available for PCI-EXPRESS as well. The PCI-EXPRESS target can act as a debug interface for the GRLIB framework. PCI-EXPRESS debug environment could transfer data at the rate of 120 Mbits/second from PC to the memory of GRLIB.

4.2.2 Xilinx driver

The drivers provided by Xilinx memory endpoint test driver [refer xapp1022] is used for simple transfer of data from PC to GRLIB framework and vice versa. The application C files are modified to transfer from PC to GRLIB, similarly the device driver files are modified to place a buffer memory space in the PC memory to write read and verify while bus mastering.

4.2.3 JTAG and Ethernet for bus mastering and burst transfers

Simple C codes are written in order to generate traffic. JTAG and Ethernet is used for loading the executables into the system and execute it for transfers. The write are made followed by reading then compared weather they are the same or not. For verifying burst transfers using DMA similar C code giving details about fetch, destinations address, length and start is used. The Ethernet is used for generating burst transfers, mem and bload commands in GRMON are used in order to achieve burst transfers.

5 Discussion

The works specified according to the specification are implemented, verified and performance evaluation was carried out step by step and analysed. Whenever necessary the specifications are modified and adapted with implementations to make improvements in performance or hardware resource utilization. The respinning was quiet time consuming as a simple change in specifications resulted in reiteration of implementation and complete verification. The number of versions of wrapper makes it complicated if a common specification for each design is modified. The Two-Process design style used for implementing the system helped greatly while simulating and analysing the design. The code is readable and can be maintained easily because of the structured coding style resulting from two process design. The advantages available from GRLIB in implementation, simulation and debugging are extensively utilized to make this working module.

6 Conclusion

The purpose of this Master thesis to integrate the Xilinx PCI-Express interface core to the GRLIB framework was fulfilled. The work is carried out with performance and area requirement in mind. The different forms of the design is implemented in order to address for every need. The design is made in accordance with specifications provided by AMBA and PCI-EXPRESS. The difficulties arised like clock synchronisation, boundary crossing and tool related issues are addressed properly and a working module is implemented on the Xilinx Spartan6 board. Possible changes like timing and I/O contrainsts to the Xilinx SP605 GRLIB template design is made to make the PCI-EXPRESS work along with other components of GRLIB framework.

The board inserted into the PCI-Express slot of a PC motherboard and communication is made between the PC and GRLIB framework and also the other way around. The communication between devices is supported with both single and burst transfers of the AMBA. The Example simulation environment provided with PCI-EXPRESS core helped to verify the system using modelsim simulation. The Hardware design is verified and analysed using drivers from Xilix and GRMON debug environment .

7 Future Work

The performance achieved by this design can be improved by several means. The PCI-EXPRESS Master Burst Transfer which has hardcode FIFO depths, the FIFO depths can be made variable and faster burst transfer can be achieved. Other features of PCI-EXPRESS like interrupts can be added to this design. The unavailability of simulation response when the PCI-EXPRESS core act as master results in complicating the implementation and through simulation only partial verification can be achieved, this can be rectified by incorporating root module which respond to request given by GRLIB PCI-EXPRESS Master. Further all the cores only support word trasfers, logic can be added to support byte tranfer.

8 References

[1] GRLIB IP Library User's Manual. Version 1.1.0 B4113 January, 2012 http://www.gaisler.com/products/grlib/grlib.pdf

[2] Xilinx SP605-Hardware Setup Guide, http://www.xilinx.com/support/documentation/boards_and_kits/xtp089.pdf

[3] Xilinx SP605 Getting Started Guide ug525, http://japan.xilinx.com/support/documentation/boards_and_kits/ug525.pdf

[4] AMBA Specification Revision 2.0. ARM Limited. 1999.

[5] Gaisler, J. Fault-tolerant Microprocessors for Space Applications. Gaisler Research.

[6] PCI-EXPRESS Base 1.1 Specification. PCI-SIG.

[7] Xilinx Spartan-6 FPGA Integrated Endpoint Block for PCI Express User Guide, http://www.xilinx.com/support/documentation/user_guides/s6_pcie_ug654.pdf

[8] Xilinx SP605-Hardware Setup Guide, http://www.xilinx.com/support/documentation/boards_and_kits/ug526.pdf

[9] GRMON User's Manual. Version 1.1.51. *Aeroflex Gaisler AB*. November, 2011, <u>http://www.gaisler.com/doc/grmon.pdf</u>

Appendix A - Transaction Level Packets (TLPs)

Write TLPs

The figure below shows an example write TLP (4 DWs) which has 3 headers and a data field using 32 bit addressing.

31	30 29	28 27 26 25 24	23	22 21 20	19 18 17 16	15	14	13 12	11 10	9	8	7	6	5	4	3	2	1	0	
R	Fmt	Туре	R	TC	Reserved	Т	Ε	Attr	R					Le	ng	th				
						D	Р													
	Requester ID							Tag Last I										First DW		
]	DV	V B	BE		ł	BE				
	Address[31:2]]	R				
					Data	[31:0]														

First DW:

R-Reserved

Fmt	TLP Format							
00	No data, 3 DW header							
01	01 No data, 4 DW header							
10	3 DW header and data							
11	4 DW header and data							

FMT and TLP format

TLP	Fmt	Туре
Memory Read	00 or 01	00000
Memory Write	10 or 11	00000
I/O Read	00	00010
I/O Write	10	00010
Completion	10	01010

FMT and type for respective TLPs

Fmt and Type field together indicates whether it is a Read, Write or completion TLP.

TC - Traffic class

TD - Presence of TLP digest at the end of TLP is indicated by setting this bit 1b.

EP – Indicates Poisoned TLP

Length – Indicates the data payload length in DWs.

Second DW:

Requester ID

Bus Number	Device Number	Function Number
7:0	4:0	2:0

Used for reporting back errors during write but significant during reads.

Tag -No significance during writes

First DW BE - Indicates which four bytes are significant in the first DW of the data payload

Last DW BE - Indicates which four bytes are significant in the last DW of the data payload

Third DW: Contains 30 most significant address bits and 2 reserved bits which should be zero.

Fourth DW: Single DW of data.

Read TLPs

The figure below shows an example read TLP (3 DWs).

31	30 29	28 27 26 25 24	23	22 21 20	19 18 17 16	15	14	13 12	11 10	9	8	7	6	5	4	3	2	1	0
R	Fmt	Туре	R	ТС	Reserved	Т	Ε	Attr	R	Length									
						D	Р												
		Requ	ester	· ID				Tag		•				ast		I	Firs		W
	DW BE												1	BE					
	Address[31:2]]	R			

The Read TLP request is similar to the write TLP with few differences. Only the differences are discussed below.

Second DW :

The Requester Id specifies where to send the completion of a read request. Tag – This field can be given any value but it is useful for the requester to keep track of the completions coming back.

Completion TLP

The figure below shows an example Completion TLP (4 DWs) which has 3 headers and a data field using 32 bit addressing.

31	30 29	28 27 26 25 24	23	22 21 20	19 18 17 16	15	14	13	12	11 10	9	8	7	6	5	4	3	2	1	0
R	Fmt	Туре	R	TC	Reserved	Т	Ε	Att	r	R					Le	eng	gth			
						D	Р													
Completer ID							Completion B Byte Count													
						S	tatus													
									Μ											
Requester ID								7	Гад				I	R 1	Lov	ve	r A	dd	lres	5
					Da	ta[31	:0]													

The First DW is similar to read/write request.

Second DW:

Completer Id - sender of the packet

Completion status - Indicates completion status

BCM- Set by PCI-X completers not set by PCI-EXPRESS completers.

Byte count- The amount of bytes pending for transmission including the available data in the current payload, useful if multiple completions are expected.

Third DW:

Requester ID and Tag – similar to read request Lower Address – least seven bits of the requested address.