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# On BICM-ID with Multiple Interleavers

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**Abstract**—In this letter, we study the performance of BICM-ID with multiple interleavers (BICM-ID-M) in terms of bit-error rate (BER), and show that BICM-ID-M is well-suited to exploit the unequal error protection (UEP) caused by the binary labeling. We show that BICM-ID-M should *always* be the preferred alternative for BICM-ID and that the gains obtained appear even for the simplest configuration (0.5–0.75 dB for a BER of  $10^{-7}$ ). It is found that conventional design paradigms such as maximizing the free distance of the code should be modified.

**Index Terms**—BICM, BICM-ID, M-interleavers, UEP.

## I. INTRODUCTION

**B**IT-INTERLEAVED coded modulation (BICM) was introduced in [1], analyzed in [2], [3], and is nowadays the preferred alternative for CM over the Gaussian and fading channels [3, Sec. 1]. Its flexibility makes it very attractive and it has made its way into a large number of communication standards [3, Sec. 1]. By recognizing BICM as a serial concatenation of codes, *BICM with iterative decoding* (BICM-ID) was introduced in [4]–[6]. BICM-ID exhibits a waterfall and an error floor region, and it has been well studied in the literature, cf. [7] and references therein. In BICM-ID, the binary labeling plays a key role and its optimization usually targets a decrease of the BER in the error floor region.

The original papers introducing BICM [1] and BICM-ID [4] postulated the application of multiple interleavers (M-interleavers) connecting each of the encoder's output to one modulator's input. However, most of the existing literature on BICM and BICM-ID follows the framework set in [2] and assumes the use of one single interleaver (S-interleavers). BICM with M-interleavers were analyzed in [8] and shown to offer gains when the modulation introduces UEP.

In this letter, we study the error floor of BICM-ID-M. We prove that BICM-ID-M asymptotically *always* outperforms BICM-ID with S-interleavers (BICM-ID-S) and that the gains obtained by using BICM-ID-M instead of BICM-ID-S appear even for the simplest configuration. We show that conventional design paradigms for the encoder, e.g., the use of optimum distance spectrum (ODS) codes [9], should be modified.

Manuscript received March 26, 2010. The associate editor coordinating the review of this letter and approving it for publication was Vladimir Stankovic.

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This work was partially supported by the European Commission under projects NEWCOM++ (216715) and FP7/2007-2013 (236068), by the Swedish Research Council, Sweden (2006-5599), and by the FQRNT (Merit Scholarship Program for Foreign Students), Canada.

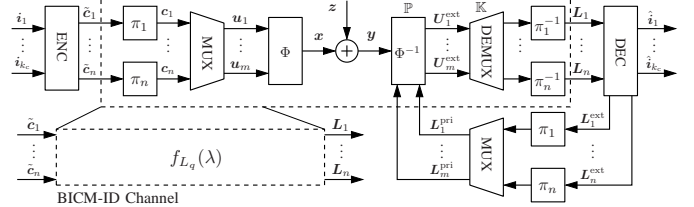


Fig. 1. BICM-ID model. The equivalent BICM channel is also shown.

TABLE I  
THE THREE MOST RELEVANT CONFIGURATIONS DEFINED BY  $\mathbb{K}$ .

MUX	Configuration obtained	Analyzed in
$\mathbb{K} = m^{-1} \mathbb{1}_m$	S-interleavers	[2]
$\mathbb{K} = \mathbb{I}_m$	Original M-interleavers	[1], [4]
$\mathbb{K} = \Pi(\mathbb{I}_m)$	Optimized M-interleavers	[8]

## II. SYSTEM MODEL AND PRELIMINARIES

### A. System Model

The BICM-ID system model is presented in Fig. 1, which can be considered a generalization of [8, Sec. II-A]. The vectors of information bits  $\mathbf{i}_s$  with  $s = 1, \dots, k_c$  are encoded by a rate  $R_c = k_c/n$  convolutional encoder. The vectors of coded bits  $\tilde{c}_i$  with  $i = 1, \dots, n$  are fed to the interleavers  $\pi_1, \dots, \pi_n$  which give statistically independent randomly permuted sequences  $\mathbf{c}_i = \pi_i(\tilde{c}_i)$ . The multiplexing unit (MUX) assigns the bits  $\mathbf{c}_i$  to the different bit positions in the symbol. We define the MUX using an  $n \times m$  matrix  $\mathbb{K}$ , whose elements,  $0 \leq k_{iq} \leq 1$ , represent the probability that a bit from  $\mathbf{c}_i$  is assigned to the  $q$ th output  $\mathbf{u}_q$  with  $q = 1, \dots, m$ . For simplicity, and since we are interested in the original BICM(-ID) configuration(s), from now on, we only consider  $n = m$  and  $k_{iq} \in \{0, 1\}$ . The three most relevant configurations in this case are shown in Table I, where  $\mathbb{1}_m$  and  $\mathbb{I}_m$  are the all-ones and the identity matrices, respectively, and where  $\Pi(\cdot)$  is a row permutation (see more details in [8]).

At any time instant  $t$ , the codeword  $\mathbf{b} = [u_{1,t}, \dots, u_{m,t}]$  is mapped to a complex constellation symbol  $x \in \mathcal{X}$  using a memoryless mapping  $\Phi: \{0, 1\}^m \rightarrow \mathcal{X}$ , where  $\mathcal{X} \subset \mathbb{C}$ , and  $|\mathcal{X}| = 2^m$ . We analyze phase shift keying (M-PSK) modulation, i.e.,  $x_j = \exp(-\frac{2\pi j\sqrt{-1}}{M})$  with  $j = 1, \dots, M$ ; extension to other modulations is straightforward. The symbols are transmitted through an AWGN channel  $y = x + z$ , where  $z$  is a circularly-symmetric complex Gaussian random variable with zero-mean and variance  $N_0/2$  in real/imaginary parts. The bit energy-to-noise ratio is  $\frac{E_b}{N_0} = \frac{1}{N_0 k_c}$ . The demapper computes extrinsic L-values as  $U_q^{\text{ext}}(y) = U_q^{\text{pos}}(y) - L_q^{\text{pri}}$ , where  $U_q^{\text{pos}}(y) \triangleq \log \frac{\Pr\{b_q=0|y\}}{\Pr\{b_q=1|y\}}$  and  $L_q^{\text{pri}} \triangleq \log \frac{\Pr\{b_q=0\}}{\Pr\{b_q=1\}}$  are the a posteriori and a priori L-values for  $b_q$ , respectively.

Let  $\mathcal{D} \triangleq \{d_1, \dots, d_D\}$  be the set of squared Euclidean distances between the constellation points, where  $D = \frac{M}{2}$  for  $M$ -PSK. For example, for 8-PSK  $D = 4$ ,  $d_1 = 0.58$ ,  $d_2 = 2$ ,  $d_3 = 3.41$ , and  $d_4 = 4$ . The generalized Euclidean distance spectrum (GEDS) of a constellation (see also [7, Ch. 4]) is defined by the  $m \times D$  matrix  $\mathbb{P}$  whose entries  $p_{ql}$  are the number of pairs (normalized by  $M/2$ ) of constellation points at distance  $d_l$  such that their binary labelings differ in all the bit position except in the  $q$ th one. We also define the generalized minimum Euclidean distance (GMED) of the constellation by  $d_q^{\min}$  with  $q = 1, \dots, m$ , which corresponds to the squared Euclidean distance associated to the first nonzero element in the  $q$ th row of  $\mathbb{P}$ . For example, for 4-PSK ( $D = 2$ ,  $d_1 = 2$ ,  $d_2 = 4$ ) only two labelings with different GEDS exist: the Gray code (GC) and the anti-Gray code (AGC) [7, App. A]. The GEDS of the AGC is given by  $p_{1,1} = p_{2,2} = 1$ ,  $p_{1,2} = p_{2,1} = 0$ ,  $d_1^{\min} = 2$  and  $d_2^{\min} = 4$ , and for the GC by  $p_{1,1} = p_{2,1} = 1$ ,  $p_{1,2} = p_{2,2} = 0$ ,  $d_1^{\min} = d_2^{\min} = 2$ .

### B. Perfect Feedback and the BICM-ID Channel

We use the so-called perfect feedback (PF) assumption to analyze the error-floor region. This assumption states that after a certain number of iterations, and for a sufficiently high signal-to-noise ratio (SNR), it can be assumed that the a-priori L-values are large enough so that the demapper knows all the bits except the one for which it is calculating the extrinsic L-value. This transforms the detection of the high-order modulation into the detection of binary symbols, and thus, the extrinsic L-values calculated by the demapper  $\Phi^{-1}$  can be shown to be Gaussian-distributed [7, Ch. 4].

For a given transmitted symbol  $x$  labeled by  $\mathbf{b} = [b_1, \dots, b_m]$ , it can be shown that  $U_q^{\text{ext}}(y|x) \sim \mathcal{N}(\mu, 2|\mu|)$ , where  $\mu = N_0^{-1}(-1)^{b_q}d$  and where  $d \in \mathcal{D}$ . Therefore, there exist  $D$  Gaussian distributions that can be used to model the extrinsic L-values, where  $d$  depends on the transmitted symbol and the bit position, i.e.,  $d = d_l$  only if  $p_{ql} \neq 0$ . The probability density function (pdf) of  $L_q$  is then given by

$$f_{L_q}(\lambda) = \sum_{l=1}^D g_{ql} \Phi(\lambda; \mu_l, 2\mu_l), \quad (1)$$

where  $\Phi(\lambda; \mu, \sigma^2)$  is a Gaussian function,  $g_{ql}$  is the  $(q, l)$ th entry of the  $m \times D$  matrix  $\mathbb{G} \triangleq \mathbb{K}\mathbb{P}$  which represents the probability that the  $q$ th L-value is Gaussian distributed with parameters  $(\mu_l, 2\mu_l)$ , and where  $\mu_l = N_0^{-1}d_l$  (assuming  $b_q = 0$ ). Expression (1) states that the L-values passed to the decoder (cf. the output of the BICM-ID channel in Fig. 1) are modeled using a Gaussian mixture, where the structure of the matrix  $\mathbb{K}$  determines the weights  $g_{ql}$  of the Gaussian mixture in (1). Using (1), we replace the BICM-ID channel by a symmetric binary-input soft-output memoryless channel as shown in Fig. 1.

### C. Union Bound

Let  $\beta^{\mathcal{C}}(\mathbf{w})$  be the generalized weight distribution spectrum of a convolutional encoder, where the *generalized weight*  $\mathbf{w} = [w_1, \dots, w_m]$  gathers the weights  $w_q$  of each of the encoder's

outputs, and where  $\beta^{\mathcal{C}}(\mathbf{w})$  can be calculated as described in [8, Sec. III-A]. The (truncated) union bound (UB) is given by

$$\text{BER} \leq \text{UB} = \sum_{\mathbf{w} \in \mathcal{W}} \beta^{\mathcal{C}}(\mathbf{w}) \text{PEP}(\mathbf{w}), \quad (2)$$

where  $\mathcal{W} \triangleq \{\mathbf{w} \in (\mathbb{N}_0)^m : \omega^{\text{free}} \leq \sum_{q=1}^m w_q \leq \hat{\omega}\}$ ,  $\mathbb{N}_0$  is the set of nonnegative integers,  $\omega^{\text{free}}$  is the free distance of the code,  $\hat{\omega}$  is the truncation of the UB, and  $\text{PEP}(\mathbf{w})$  is the probability of detecting a sequence with generalized weight  $\mathbf{w}$  instead of the transmitted all-zero sequence.

For a given  $\mathbf{w}$ , the decision variable passed to the decoder is  $S(\mathbf{w}) = S(w_1) + \dots + S(w_m)$  where  $S(w_q) = \sum_{i=1}^{w_q} L_q^{(i)}$ , and where  $L_q^{(i)}$  are i.i.d. random variables with a pdf given by (1). Let  $\binom{w_q}{\mathbf{r}_q} \triangleq \frac{w_q!}{r_{q1}! \dots r_{qD}!}$  be the multinomial coefficients which represents the number of different ways of ordering  $w_q$  bits in subsets of  $r_{q1}, \dots, r_{qD}$  elements, where  $\mathbf{r}_q \triangleq [r_{q1}, \dots, r_{qD}]$ .

*Theorem 1:* The pdf of  $S(\mathbf{w})$  can be expressed as

$$f_{S(\mathbf{w})}(\lambda) = \sum_{\mathbb{R} \in \mathcal{R}(\mathbf{w})} \prod_{q=1}^m \binom{w_q}{\mathbf{r}_q} \prod_{l=1}^D (g_{ql})^{r_{ql}} \Phi(\lambda; \Delta(\mathbb{R}), 2\Delta(\mathbb{R})),$$

where  $\mathbb{R} \triangleq [\mathbf{r}_1^T, \dots, \mathbf{r}_m^T]^T$ ,  $\Delta(\mathbb{R}) \triangleq N_0^{-1} \sum_{q=1}^m \sum_{l=1}^D d_l r_{ql}$ ,  $\mathcal{R}(\mathbf{w}) \triangleq \{\mathbb{R} \in \mathbb{N}_0^{m \times D} : \sum_{l=1}^D r_{ql} = w_q, q = 1, \dots, m\}$ , and we interpret  $0^0$  as 1.

*Proof:* Because of the interleaving, the L-values are independent, and thus, the pdf of  $S(w_q)$  is the convolution of  $w_q$  copies of the Gaussian mixture in (1), i.e.,

$$f_{S(w_q)}(\lambda) = \sum_{\mathbf{r}_q \in \mathcal{V}(w_q)} \binom{w_q}{\mathbf{r}_q} \prod_{l=1}^D (g_{ql})^{r_{ql}} \Phi(\lambda; \delta_q, 2\delta_q),$$

where  $\mathcal{V}(w_q) \triangleq \{\mathbf{r}_q \in (\mathbb{N}_0)^D : \sum_{l=1}^D r_{ql} = w_q\}$ , where the  $l$ th element in  $\mathbf{r}_q$  represents the number of bits transmitted using the  $l$ th Gaussian distribution and  $\delta_q = N_0^{-1} \sum_{l=1}^D d_l r_{ql}$ . The pdf of  $S(\mathbf{w})$  is obtained by convolving the densities  $f_{S(w_q)}(\lambda)$ ,  $q = 1, \dots, m$ , which completes the proof. ■

By computing  $\text{PEP}(\mathbf{w})$  as the tail integral of the pdf given by Theorem 1, the following UB expression is obtained.

*Corollary 2:* The UB in (2) can be expressed as

$$\text{UB} = \sum_{\mathbf{w} \in \mathcal{W}'} \sum_{\mathbb{R} \in \mathcal{R}'(\mathbf{w})} W^{\mathcal{C}}(\mathbb{R}, \mathbb{G}, \mathbf{w}) Q\left(\sqrt{\Delta(\mathbb{R})/2}\right). \quad (3)$$

In (3)  $\mathcal{W}' \triangleq \{\mathbf{w} \in \mathcal{W} : \beta^{\mathcal{C}}(\mathbf{w}) \neq 0\}$ ,  $\mathcal{R}'(\mathbf{w}) \triangleq \{\mathbb{R} \in \mathcal{R}(\mathbf{w}) : (g_{ql})^{r_{ql}} \neq 0 \forall q, l\}$ , and

$$W^{\mathcal{C}}(\mathbb{R}, \mathbb{G}, \mathbf{w}) = \beta^{\mathcal{C}}(\mathbf{w}) \prod_{q=1}^m \binom{w_q}{\mathbf{r}_q} \prod_{l=1}^D (g_{ql})^{r_{ql}}. \quad (4)$$

The definitions of  $\mathcal{W}'$  and  $\mathcal{R}'(\mathbf{w})$  guarantee  $W^{\mathcal{C}}(\mathbb{R}, \mathbb{G}, \mathbf{w}) \neq 0$  for any  $\mathbf{w} \in \mathcal{W}'$  and  $\mathbb{R} \in \mathcal{R}'(\mathbf{w})$ . Clearly, the multiplexing  $\mathbb{K}$  affects only the inner product in (4).

## III. MAIN RESULTS AND CONCLUSIONS

### A. BICM-ID-M with 4-PSK

In Fig. 2 we show the BER performance of BICM-ID-M and BICM-ID-S for one of the simplest configurations one could think of, i.e., 4-PSK with the AGC and a rate  $R_c = 1/2$  ODS

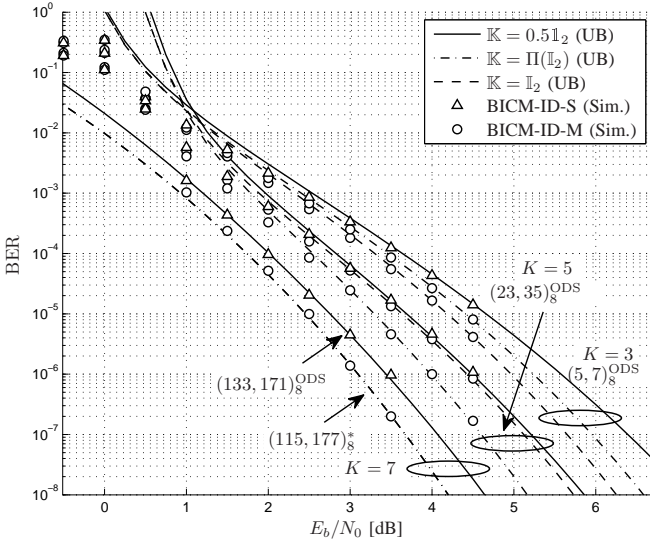


Fig. 2. BER performance of BICM-ID-M and BICM-ID-S. The simulation results are shown with markers and the bound in (3) with lines.

convolutional code [9] of constraint lengths  $K = 3, 5$  (the results for  $K = 7$  will be discussed in Sec. III-C). The bound in (3) is shown to agree with the simulations results, and gains of 0.5–0.75 dB are obtained for a BER of  $10^{-7}$  if  $\mathbb{K}$  is properly selected. We note that the optimum  $\mathbb{K}$  depends on the code, and that for each  $K$ , the two BICM-ID-M configurations give a lower BER than BICM-ID-S. In the following subsection, we will prove that this is asymptotically always the case.

### B. Optimality of BICM-ID-M

The UB given by Corollary 2 is a sum of weighted Q-functions. We are interested in the behavior of (3) for high SNR, and thus, the arguments of the Q-functions become relevant. We consider constellations with a GEDS such that  $d_q^{\min} \neq d_{q'}^{\min}$  for some  $q, q'$ , i.e., constellations that introduce UEP (e.g., 4-PSK with the AGC). We define  $\bar{d}$  as the smallest element in the GMED of the constellation, i.e.,  $\bar{d} \triangleq \min_{q \in \{1, \dots, m\}} \{d_q^{\min}\}$ .

*Lemma 3:* The arguments of the dominant Q-functions in the UB (3) for a given  $w \in \mathcal{W}'$  are

$$\Delta_M^* \triangleq N_0^{-1} \sum_{q=1}^m d_q^{\min} w_q, \quad \Delta_S^* \triangleq N_0^{-1} \bar{d} \sum_{q=1}^m w_q,$$

for BICM-ID-M and BICM-ID-S, respectively.

*Proof:* For BICM-ID-M,  $\mathbb{G}_M = \mathbb{P}$ , and therefore, the solution of  $\min_{\mathbb{R} \in \mathcal{R}'(w)} \{\Delta_M(\mathbb{R})\}$  is obtained when  $\mathbb{R}$  is such that all the  $w_q$  bits are transmitted using the Gaussian distribution associated to  $d_q^{\min}$ ,  $\forall q$ . With this, we obtain the expression for  $\Delta_M^*$ , which holds for any  $\mathbb{G}'_M = \Pi(\mathbb{G}_M)$ . For BICM-ID-S,  $\mathbb{G}_S = m^{-1} \mathbb{1}_m \mathbb{P}$ . This matrix has a first column with a nonzero entry determined by  $\bar{d}$ . Moreover, all the elements in this column are identical (and nonzero), and therefore, the solution of  $\min_{\mathbb{R} \in \mathcal{R}'(w)} \{\Delta_S(\mathbb{R})\}$  is obtained when all the  $w_q$  bits are transmitted using the Gaussian distribution associated to  $\bar{d}$ ,  $\forall q$ . Using this, we obtain the expression for  $\Delta_S^*$ , which concludes the proof. ■

*Corollary 4:* For high SNR and a given code  $\mathcal{C}$ , the UB for BICM-ID-M is always smaller than the UB for BICM-ID-S.

The proof of Corollary 4 follows directly from the inequality  $\Delta_M^* > \Delta_S^*$  which holds for any  $w$ . Corollary 4 states that, for high SNR, BICM-ID-M should always be preferred over BICM-ID-S, even if the MUX is not optimized. This conclusion does not hold for (noniterative) BICM, cf. [8].

### C. Optimal Convolutional Codes

Corollary 2 allows us to express the asymptotic behavior of the UB for the pair  $[\mathcal{C}, \mathbb{K}]$  as  $UB \approx Q\left(\sqrt{\frac{A^d}{2N_0}}\right)$ , where  $A^d$  is the argument of the dominant Q-function in the UB, i.e., the smallest  $\Delta(\mathbb{R})$  for the pair  $[\mathcal{C}, \mathbb{K}]$ . In the following, we define the optimum convolutional codes (OCC).

*Definition 1 (OCC for BICM-ID):* A convolutional code  $\mathcal{C}^*$  is said to be optimal if there exists a  $\mathbb{K}^*$  such that, among all the other codes with the same constraint length and MUX configurations, the pair  $[\mathcal{C}^*, \mathbb{K}^*]$  gives the largest  $A^d$ .

Definition 1 considers both the MUX and the code as one entity, and does not assume  $\mathcal{C}^*$  to belong to the set of codes with maximum free distance, which we denote by  $\omega_{\max}^{\text{free}}$ . An exhaustive search showed that for  $K = 5, 6$  ( $\omega_{\max}^{\text{free}} = 7, 8$ ) there exist many codes with  $\omega_{\max}^{\text{free}} = \omega_{\max}^{\text{free}} - 1$  that perform equally good as the ODS codes, i.e., they give the same  $A^d$ . For  $K = 7, 9$  ( $\omega_{\max}^{\text{free}} = 10, 12$ ), this happens for codes with  $\omega_{\max}^{\text{free}} = \omega_{\max}^{\text{free}} - 2$ , which shows that maximizing  $\omega_{\max}^{\text{free}}$  is not the criterion that defines optimal codes in this scenario.

The OCCs are defined asymptotically, which does not assure their optimality for a finite SNR. Alternatively, we can use (3) for a given SNR and search for a good pair  $[\mathcal{C}, \mathbb{K}]$ . As an example, we performed an exhaustive search for the optimal  $[\mathcal{C}^*, \mathbb{K}^*]$  at  $\frac{E_b}{N_0} = 3.5$  dB for  $K = 7$  and  $\hat{\omega} = \omega_{\max}^{\text{free}} + 5$ , cf. (2). We found the code  $(115, 177)_8$  ( $\omega_{\max}^{\text{free}} = 8$ ) and  $\mathbb{K}^* = \Pi(\mathbb{I}_2)$  to be optimal. Its performance is presented in Fig. 2. Gains of 0.5 dB for BER =  $10^{-6}$  are obtained when compared with the most common configuration, i.e., BICM-ID-S and the ODS code with  $\omega_{\max}^{\text{free}} = 10$ .

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