

DISCRETENESS EFFECTS IN Λ CDM SIMULATIONS: A WAVELET-STATISTICAL VIEW

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ABSTRACT

The effects of particle discreteness in N -body Λ CDM simulations are still an intensively debated issue. In this paper we explore such effects, taking into account the scatter caused by the randomness of the initial conditions and focusing on the statistical properties of the cosmological density field. For this purpose, we run large sets of Λ CDM simulations and analyze them using a wide variety of diagnostics, including new and powerful wavelet statistics. Among other facts, we point out (1) that dynamical evolution does not propagate discreteness noise up from the small scales at which it is introduced and (2) that one should aim to satisfy the condition $\epsilon \sim 2d$, where ϵ is the force resolution and d is the inter-particle distance. We clarify what such a condition means and how to implement it in modern cosmological codes.

Subject headings: cosmology: miscellaneous — dark matter — large-scale structure of universe — methods: n -body simulations — methods: numerical — methods: statistical

1. INTRODUCTION

N -body simulations are becoming a more and more powerful tool for investigating the formation of structure in the universe. Since this is a grand-challenge problem with a huge dynamic range, it is of basic importance to understand just how significant numerical effects are in cosmological simulations. This is becoming even more important now, with the advent of precision cosmology, which aims at breaking the degeneracy of cosmological models and providing accurate determination of the cosmological parameters, at the few-percent level. The difficult task for simulations will then be to determine error bars in the output data, taking into account not only the uncertainty of the measurements themselves but also numerical effects, which enter the simulation model and propagate during its evolution.

Many recent investigations have focused on the effects of particle discreteness in Λ CDM simulations. In fact, the number of particles N determines two important quantities: the mass resolution and the wavelength of the highest-frequency mode included in the initial conditions. Such quantities, together with the force resolution and other more technical factors, affect the halo mass function and the statistical properties of the cosmological density field (see, e.g., Splinter et al. 1998; Knebe et al. 2000; Hamana et al. 2002; Smith et al. 2003; Teodoro & Warren 2004; Warren et al. 2006; Hansen et al. 2007; Joyce & Marcos 2007a; Baertschiger et al. 2008; Bagla & Prasad 2008; Tinker et al. 2008), as well as the halo density profile and the dynamics of structure formation (e.g., Knebe et al. 2000; Binney & Knebe 2002; Power et al. 2003; Binney 2004; Diemand et al. 2004; Heitmann et al. 2005; Zhan 2006; Joyce & Marcos 2007b; Vogelsberger et al. 2008). Wang & White (2007) have shown that discreteness effects are even more important in simulations of hot or warm dark matter, in which the initial power spectrum has a natural high-frequency cutoff at a relatively long wavelength. So why another contribution concerning Λ CDM simulations? Because the topic is still hot (Melott 2007; Joyce et al. 2008; references therein), and there is more to learn.

Actual significance of discreteness effects.—As a cosmological simulation can only give one view of the local universe, it

is important to run an ensemble of simulations, varying the random realization of the initial conditions, or, in other words, varying the phase and amplitude of the initial random fluctuations for a given power spectrum (Knebe & Domínguez 2003; Sirko 2005). The randomness of the initial conditions causes statistical scatter in the diagnostics, which competes against the systematic effects of discreteness and should therefore be evaluated. This requires running large ensembles of simulations.

Deeper and wider view of such effects.—Wavelets are a state-of-the-art numerical technique used for extracting multiscale information from scientific data (see, e.g., Fang & Thews 1998; Vidakovic 1999; Press et al. 2007, p. 699–716). Despite their numerous applications in cosmology (e.g., Fang & Feng 2000; He et al. 2005; Martínez et al. 2005; Feng 2007; Saar et al. 2007), they have not yet been used in the context of discreteness effects. Wavelets provide a multiresolution view of the data, which in our case represent the density field. The field is analyzed first at the finest resolution consistent with the sampling and then at coarser and coarser resolution levels. In doing so, wavelets probe the structure of the field and the contributions from the various scales. Besides, wavelets are sensitive to both the amplitude and the phase of the density fluctuations. Thus, wavelet-based statistics can offer a deeper and wider view of discreteness effects than traditional diagnostics.

Particular aspects of the problem.—There are several aspects of the problem that deserve particular attention. (1) What is the range of scales affected by discreteness? (2) As already mentioned, discreteness imposes two limitations: a finite mass resolution, and a lack of initial fluctuation power on small scales. It would be interesting to study their statistical effects separately. Binney (2004) himself concluded that “it would be interesting to have a series of simulations in which the power spectrum is truncated at large wavenumbers, with the result that any increases in the particle number lead to the same structures being more and more densely populated, rather than to ever smaller-scale structures being simulated.” Although Moore et al. (1999) did not see a significant difference in the density profile of a halo simulated with a truncated power spectrum, Colín et al. (2008) found steeper central density profiles in a larger sample of halos that formed with

masses close to the free-streaming cutoff scale. Here instead we study in detail how a truncated power spectrum affects the statistics of the density field. (3) Discreteness effects also arise from the gridlike particle distribution used in the initial conditions (e.g., Hansen et al. 2007). It would be worthwhile to check whether the initial grid leaves any statistical trace at low redshifts. (4) A further aspect of the problem concerns the probability distribution of the initial fluctuations and its evolution with redshift.

For this purpose, we have run two large sets of simulations. In one we vary N and the random realization of the initial conditions, while in the other we truncate the initial power spectrum and vary N through different sampling techniques so as to further probe discreteness effects and the transfer of power from large to small scales. In both sets we keep the force resolution fixed, so as to decouple the effects of discreteness from those of force resolution (cf. Binney 2004). Our simulations span scales from $80 h^{-1}$ kpc to $20 h^{-1}$ Mpc. We analyze the statistical properties of the cosmological density field using a large variety of diagnostics, including new and powerful wavelet statistics. We compute all the diagnostics in a manner consistent with the force resolution, so as to probe effects that are fully resolved dynamically.

The rest of the paper is organized as follows: The first set of simulations is described in § 2. The actual significance of discreteness effects against statistical scatter is assessed in § 3, where we also inquire into the nature of such scatter. In § 4, we introduce the wavelet statistics and analyze discreteness effects. The second set of simulations is described in § 5, and particular aspects of the problem are probed in § 6. We draw the conclusions in § 7.

2. SIMULATIONS

Our cosmological N -body simulations use the particle-mesh code by Klypin & Holtzman (1997) and are based on one of their runs. We adopted the same code and basic run in an introductory study (Agertz 2004).

A particle-mesh code is appropriate for our purpose because it computes all the dynamical quantities, from the density field $\delta(\mathbf{x}) = [\rho(\mathbf{x}) - \bar{\rho}]/\bar{\rho}$ to the forces, with given spatial resolution. The Klypin-Holtzman code is publicly available and well described. It can also be used for generating the initial conditions and analyzing the output data. The initial conditions are set up by using the Zel'dovich approximation to displace particles from a regular grid. The power spectrum $P(k)$, correlation function $\xi(r)$, and mass variance $\sigma_M^2(r)$ of the output density field are computed consistent with the spatial resolution of the code, which is twice the cell size Δ_c .

The basic run is a Λ CDM simulation. The cosmological parameters are $\Omega_\Lambda = 0.7$, $\Omega_m = 0.3$, $\Omega_b = 0.026$, $h = 0.7$, $\sigma_8 = 1$, and $n = 1$. The simulation has $N = 32^3$ particles, $N_c = 128^3$ cells, and a box of $L = 20 h^{-1}$ Mpc. It runs from redshift $z = 15$ ($a = 0.0625$) to $z = 0$ ($a = 1$) in 469 steps ($\Delta a = 0.002$). This simulation is simple and realistic enough for our purpose.

The simulations in this paper have the same input parameters as the basic run except for N and the random number seed for generating the initial conditions. We use five values of N : $N = 16^3, 32^3, \dots, 256^3$. In other words, the number of particles per cell ranges from 1/512 to 8, and the spatial resolution ranges from $\frac{1}{4}$ to 4 times the average interparticle distance. For each N , we generate 10 random realizations of the initial conditions. Such a set of 50 simulations is appropriate for exploring how their outcome depends on N and for evaluating the statistical scatter of the measurements. Additional simulations are discussed in § 5.

3. DISCRETENESS EFFECTS VERSUS STATISTICAL SCATTER

3.1. $P(k)$, $\xi(r)$, and $\sigma_M^2(r)$ Are Scatter Dominated

Three popular statistical diagnostics used in cosmology are the power spectrum $P(k)$, the correlation function $\xi(r)$, and the mass variance $\sigma_M^2(r)$ (see, e.g., Peebles 1980; Coles & Lucchin 2002). $P(k)$ is the average square amplitude of density fluctuations on scale $2\pi/k$, with proper normalization. In the Klypin-Holtzman code, $P(k)$ is computed as

$$P(k) = \frac{1}{L^3} \frac{\sum |\hat{\delta}(\mathbf{k})|^2}{\Delta N_k}, \quad (1)$$

where $\hat{\delta}(\mathbf{k})$ is the fast Fourier transform of the density field $\delta(\mathbf{x})$ tabulated in the mesh of the code, the sum is over all wavenumbers spanning a spherical shell of radius k and thickness $\Delta k = 2\pi/L$, ΔN_k is the number of harmonics in the shell, and L is the box size. The quantity $\xi(r)$ is the real-space equivalent of $P(k)$ and measures the correlation strength of structures on scale r . In the Klypin-Holtzman code, $\xi(r)$ is computed by discretizing the relation

$$\xi(r) = \frac{1}{2\pi^2} \int_0^\infty P(k) \frac{\sin kr}{kr} k^2 dk. \quad (2)$$

The algorithm consists of several steps, which cannot be translated into a single formula [cf. the routine FCORR (R) in the code's PMpower.f file]. Similarly, we compute $\sigma_M^2(r)$ by discretizing the relation

$$\sigma_M^2(r) = \frac{1}{2\pi^2} \int_0^\infty P(k) W^2(kr) k^2 dk, \quad (3)$$

where $W(kr)$ is the spherical top-hat window function

$$W(x) = \frac{3}{x^3} (\sin x - x \cos x). \quad (4)$$

Note that the only difference between $\xi(r)$ and $\sigma_M^2(r)$ is the replacement of $\sin(kr)/kr$ with $W^2(kr)$.

Another way to compute $\xi(r)$ and $\sigma_M^2(r)$ is by using particle-based estimators (e.g., Knebe & Dominguez 2003), rather than the mesh-based estimators above. However, the computation takes an order of magnitude longer than the simulations themselves. Besides, it is more difficult to compute $\xi(r)$ and $\sigma_M^2(r)$ consistent with the spatial resolution of the code. This results in extra spikes, which are nothing but noise from the particle-based estimation. Apart from that, the results are similar. So in the following we go on discussing the mesh-based case.

As another short digression, in our simulations there are two Nyquist frequencies involved. One is the ‘‘particle Nyquist frequency’’

$$k_N = \pi N^{1/3}/L, \quad (5)$$

which is associated with the gridlike particle distribution used in the initial conditions. This is the wavenumber at which the initial power spectrum is truncated. Therefore, k_N determines the initial number of modes. The other Nyquist frequency, $\pi N_c^{1/3}/L$, is associated with the mesh of the code (N_c is the number of cells). This is the largest $|k_i|$ ($i = 1, 2, 3$) that can be resolved in

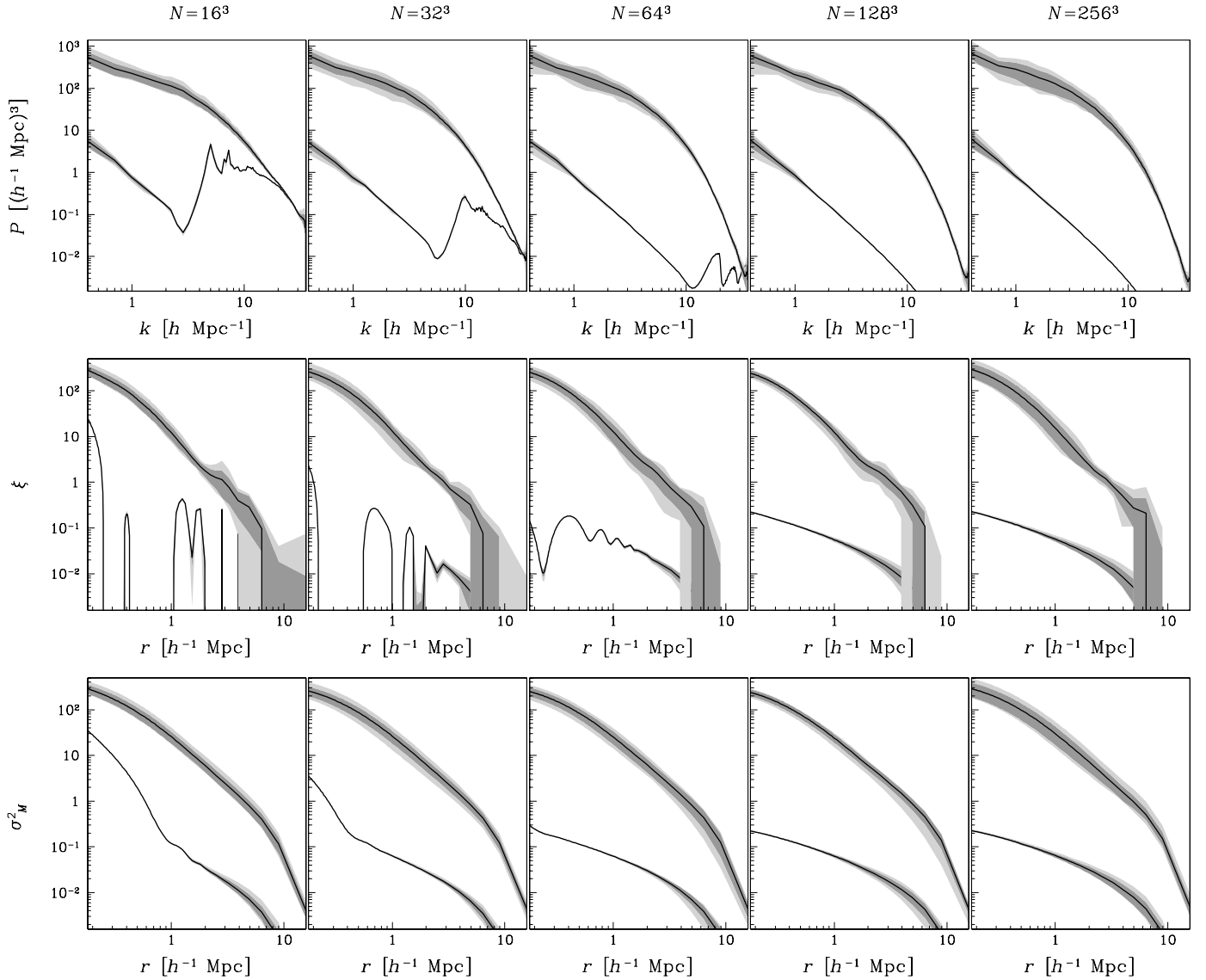


FIG. 1.—Power spectrum $P(k)$, correlation function $\xi(r)$, and mass variance $\sigma_M^2(r)$ for various values of N . Each panel shows the statistical scatter of the diagnostic at redshift $z = 15$ (lower set of curves) and at $z = 0$ (upper set). The black lines and dark and light gray regions represent the average, rms deviation, and range of the diagnostic, respectively.

the mesh. Harmonics with $|k_i| > \pi N_c^{1/3}/L$ are aliased into the principal zone $|k_i| \leq \pi N_c^{1/3}/L$, but they are greatly attenuated if the mass-assignment scheme is TSC (“triangular shaped cloud”) or CIC (“cloud in cell”), as are used in the code (see Hockney & Eastwood 1988). Of the two Nyquist frequencies, only k_N varies in our set of simulations and enters the following discussion.

Let us thus study how the number of particles affects the standard diagnostics described above. Figure 1 shows $P(k)$, $\xi(r)$, and $\sigma_M^2(r)$ in the range of scales spanned by the simulations, that is, approximately from the cell size $\Delta_c = L/N_c^{1/3}$ to the box size L . At $z = 15$, all the diagnostics manifest the peculiarity of the initial conditions for $N < N_c$. Such discreteness effects appear if initially the particles are distributed over a grid coarser than the dynamical mesh. At $z = 0$, discreteness effects are hardly detectable. All the diagnostics show large statistical scatter instead. The initial and final redshifts are discussed in detail below.

Redshift $z = 15$.—For $N < N_c$, we observe fluctuations in $P(k)$ beyond the particle Nyquist frequency k_N . As k_N increases with N , in the presence of one or more particles per cell we can no

longer detect the peculiar imprint of the initial conditions on $P(k)$. Discreteness effects can also be observed in the other diagnostics for $N < N_c$: $\xi(r)$ fluctuates on scales smaller than a few times the average interparticle distance $L/N_c^{1/3}$, and $\sigma_M^2(r)$ changes slope on scales below $L/N_c^{1/3}$ and approaches the r^{-4} behavior expected for a gridlike distribution (e.g., Hansen et al. 2007).

Redshift $z = 0$.—The diagnostics are unaffected by the number of particles. The only clear exception is $P(k)$ for $N \leq 32^3$, which differs significantly from the other power spectra at wavenumbers larger than about 5 times its particle Nyquist frequency (its tail has a positive vertical offset with respect to the other tails). The other power spectra are similar, considering their scatter, and so are all the correlation functions and mass variances. On the other hand, the random realization of the initial conditions seems to have an important influence on all the diagnostics: their rms scatter is as large as a factor of 2 or more. In $P(k)$ and $\xi(r)$ the scatter is more important on large scales, while in $\sigma_M^2(r)$ it is quite uniform. This difference between $\sigma_M^2(r)$ and $\xi(r)$ is a consequence of the large-scale behavior of $W^2(kr)$, which decays faster than $\sin(kr)/kr$ and hence damps large-scale scatter more effectively.

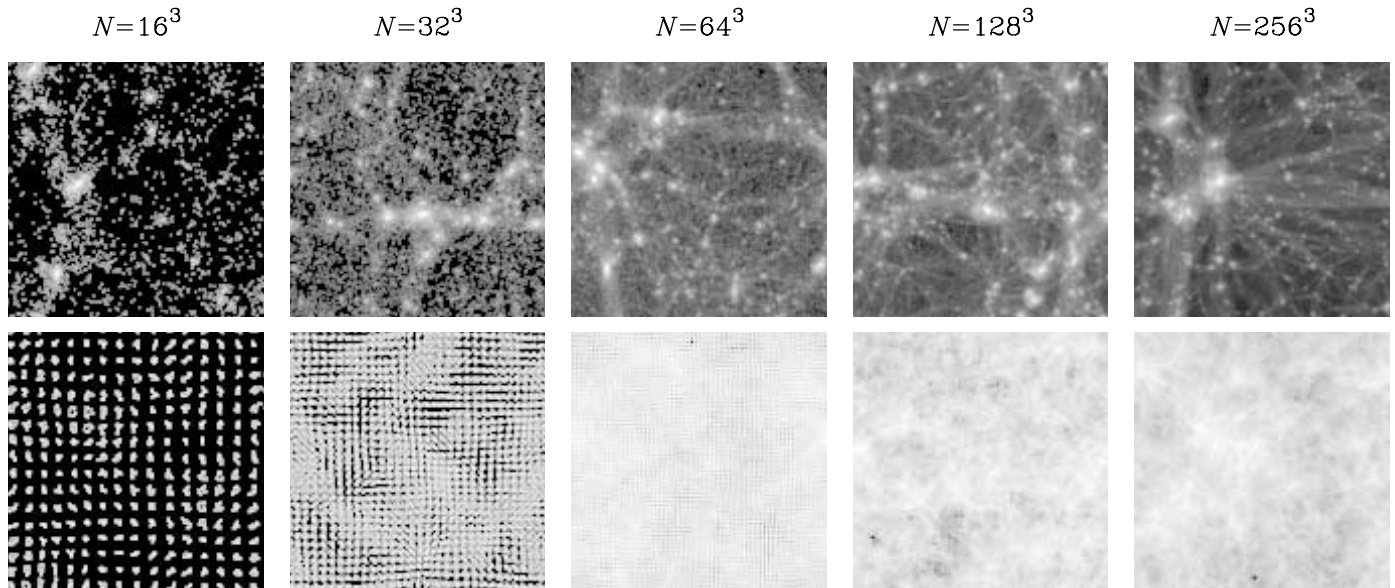


FIG. 2.—Logarithmic gray-scale map of the projected density field for various N at redshifts $z = 0$ (top) and $z = 15$ (bottom).

Our findings reinforce those of Knebe & Domínguez (2003) and Sirko (2005), who observed large scatter in the standard diagnostics for a typical number of particles.

The results of this analysis can be summarized as follows: At low redshifts the power spectrum, correlation function, and mass variance are dominated by statistical scatter rather than by the systematic effects of discreteness. Discreteness effects are only detectable in $P(k)$, far beyond the particle Nyquist frequency ($k \gtrsim 5k_N$) and only if there is much less than one particle per cell ($N \leq 32^3$ for $N_c = 128^3$). In the other diagnostics there is no clear dependence on the number of particles, even if N varies by $3\frac{1}{2}$ orders of magnitude. This is in contrast to the clear dependence on N and the small scatter at high redshifts.

3.2. $\delta(x)$ Is Discreteness Dominated

Figure 2 shows the density field $\delta(x)$ tabulated in the mesh of the code. Hence, the spatial resolution is the same as for $P(k)$, $\xi(r)$, and $\sigma_M^2(r)$. Here the effect of varying N is mainly a change in granularity: $\delta(x)$ becomes much less granular as N increases from 16^3 to 64^3 or 128^3 . In contrast, the random realization of the initial conditions turns out to influence only the spatial pattern.¹ Thus the results of § 3.1 are at odds with the visual outcome of the simulations. At low, as well as at high, redshifts the density field is dominated by the systematic effects of discreteness. It is peculiar, if not surprising, that standard statistics such as the power spectrum, correlation function, and mass variance are insensitive to the granularity of the density field, even when this property changes as much as in Figure 2, whereas they are sensitive to its random realization.

3.3. The Scatter Can Be Regarded as Spurious and Be Reduced

In order to gain insight, we consider simpler statistics of the density field, namely, its standard deviation σ , skewness S , and

¹ In Fig. 2, the random number seed for generating the initial conditions does not vary. The density field shows different patterns because, as a consequence of increasing N , the realization of the fluctuations is different. In fact, the Klypin-Holtzman code does not keep the same realization of long waves, while adding more and more short waves. This phase difference does not change the granularity of the density field.

kurtosis K (the mean is zero). S and K are useful for measuring departures from Gaussianity (see, e.g., Press et al. 2007), which are significant at low redshifts. Following Press et al., we compute σ , S , and K from the density field $\delta(x)$ tabulated in the mesh of the code. The analysis of these statistics shows that σ , S , and K are also scatter dominated (see Fig. 3).

Where does the degeneracy come from? Figure 4 illustrates what the histogram of the density field looks like at redshift $z = 0$. In particular, the top panel shows the histogram for the range of values spanned by the density contrast, while the bottom panel shows a zoom of the histogram.² The simplicity of this figure points out two remarkable peculiarities of the δ -distribution: (1) a huge spike at $\delta = -1$, and (2) an extremely long tail for $\delta > 0$. In computing the statistics, the tail of high-density peaks has much more weight than the frequent deep underdensities. This makes the statistics very sensitive to rare events and, hence, scatter dominated. But how genuine is such scatter? We know that it is difficult to extract robust statistical information from data characterized by a long-tailed probability distribution (e.g., Press et al. 2007). Robust estimation requires the defining of appropriate statistics (see Press et al. 2007) or even transforming the data (see Stuart & Ord 1991). Thus, the sensitivity pointed out above means that standard statistics of the density field are not so well defined, and that their scatter can be regarded as spurious.

Considering deep underdensities and high-density peaks separately, in view of their distinct cosmological meanings (voids and dark matter halos), still yields a strongly unbalanced δ -distribution: clustered below $\delta \sim 0$, and dispersing up to $\delta \sim 200$. What about a statistical transformation of the density field? Let us consider the $\ln(1 + \delta)$ distribution, for $\delta \neq -1$. This transformation shortens the overdensity tail, and it even makes the distribution roughly normal (see Fig. 5). In addition, this transformation is appealing because $1 + \delta$ is a basic cosmological quantity and the $\ln(1 + \delta)$ distribution matches the δ -distribution in the linear regime. Log-normal models have been discussed by Coles & Jones (1991) and Kayo et al. (2001), among others. One may find better transformations by considering the class of $\alpha^{-1}[(1 + \delta)^\alpha - 1]$ distributions,

² We do not scale the y-axis logarithmically because it is the probability distribution, and not its logarithm, that enters into the definition of the statistics.

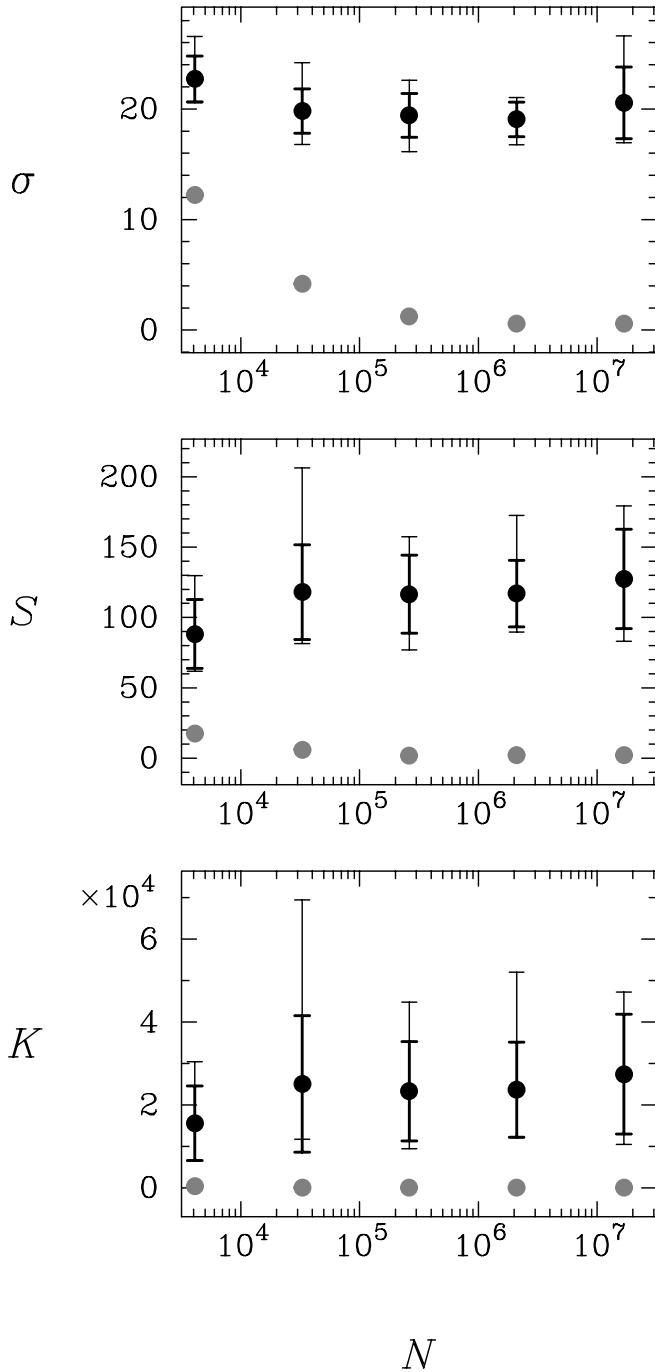


FIG. 3.—Statistics of the density field as functions of N : the standard deviation σ , skewness S , and kurtosis K . The redshifts shown are $z = 0$ (black) and $z = 15$ (gray). The scatter of the diagnostics is shown by plotting their average (circles), rms deviation (thick error bars), and range (thin error bars).

for $\delta \neq -1$ and $0 < \alpha < \frac{1}{2}$, but at the cost of a free parameter to fine-tune. We do not follow that approach.

Encapsulating the singularity of the δ -distribution ($\delta = -1$) in one statistic, the fraction of void cells or void probability ν , we can define statistics of the transformed density field such as its mean μ , standard deviation σ , skewness S , and kurtosis K (we reuse old symbols to denote the new quantities). Note that ν is not meant to describe the distribution of voids as cosmological structures, which would require a topological approach. Note also that now $\mu \neq 0$, since the transformation has a bias (see Stuart & Ord 1991) and S and K measure departures from lognormality.

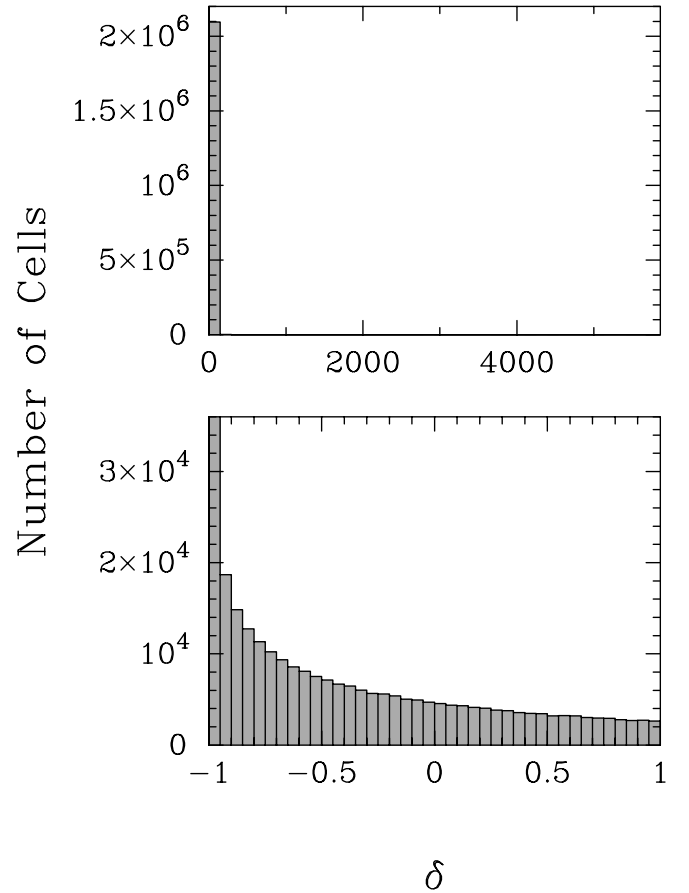


FIG. 4.—Histograms of the density field at redshift $z = 0$ for a representative simulation. The diagram is presented for the range of values spanned by δ (top) and for the subrange $-1 \leq \delta \leq 1$ (bottom). In the bottom panel, the upper limit of the y -axis is set to $1/50$ the maximum height of the histogram.

Such statistics are dominated by discreteness, as is the density field itself: a sharp trend with N emerges and the scatter is mostly unnoticeable, at low as well as at high redshifts (see Fig. 6). In particular, the fact that the fraction of void cells decreases with the number of particles for a given cell size is in natural agreement with the visual outcome of the runs.

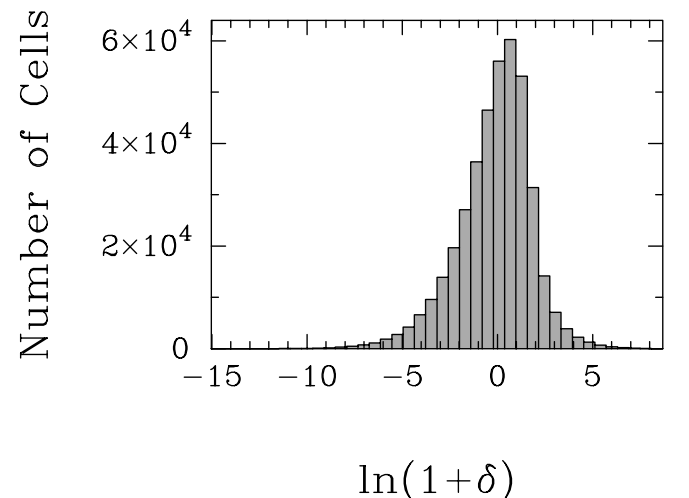


FIG. 5.—Histogram of the transformed density field at redshift $z = 0$ for the same representative simulation as in Fig. 4.

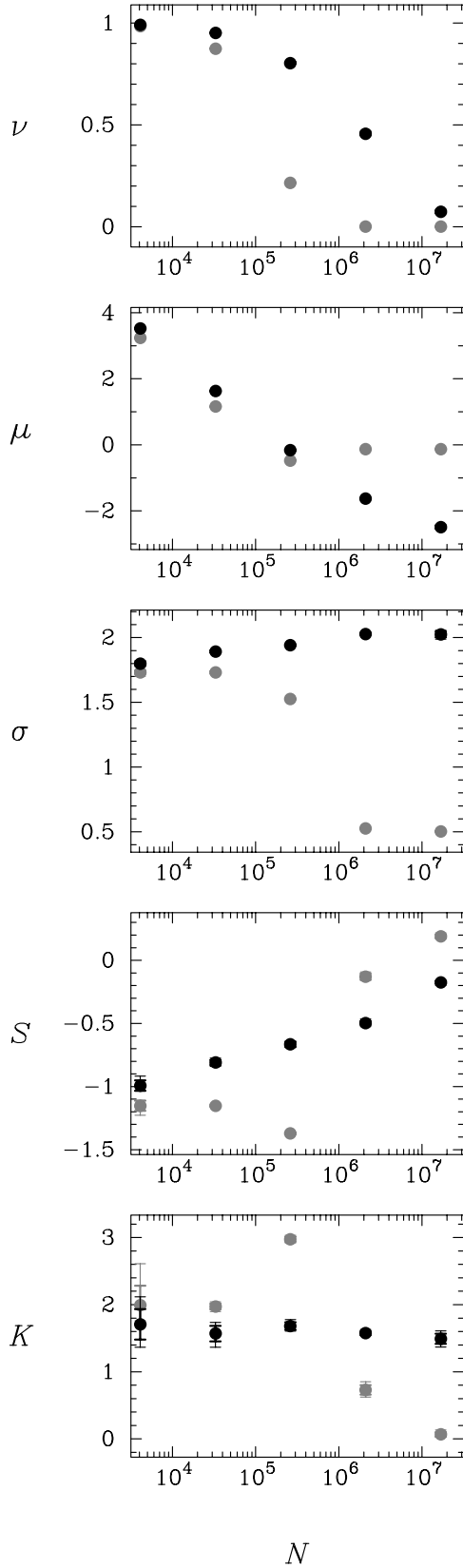


FIG. 6.— Statistics of the transformed density field as functions of N : the fraction of void cells ν , mean μ , standard deviation σ , skewness S , and kurtosis K . The redshifts shown are $z = 0$ (black) and $z = 15$ (gray). The scatter of the diagnostics is shown by plotting their average (circles), rms deviation (thick error bars), and range (thin error bars).

To summarize, in this section we have learned that the statistical scatter can be regarded as spurious and can be strongly reduced. The consideration of scale-dependent statistics adds complexity but does not change the message. In § 4, we shall see that the method of scatter reduction can be extended to wavelet statistics, which is fundamental for an appropriate multiscale analysis.

4. WAVELET STATISTICAL ANALYSIS

4.1. The Fast Wavelet Transform

Data such as the cosmological density field encompass information on various scales. In order to extract such information, we should be able to separate small-scale features from large-scale features and to understand their contributions to the overall structure of the data. In this section, we describe a technique that can be used for the purpose above: the fast wavelet transform. For further reading, see Romeo et al. (2003, hereafter Paper I) and Romeo et al. (2004, hereafter Paper II). In particular, Paper II provides a reader-friendly and self-contained discussion of wavelets, from the basics to advanced aspects of the technique.

The fast wavelet transform involves localized wavelike functions, which are dilated over the relevant range of scales and translated across the data. The contributions of small-scale and large-scale features are singled out with an iterative procedure. The first step consists of separating the smallest-scale features from the others. This is done by passing the data through a high-pass filter and a complementary low-pass filter. These filters are the discrete counterparts of the analyzing functions of the transform, the wavelet $\psi(x)$ and the scaling function $\phi(x)$, respectively, and are constructed with a mathematical technique known as multiresolution analysis. Filtering produces redundant information, since each set of filtered data is of the same size as the original data set. Redundancy is avoided by rejecting every other point of the filtered data. It is well known that downsampling produces aliasing in the context of the Fourier transform, but the filters of the wavelet transform are constructed in such a way as to eliminate it. The second step consists of separating the features that appear on a scale twice as large as in the first step. This is done by regarding the low-pass-filtered and downsampled data as new input data and analyzing them as in the first step. The procedure continues until all features below a given “upper scale” are separated. In summary, the one-dimensional fast wavelet transform decomposes the original data into a coarse “approximation” and a sequence of finer and finer “details,” keeping the total size of the data constant (see Paper I, Fig. 2). The two- or three-dimensional fast wavelet transform is similar to the one-dimensional case, except for the more complicated structure of the transformed data (compare Paper II, Fig. 6). In general, given n -dimensional data of size N_d^n , the first step of the transform decomposes them into 2^n parts of size $(N_d/2)^n$: one approximation and $2^n - 1$ details, one for each axis and each diagonal. This is done by one-dimensionally transforming the data along each index, for all values of the other indices, consecutively. The second step decomposes the approximation into 2^n parts of size $(N_d/4)^n$, and so on.

Note that there is an important difference between the approximation and each of the details produced by the fast wavelet transform. Independent of the number of dimensions, each detail is a compact piece of information concerning a single scale. In contrast, the approximation encompasses (unprocessed) information on various scales; it can be viewed as a smoothed miniature of the data. Note also, however, that there is a nonstandard version of the multidimensional discrete wavelet transform in

which the details have mixed scale content. That is the one described by Press et al. (2007; see in particular Fig. 13.10.4b).

4.2. Transforming the Density Field and Computing Its Statistics

We compute the fast wavelet transform of the output density field in each simulation by using the code JOFILUREN (Papers I and II), referring the reader to Paper II for a thorough discussion of the method. To carry out the computation, we must specify the analyzing function and the upper scale of the fast wavelet transform. We choose the ‘‘bior 4.4’’ wavelet (see Paper II, Fig. 1), which is the one suggested in Paper II for CDM simulations. The upper scale is specified in terms of the scale parameter $N_{t,\min}$: an upper scale of 2^n cell sizes corresponds to $N_{t,\min} = N_c^{1/3}/2^n$, where N_c is the number of cells. We set $N_{t,\min} = 16$, which is the lower bound suggested in Paper II for the ‘‘bior 4.4’’ wavelet. Hence the density field is wavelet-analyzed at spatial scales $2^{s-1}\Delta_c$ ($s = 1, \dots, 4$), where Δ_c is the cell size. The corresponding details \mathcal{D}_s are sets of $7N_c/8^s$ data $D_s(i, j, k)$,³ which can be used to probe the statistical properties of the density field at such spatial scales. The approximation is less useful for this purpose because of its mixed scale content, as noted in § 4.1.

Wavelet statistics of the density field should not be computed directly from \mathcal{D}_s . In fact, the distribution of \mathcal{D}_s -values at redshift $z = 0$ shows a central singularity and a very long tail on both sides. Such features are similar to those discussed in § 3.3 and have similar consequences. Therefore, we extend the procedure followed in that case. Using $\ln[1 + \delta(\mathbf{x})]$ rather than $\delta(\mathbf{x})$ does not solve the problem here, because this field diverges in a significant fraction of the mesh (the void cells) and hence its fast wavelet transform is not defined. Our solution is to consider the subsets $\mathcal{D}_s^0 = \{D_s(i, j, k) = 0\}$ and $\{D_s(i, j, k) \neq 0\}$ separately and transform the latter: $\mathcal{D}_s^T = \{\ln|D_s(i, j, k)|\}$. We then define the void probability ν_s as the fraction of vanishing detail coefficients at spatial scale s . We compute ν_s by counting the number of data contained in \mathcal{D}_s^0 and recalling that there are $7N_c/8^s$ detail coefficients in total (at scale s). We also compute the mean μ_s , standard deviation σ_s , skewness S_s , and kurtosis K_s of the data contained in \mathcal{D}_s^T . Such wavelet statistics are a scale-dependent generalization of the statistics discussed in § 3.3. A generic member of this family is denoted by f_s . Hereafter, the subscript s is added only when needed.

4.3. A First View of Discreteness Effects

Figure 7 shows the wavelet statistics as functions of the number of particles at various spatial scales. Note at the outset that the large scatter of $S_4(N)$ and $K_4(N)$ is not a failure of our statistical transformation. This appears because the skewness and kurtosis are high-order statistics, and at that spatial scale there are relatively few detail coefficients. By analyzing the behavior of $f_s(N)$ at $z = 15$, we learn that the imprint of the initial conditions on the wavelet statistics is twofold. First, there is a strong correlation between the number of particles and the spatial scale: $f_s(N8^n)$ behaves approximately as $f_{s+n}(N)$. In fact, the red curves shifted by one step to the left match the green curves, which in turn match the blue ones, and so on. This correlation appears because the effect of varying N is, to zeroth-order approximation, a simple change of scale in the particle distribution. Second, at a given spatial scale $s \leq 3$ there is a number of particles $N = 64^3/8^{s-1}$ that minimizes σ and S and maximizes K . This follows from the

³ We are neglecting the three-dimensional substructure of the details, which are here irrelevant. Hence, at a given s the spatial indices (i, j, k) span the cube $C_{s-1} = \{1 \leq (i, j, k) \leq N_c^{1/3}/2^{s-1}\}$ minus its subset C_s .

fact that the δ -distribution has a transition for $N = 64^3$ (see § 6.2). The behavior of $f_s(N)$ at $z = 0$ is more difficult to understand in detail. Nevertheless, we can deduce two basic facts:

1. There is a weak trace of the initial correlation between N and s , while there is no critical N . This suggests that the average interparticle distance is still a significant scale when the particle distribution is hierarchically clustered.

2. Independent of redshift, the behavior of $f_s(N)$ simplifies at $s \geq 3$: all the wavelet statistics converge for large N , and they may be constant at $s > 4$. In other words, increasing N affects smaller and smaller spatial scales; scales larger than $s = 4$ (the average interparticle distance for $N = 16^3$) might be unaffected. This suggests that discreteness effects are confined to scales smaller than about twice the average interparticle distance and do not propagate bottom-up while cosmological structures are forming. If confirmed, this is one important aspect of the robustness of cosmological N -body simulations.

5. ADDITIONAL SIMULATIONS

To understand more, we carried out three additional sets of simulations, which are intermediate between those with $N = 16^3$ and $N = 256^3$. Each set is a statistical ensemble of 10 simulations produced by varying the random realization of the initial conditions, as before. The number of particles and the other input parameters are the same as in the original $N = 256^3$ simulations. What differs in each set is discussed below.

In the first set, the initial power spectrum $P_i(k)$ is truncated at a wavenumber $k = k_{\max} = 16\pi/L$, where L is the box size. One simulation is shown in Figure 8 (*top*). Recall that the natural truncation wavenumber is the particle Nyquist frequency $k_N = \pi N^{1/3}/L$, which determines the initial number of modes $N_m \approx (k_N L/\pi)^3 \approx N$. Hence k_{\max} can be regarded as an effective particle Nyquist frequency that sets the initial number of modes to $N_m \approx (k_{\max} L/\pi)^3 \approx 16^3$, while the number of particles is $N = 256^3$. By comparing this set with the $N = 16^3$ and $N = 256^3$ simulations, we can study the behavior of the statistics as the mass resolution and the initial number of modes vary independently.

In the second set, the output density field is computed by subsampling the particle distribution regularly, selecting 16^3 particles (looping over particle index and choosing every 16th particle). One such simulation is shown in Figure 8 (*middle*). Subsampling implies a loss of information at scales smaller than about twice the new average interparticle distance (per the sampling theorem). In addition, regular subsampling leaves the initial particle distribution gridlike. So, if this set turns out to be similar to the $N = 16^3$ simulations, the inference is that discreteness effects imply a loss of information similar to subsampling and, hence, that their spatial range is about twice the average interparticle distance.

In the third set, the output density field is computed by subsampling the particle distribution randomly, selecting 16^3 particles (see the selection sampling technique presented by Knuth 1998). One simulation is shown in Figure 8 (*bottom*). Random subsampling makes the initial particle distribution Poisson-like. By comparing this set with the regularly subsampled simulations, we can check whether the initial grid leaves any statistical trace at low redshifts.

6. PROBING DISCRETENESS EFFECTS

6.1. Spatial Range and Complexity

Figure 9 shows the wavelet statistics as functions of the spatial scale for five sets of simulations: the original $N = 16^3$ and

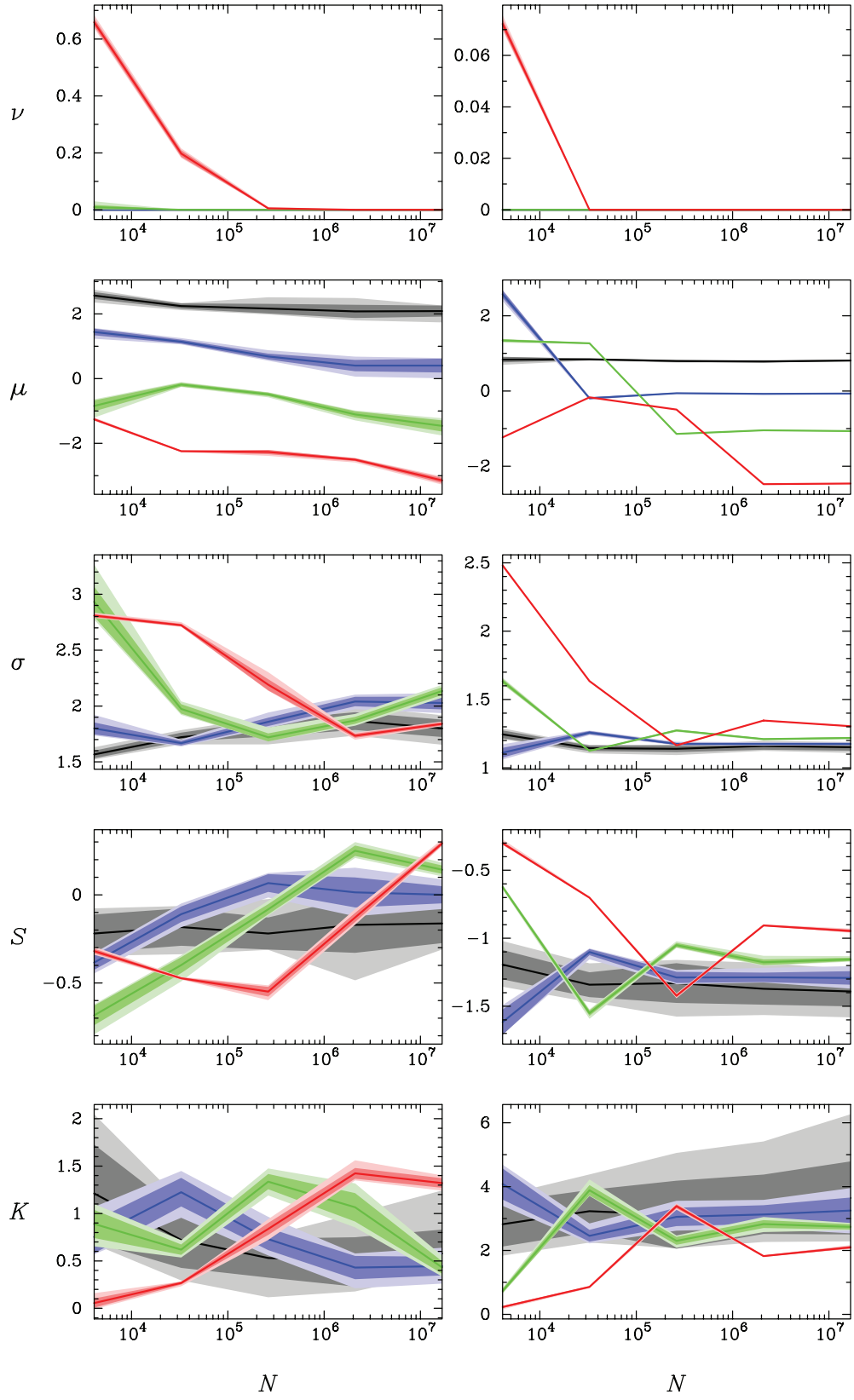


FIG. 7.—Wavelet statistics of the density field as functions of N at redshifts $z=0$ (left) and $z=15$ (right): the void probability ν , mean μ , standard deviation σ , skewness S , and kurtosis K . The spatial scales shown are $s=1$ (red), $s=2$ (green), $s=3$ (blue), and $s=4$ (gray). The scatter of the diagnostics is shown by plotting their average (lines), rms deviation (dark regions), and range (light regions).

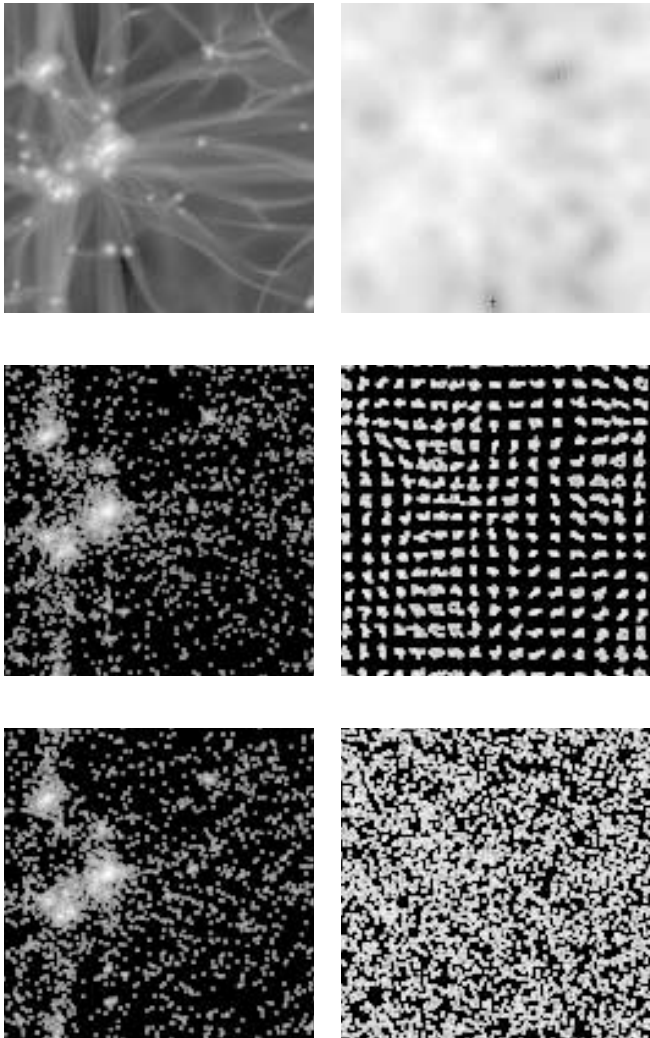


FIG. 8.—Logarithmic gray-scale maps of the projected density field at redshifts $z = 0$ (left) and $z = 15$ (right) for the additional simulations with power spectrum truncation (top), regular subsampling (middle), and random subsampling (bottom).

$N = 256^3$ simulations, and the additional simulations with power spectrum truncation and regular and random subsampling. Recall that $N = 16^3$ and $N = 256^3$ represent the cases in which the spatial resolution scale ($s = 2$) is much smaller and much larger, respectively, than the average interparticle distance ($s = 4$ and $s = 0$). Our deductions are as follows.

1. The $N = 256^3$ simulations are more basic than the others. The wavelet statistics have featureless behavior at high redshifts. The behavior at low redshifts is also featureless, except that the standard deviation and the kurtosis depart from monotonicity below the spatial resolution scale. Another interesting aspect of the evolution with redshift is that the skewness and the kurtosis approach zero, which means that the density field becomes approximately lognormal.

2. A comparison between the simulations with power spectrum truncation and the $N = 256^3$ simulations illustrates how complexity arises if the effective particle Nyquist scale is spatially resolved ($s = 5$): at high redshifts, the standard deviation, the skewness, and the kurtosis oscillate; at low redshifts they all depart from monotonicity below the spatial resolution scale. Decreasing the number of modes also yields a systematic decrease or increase in the wavelet statistics, with one exception. A further interesting aspect of the evolution with redshift is that the

simulations with power spectrum truncation become more similar to the $N = 256^3$ simulations. This means that there is a transfer of statistical information from the modes initially excited to those initially suppressed, but the loss of information is still significant at $z = 0$. If not only the effective particle Nyquist scale but also the average interparticle distance is spatially resolved, then further complexity arises ($N = 16^3$ simulations vs. simulations with power spectrum truncation). The peculiarities of the wavelet statistics are pointed out in § 4.3.

3. The regularly subsampled simulations agree rather well with the $N = 16^3$ simulations. This confirms that discreteness effects are insignificant beyond a scale of about twice the average interparticle distance.

4. At $z = 15$, random subsampling differs significantly from regular subsampling. Random subsampling suppresses the minima of the standard deviation and the skewness, as well as the maximum of the kurtosis and of the mean, at a scale of half the effective average interparticle distance ($s = 3$). It also increases the void probability at the cell size scale by more than a factor of 3. At $z = 0$, random subsampling is equivalent to regular subsampling. Therefore, the initial grid leaves a strong imprint on the wavelet statistics at high redshifts, whereas there is no memory of the initial grid at low redshifts.

6.2. Initial Non-Gaussianity from Gaussian Initial Conditions

In cosmological N -body simulations, the initial conditions are generated assuming that the random density field is Gaussian. Gaussianity is one of the basic cosmological assumptions. This implies that the density field is entirely characterized by its power spectrum or correlation function (see, e.g., Peacock 1999).

But is the density field that results from the initial conditions really Gaussian? Figure 10 illustrates the effect of varying the number of particles. Each histogram is shown for the range of values spanned by the density contrast and for the subrange $-1 \leq \delta \leq 1$. Apart from the peculiarities pointed out in § 3.3, note that the δ -distribution for $N = 64^3$: it is one-sided for $N \leq 64^3$ and two-sided for $N > 64^3$. This means that if the spatial resolution scale is smaller than twice the average interparticle distance, as usual, then the initial density field estimated by the code is markedly non-Gaussian (although the field that the point particles are sampling is Gaussian). The same is true even when we start the simulations as early as at $z = 100$ (Fig. 11). This inconsistency arises because at such a high force resolution, the mass distribution looks granular: there is an excess of both high-density peaks and deep underdensities. Such initial non-Gaussianity is what this or other codes actually “see” at that high force resolution; its effects will propagate dynamically. At low resolution, the departure from Gaussianity is moderate at $z = 15$ and small at $z = 100$ (compare Figs. 10 and 11). Technical issues are discussed in § 7.

7. CONCLUSIONS

The significance of discreteness effects in Λ CDM simulations depends on two comoving spatial scales: the force resolution ϵ , and the average interparticle distance d . Here ϵ is also the resolution scale for density and statistical estimation. Our wavelet analysis shows that discreteness has a strong impact if $\epsilon \ll 2d$:

1. The simulations are inconsistent with one of the basic cosmological assumptions. In fact, the initial random density field is markedly non-Gaussian, even though it is assumed to be Gaussian in the initial conditions (§ 6.2).

2. At low redshifts the density field departs significantly from lognormality, and further complexity arises (§ 6.1).

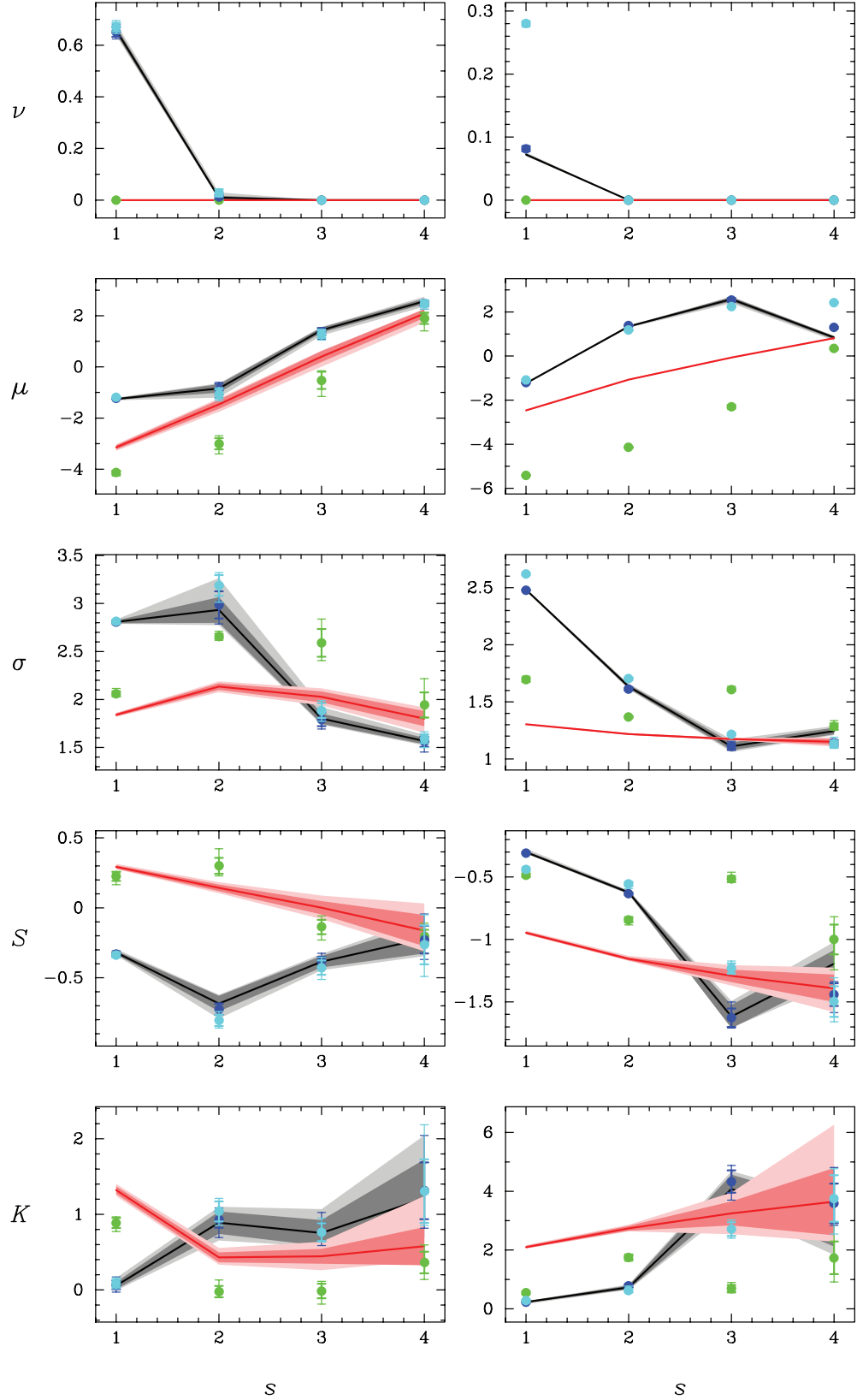


FIG. 9.—Wavelet statistics of the density field as functions of the spatial scale s at redshifts $z=0$ (left) and $z=15$ (right): the void probability ν , mean μ , standard deviation σ , skewness S , and kurtosis K . The sets of simulations shown are the original simulations with $N=16^3$ (gray curves) and $N=256^3$ (red curves), and the additional simulations with power spectrum truncation (green symbols), regular subsampling (blue symbols), and random subsampling (cyan symbols). The scatter of the diagnostics for the original and additional simulations is shown by plotting their average (lines and circles, respectively), rms deviation (dark regions and thick error bars), and range (light regions and thin error bars).

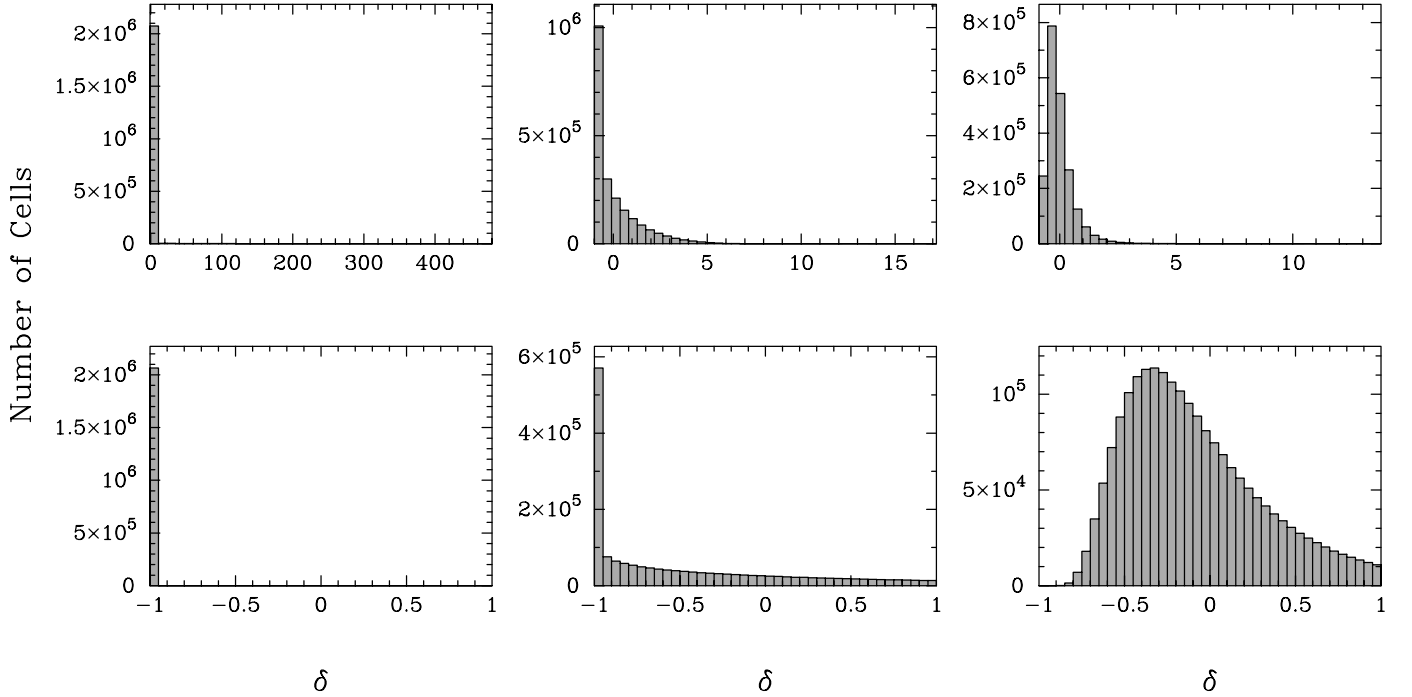


FIG. 10.—Histograms of the initial density field at redshift $z = 15$ for $N = 16^3$ (left), $N = 64^3$ (middle), and $N = 256^3$ (right). Each histogram is shown for the range of values spanned by δ (top) and for the subrange $-1 \leq \delta \leq 1$ (bottom).

3. The comoving spatial scales s affected by discreteness span the wide range $\epsilon \lesssim s \lesssim 2d$ (§ 6.1; see also § 4.3).

Discreteness effects become insignificant if $\epsilon \sim 2d$. This condition guarantees that the statistical properties of the cosmological density field are modeled accurately throughout the range of scales spanned by the simulation. In particular, this is fundamental for probing the imprints of primordial non-Gaussianities on large-scale structure, a topic of current interest (e.g., Dalal

et al. 2008; Grossi et al. 2008; Hikage et al. 2008). These results have two implications. One is that $2d$, and not ϵ , is the minimum scale for extracting robust statistical information from the simulation data. The other concerns the trade-off between force and mass resolution in modern cosmological codes, which is discussed below.

Let us consider particle-mesh codes that use adaptive mesh refinement (AMR), such as ART (Kravtsov et al. 1997), MLAPM (Knebe et al. 2001), RAMSES (Teyssier 2002), and others. The

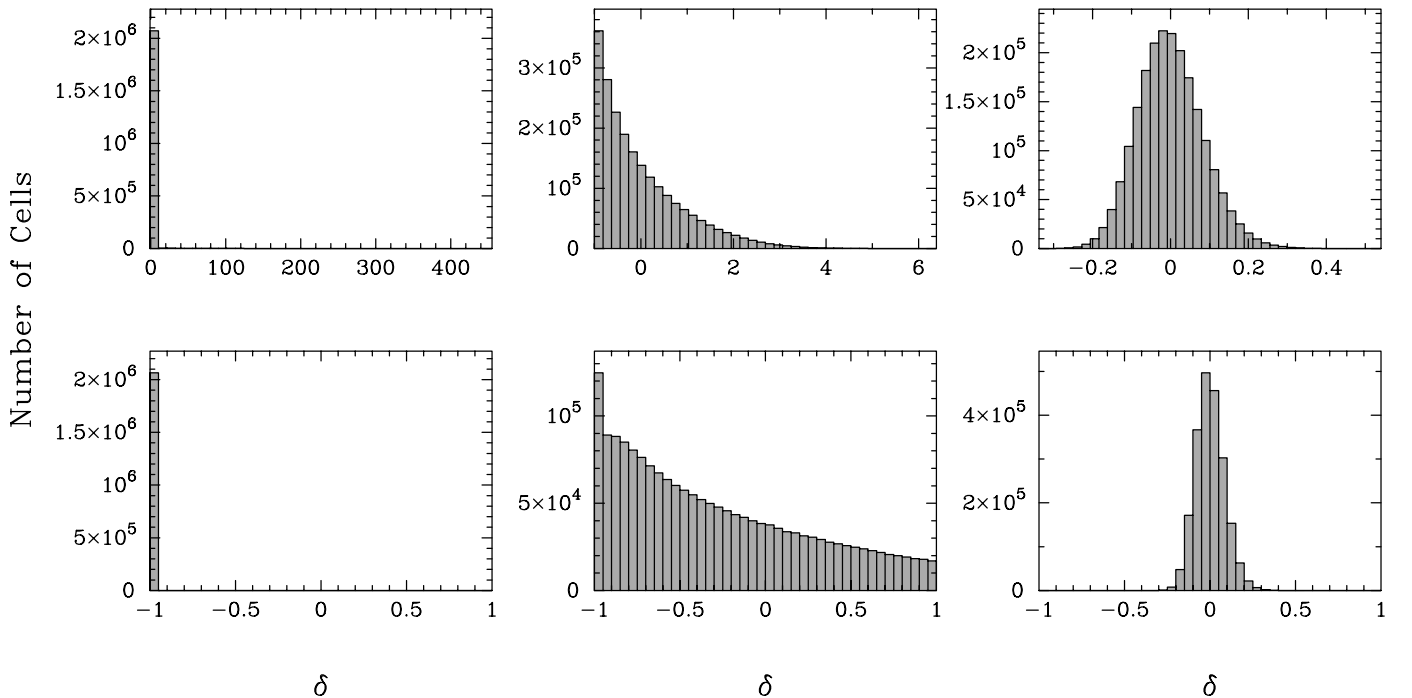


FIG. 11.—Same as Fig. 10, but at redshift $z = 100$.

condition $\epsilon \sim 2d$ can be implemented adaptively by requiring that there be no fewer than n particles per cell, where n depends on the mass-assignment/force-interpolation scheme. In fact, $\epsilon \sim \Delta_c$ for NGP (“nearest grid point”), $\epsilon \sim 2\Delta_c$ for CIC, and $\epsilon \sim 3\Delta_c$ for TSC, where Δ_c is the cell size (for a description of these schemes, see Hockney & Eastwood 1988). In addition, $n \sim (\Delta_c/d)^3$. Hence $n \sim 8$ for NGP, $n \sim 1$ for CIC, and $n \sim \frac{1}{3}$ for TSC. Such values are comparable to those currently used. This means that our condition is easy to fulfil, and hence discreteness effects can be kept under control in AMR codes.

In tree-based codes such as GADGET-2 (Springel 2005) and PKDGRAV (Stadel 2001), the force resolution is equal everywhere. The criterion for resolving the small-scale dynamics of structure formation is then more demanding and imposes $\epsilon \ll 2d$, as is currently used. This means that it may not be easy to enforce such a criterion and our condition together, although the domains of applicability are complementary. An interesting possibility would be to let the force resolution vary with redshift so as to enforce such requirements in distinct regimes of clustering, following the transfer of power from large to small scales. A more

radical alternative is to have adaptive force resolution, as in the case of AMR codes. A variable softening length can now be implemented in a form that conserves momentum and energy exactly (Price & Monaghan 2007), and its use has also been suggested in other contexts (e.g., Bate & Burkert 1997; Dehnen 2001; Nelson 2006; Price & Monaghan 2007; Wetzstein et al. 2008).

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