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Externally Divided Exhaust Period in a Turbocompound Heavy Duty C.I. Engine

Thermodynamic and mechanical modelling in GT-SUITE
Master's thesis in Automotive Engineering

NANDEEP MYSORE, RAHUL KILPADI

MASTER'S THESIS IN AUTOMOTIVE ENGINEERING

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ABSTRACT

Turbocompounding has been a development on heavy diesel engines to improve the utilisation of exhaust heat energy. This system, however, introduces additional pumping losses and exhaust back pressure. Previous research has shown that the introduction of a divided exhaust period (DEP) to the turbocompound engine using staggered timing on exhaust valves feeding individual manifolds lowers the exhaust back pressure, improving engine breathing and behaviour. Exhaust flow is divided into two distinct flow paths beginning at the exhaust valves – through the turbocharger (blowdown), and bypassing it (scavenging). However, research showed that using one exhaust valve for each flow path can significantly lower the effective flow areas for exhaust gases at higher engine speeds. This leads to highly choked flow and consequently reduced engine output. A solution proposed was the division of the flow paths external to the exhaust port, henceforth named external DEP (ExDEP). In this solution, both exhaust valves open identical to those of the original engine, but the gas flow is divided downstream with the use of independent valves. By the use of ExDEP on a turbocompounded diesel engine the above research resulted in a brake specific fuel consumption benefit of up to 4% over a regular turbocharged engine.

This thesis project, conducted at the Advanced Technology and Research division of Volvo Group Trucks Technology in association with the Combustion department of Chalmers University, aims to implement and evaluate the effects of ExDEP on an existing GT-SUITE simulation model of a two-stage turbocompounded Volvo HDE13 engine. Various flow components (valve types) and architectures are modelled. The effect of timing and phasing of the ExDEP valves on engine performance is investigated. Resizing of the existing turbine is investigated due to the altered gas flow. Rough CAD models are prepared to determine the feasibility of physically incorporating such systems on existing engines.

A further adaptation to the existing engine model is the incorporation of CAD data of a novel engine concept currently being developed at Volvo GTT, in order to study the feasibility of ExDEP with this engine.

With the implementation of ExDEP, a primary advantage foreseen is that the exhaust flow into the turbines can be constantly controlled. This eliminates the need for variable geometry turbochargers, bringing large reductions in system cost and complexity. It can enable other innovative technologies such as Miller cycle operation, air hybrid operation when an air tank is coupled to the exhaust manifold

Key words: Simulation, GT-Suite, GT-Power, ExDEP, exhaust, turbocharger, turbocompound

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Preface

In this work, an existing GT-SUITE model of a Volvo HDE13 six-cylinder engine with two-stage turbocompounding was adapted to incorporate ExDEP valves on each cylinder. The dimensions and timing of these valves and the sizing of the low pressure turbine were varied to study their effects on the brake specific fuel consumption (BSFC) of the engine at common operating points. The valves were also modelled in CAD to represent realistic solutions. The work was carried out from January 2015 to June 2015 at the Advanced Technology and Research (ATR) division of Volvo Group Trucks Technology.

We would like to extend our sincere gratitude to our supervisor Arne Andersson, Program Manager (Advanced Concepts) at Volvo GTT/ATR for his steady guidance and support. We are also grateful to Professor Sven B. Andersson of the Division of Combustion at the department of Applied Mechanics at Chalmers University of Technology, for all the advice and ready humour!

Our work would have been exponentially more tedious, even impossible, if not for the unfailing support of Per Salomonsson, Tommy Simonsson and everyone at Volvo GTT/ATR.

We would like to thank Fredrik Rahm and Per Andersson of Volvo GTT for their valuable advice, expertise and encouragement.

Finally, special heartfelt thanks to Bincheng Jiang of Volvo GTT/ATR for the immense assistance at the beginning of this project, and our colleague and good friend Anoop Suryanarayana.

Göteborg, June 2015

NANDEEP MYSORE, RAHUL KILPADI

Notations

Upper case

A_e	Effective flow area (m^2)
A_r	Actual orifice area (m^2)
BMEP	Brake mean effective pressure (bar)
BP	Brake power (kW)
BSFC	Brake specific fuel consumption (g/kWh)
C_d	Discharge coefficient
CO ₂	Carbon dioxide
NO _x	Oxides of Nitrogen
P	Pressure (N/m ²)
PMEP	Pumping mean effective pressure (bar)

Lower case

\dot{m}	mass flow rate (kg/h)
-----------	-----------------------

Greek

Δ	Difference
ρ	Density (kg/m ³)

Abbreviations

AMEP	Attachment mean effective pressure (bar)
BLD	Blowdown
CAD	Computer aided design
DEP	Divided exhaust period
EVO	Exhaust valve open
ExDEP	Externally divided exhaust period
GT-ISE	Gamma Technologies Integrated Simulation Environment
SCV	Scavenging

1 Introduction

1.1 Motivation

As stated by the European Council for Automotive R&D, there is a societal challenge to reduce the fuel consumption of heavy duty road vehicles by at least 20% with conventional control systems [1]. Technology known as turbocompounding is already in use to improve the utilisation of exhaust waste heat by introducing a turbine in the exhaust flow path and coupling this turbine to the engine crankshaft, thus converting exhaust thermal energy into mechanical work. A drawback of this technology is the increased back pressure in the exhaust path due to the flow resistance offered by the turbocompound. Prior research dealing with single-stage turbocompounding [2] has demonstrated that the part of the exhaust stroke after the initial high energy blowdown pulse can bypass the high pressure turbine, allowing expulsion of exhaust gases against a lower back pressure, hence increasing pumping work. This process of dividing the exhaust stroke into distinct paths is known as Divided Exhaust Period, and could involve either a division at the exhaust valves themselves (known as DEP), or external to the cylinder exhaust valves (known as Externally DEP or ExDEP). This improves cylinder scavenging and can enable a reduction in Brake Specific Fuel consumption

As the DEP method requires staggered opening of the cylinder exhaust valves, it results in greatly reduced flow area and leads to increased flow choking at each valve [3], adversely affecting combustion characteristics. In comparison, ExDEP architecture introduces additional valves downstream of the cylinder exhaust valves, thus retaining cylinder exhaust flow properties.

The possibility of retaining the benefits of turbocompounding and yielding up to 4% benefit in fuel consumption [3] while possibly reducing exhaust back pressure is the motivation to conduct this Master's Thesis work on Externally Divided Exhaust Period.

1.2 Objective

The objective of this thesis is to implement and observe the effects of ExDEP in a heavy duty diesel engine simulation model. This will be conducted through the investigation of prior studies of ExDEP and the requirements for valve technologies. Thermodynamic and mechanical models of an ExDEP system will be developed for use in an existing engine model in GT-SUITE to observe changes in fuel consumption.

1.3 Limitations and assumptions

In order to ensure the delivery of a working and well-documented model within the time frame of this project, some conditions and boundaries were necessitated:

- Transient operation of the engine is not considered
- Existing engine components and simulation parameters are retained as far as possible without modification
- Fluid dynamic analysis of exhaust flow is not performed
- Operation of the exhaust gas recirculation (EGR) circuit is not analysed
- Experimental verification and implementation of models is not done

2 Theory and modelling approach

2.1 Base model

The modelling of the ExDEP system has been carried out in the GT-SUITE engine simulation software using components modelled in and imported from CATIA for accurate representation. An existing engine model of a Volvo HDE13 (Heavy Duty Engine) is utilised to incorporate the ExDEP system. The Volvo HDE13 is an inline six cylinder, 12.8 litre diesel engine equipped with a twin-entry high pressure turbine driving a compressor, a single-entry axial flow low pressure turbine compounded to the crankshaft by means of reduction gearing. The engine is equipped with charge air cooling, electronically controlled fuel injection, an exhaust gas recirculation system and selective catalytic reduction. This engine model is utilised as it contains a pre-existing turbocompound that has been previously calibrated. It also contained extensive test cases performed at several static operating points, allowing a detailed selection of points and parameters for comparison. Figure 2-1 illustrates the general structure of the base engine model used in this project.

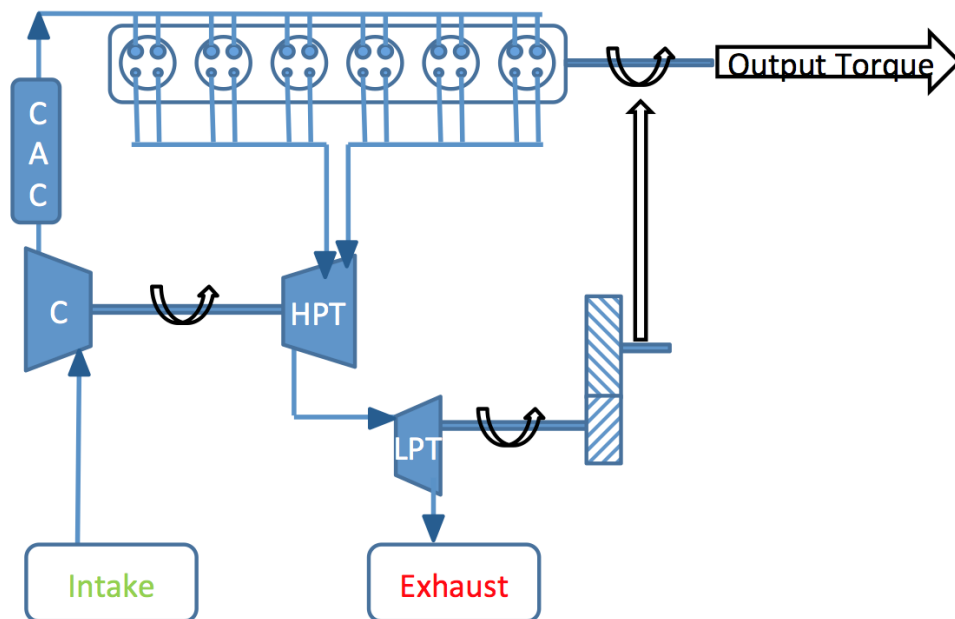


Figure 2-1 Schematic of base engine model

2.2 ExDEP architectures

Implementation of ExDEP in the existing model implies the addition of FlowSplit objects to the exhaust circuit within the GT-ISE interface to separate the exhaust gases into the blowdown and scavenging flows external to the cylinder.

To begin with, the GT-ISE base model was modified into two distinct architectures:

- Flow split after the exhaust port on each cylinder object, see Figure 2-2
- One flow split at each outlet of the exhaust manifold that connects to the corresponding entry of the high pressure (HP) turbine, see Figure 2-3

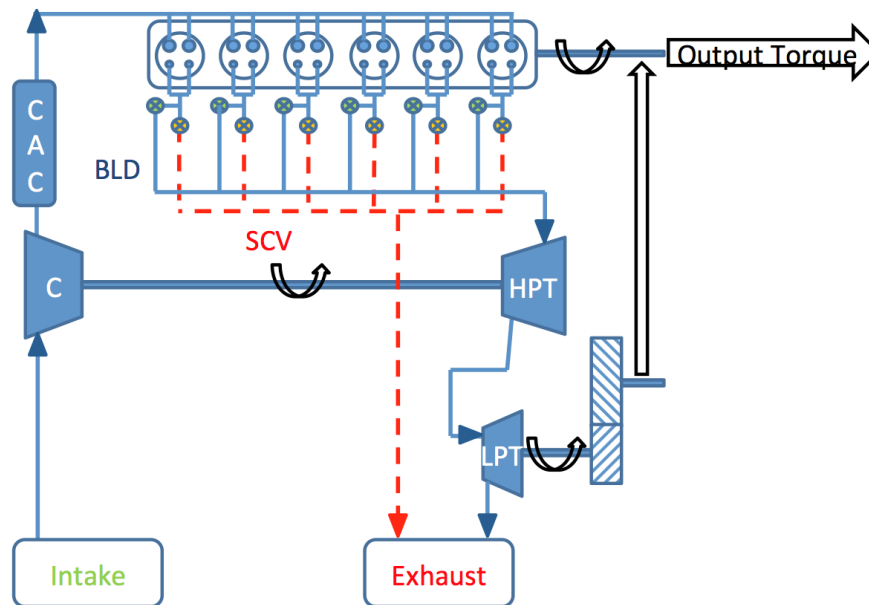


Figure 2-2 ExDEP flow split after exhaust port

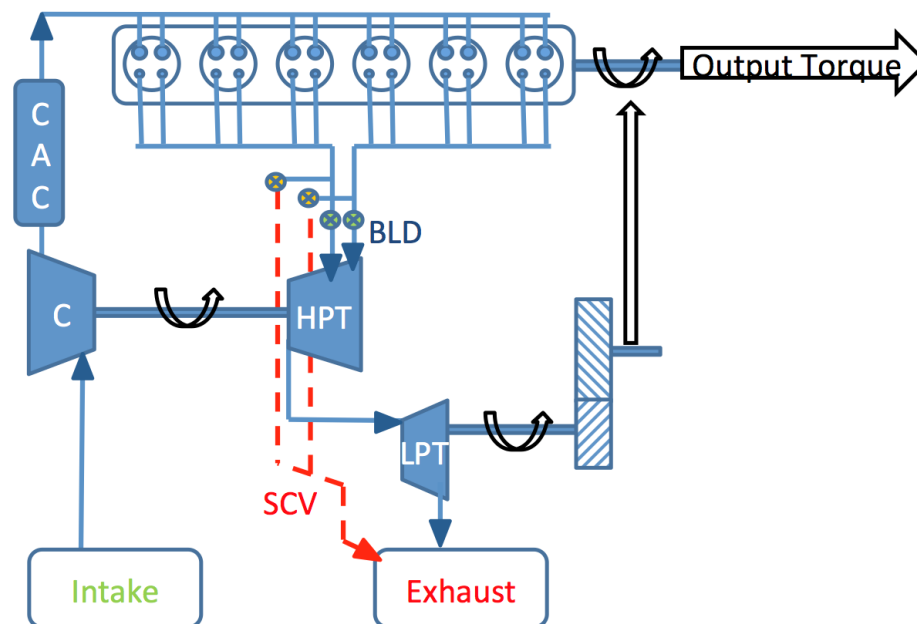


Figure 2-3 ExDEP flow split at exhaust manifold outlet

The second architecture was subsequently dropped as it was observed that only two ExDEP valves could not be used to time the flows from all six cylinders successfully. Correct ExDEP valve timing necessitated an overlap which resulted in the valve being constantly open when handling flows such as those shown in Figure 2-4, thus defeating the purpose of a flow split. The valve hence became just an inactive component in the flow circuit without dividing the gas flow.

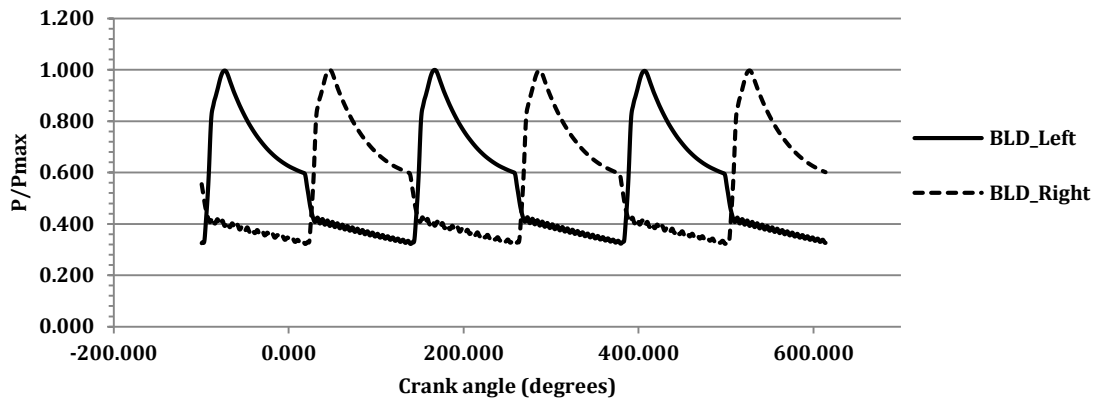


Figure 2-4 Overlapped pulses of total pressure in blowdown manifold

The first architecture was then implemented using several different concepts based on the type of valve object used and the lift profiles of the ExDEP valves. This was subsequently modified to route the scavenging flow to the LP turbine rather than to the exhaust because an experiment with such architecture showed substantial gains in shaft work. The final model architecture used is shown in Figure 2-5.

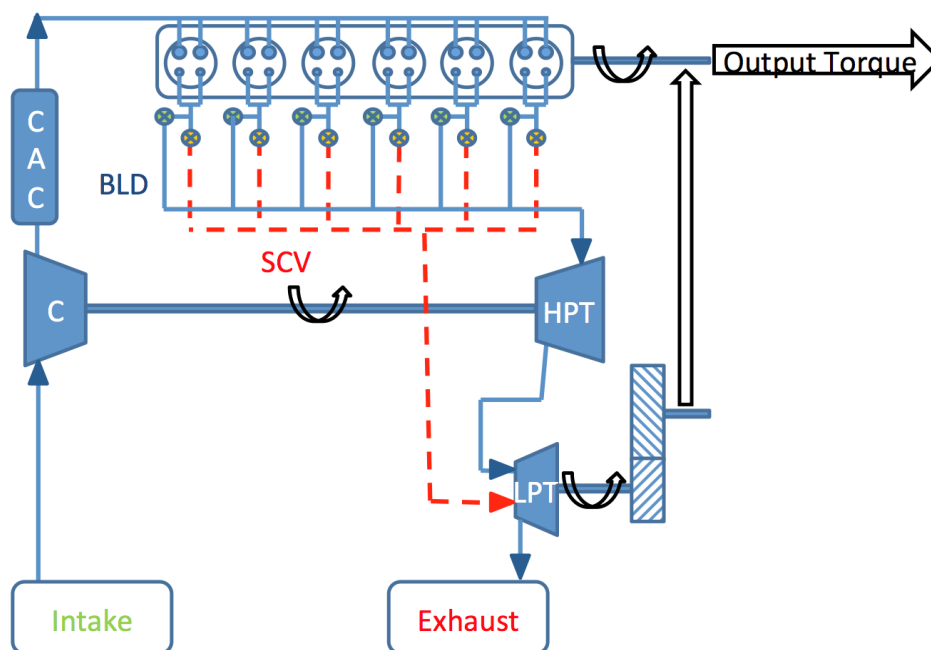


Figure 2-5 Final ExDEP architecture

2.3 Valve concepts

Two basic concepts modelled were rotary valves and fast-acting pneumatically-actuated poppet valves. Lift profiles simulated included nearly rectangular profiles (as commonly seen in pneumatic valves), linear profiles of rotary valves, cam-driven profiles (as used on the existing intake and exhaust valves) and combinations of these profiles. Since GT-SUITE requires valve timings to be defined by a two-dimensional array, it meant redefining the array for a Design of Experiments with a large number of different timings manually was an inefficient use of valuable simulation time. Hence the more complex, non-linear profiles were generated using MATLAB.

During the initial literature study, various valve concepts used commonly in automotive applications as well as other valve types were studied, such as:

- Spring-loaded check valve
- Butterfly valve
- Rotary valve
- Proportional control valve
- Electro-pneumatic valve

However, several of these valves had no reliable test data available. Also, since the ExDEP valves would be subjected to the extreme operating conditions of the exhaust circuit, it was decided to select valves that have been previously used in exhaust applications. Hence the rotary valve and the fast-acting electro-pneumatic actuated valve concepts were selected for modelling in GT-SUITE for the ExDEP application, and are described in the following sections.

2.3.1 Rotary valves

The rotary valve is a proven concept that has been in sporadic use for automotive applications for several decades. However, poor sealing restricted its widespread use through most of the 20th century. Recent improvements in valve seal technology have enabled a resurrection of rotary valves, especially in motorsport and small engine applications. Various versions of the rotary valve are currently being developed, manufactured and sold as intake and exhaust valves for automotive applications by aftermarket suppliers. One such valve developed by Coates International Ltd. [5] is pictured in Figure 2-6.



Figure 2-6 Coates Spherical Rotary Valve [5]

A rotary valve exhibits some benefits over conventional poppet valve systems, like:

- Simplicity of actuating mechanism
- Larger port areas
- Possibility to split flow into multiple paths with a single valve

However, several drawbacks are also associated with rotary valves when considering them for application in ExDEP.

- No actual flow data available
- No existing modelling object available in GT-SUITE
- Phasing and variable opening profiles require extremely complex designs
- Timing six ExDEP profiles results in almost constantly open valve
- Unreasonably large size and packaging problems with one valve per cylinder

Since GT-SUITE does not have a rotary valve object that can directly be implemented, the rotary valves were modelled using the *OrificeConn* object as in Figure 2-7. The forward and reverse discharge coefficients of the orifices could be varied based on crank angle and defined in an array within the object, while the dimensions of the port can be specified as the orifice diameter (this adds some complication when the ports have to be any shape other than circular). However this was verified to be the best way to model a rotary valve after contacting Gamma Technologies Inc.

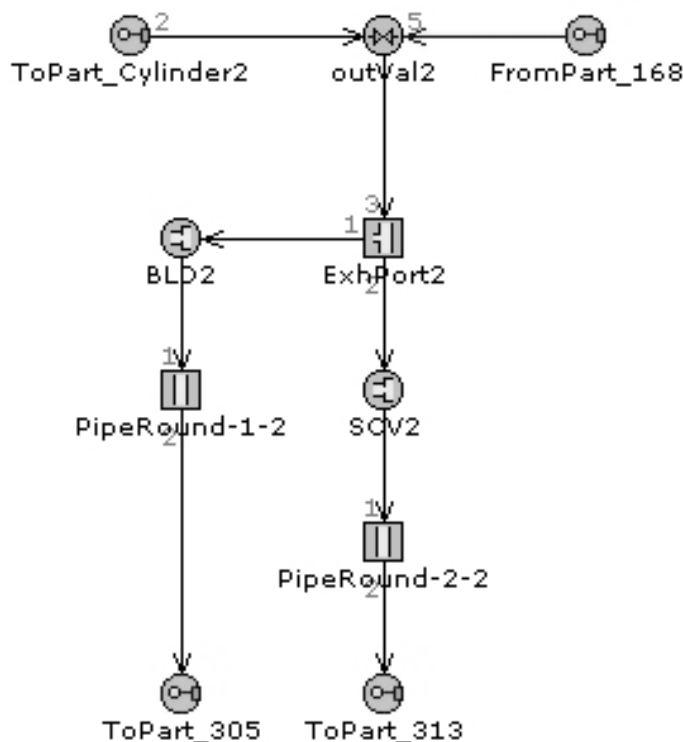


Figure 2-7 Rotary valves modelled using Orifice objects in GT-SUITE

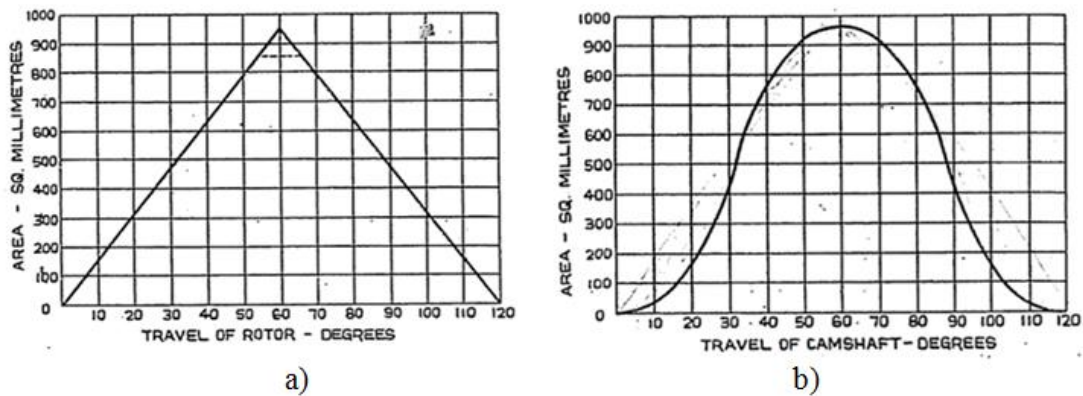


Figure 2-8 Variation of effective flow area of a) rotary valves, b) poppet valves [7]

As seen in Figure 2-8, with most normal rotary valves the discharge coefficient linearly increases from zero as the port/window on the rotor comes across the port on the stator.

Maximum discharge coefficient is achieved when both the ports are perfectly superimposed on each other and then it linearly reduces to zero as the rotor port moves past the stator port. The ports were sized based on the flow area of adjacent components, however since no actual flow test data from rotary valves was available the valve model created was an ‘ideal valve’ which achieved a maximum forward and reverse discharge coefficient of unity when both the ports are perfectly superimposed. However, actual discharge coefficients depend on port size and geometry, and seldom reach the value of unity.

The discharge coefficient through an orifice can be described using equation (2.1) [7] and equation (2.2) [8].

$$C_d = \frac{\dot{m}}{A_r \sqrt{2\rho\Delta P}} \quad (2.1)$$

$$A_e = C_d A_r \quad (2.2)$$

Rudimentary CAD models of the rotary valves were prepared to assist in visualization of packaging them next to the cylinder head, see Figure 2-9.

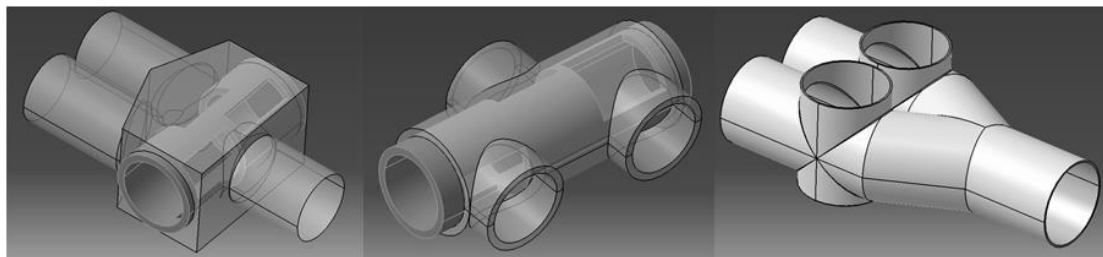


Figure 2-9 CAD concepts of various rotary valve configurations

One of the issues faced with rotary valves was packaging of the rotors, as in Figure 2-10. Several different packaging strategies were envisioned. Having the rotor axes parallel to the crankshaft meant they could easily be driven off the crankshaft, however this was a complicated way to position two independent rotors (one each for blowdown and scavenging) at each exhaust port given their estimated sizes.

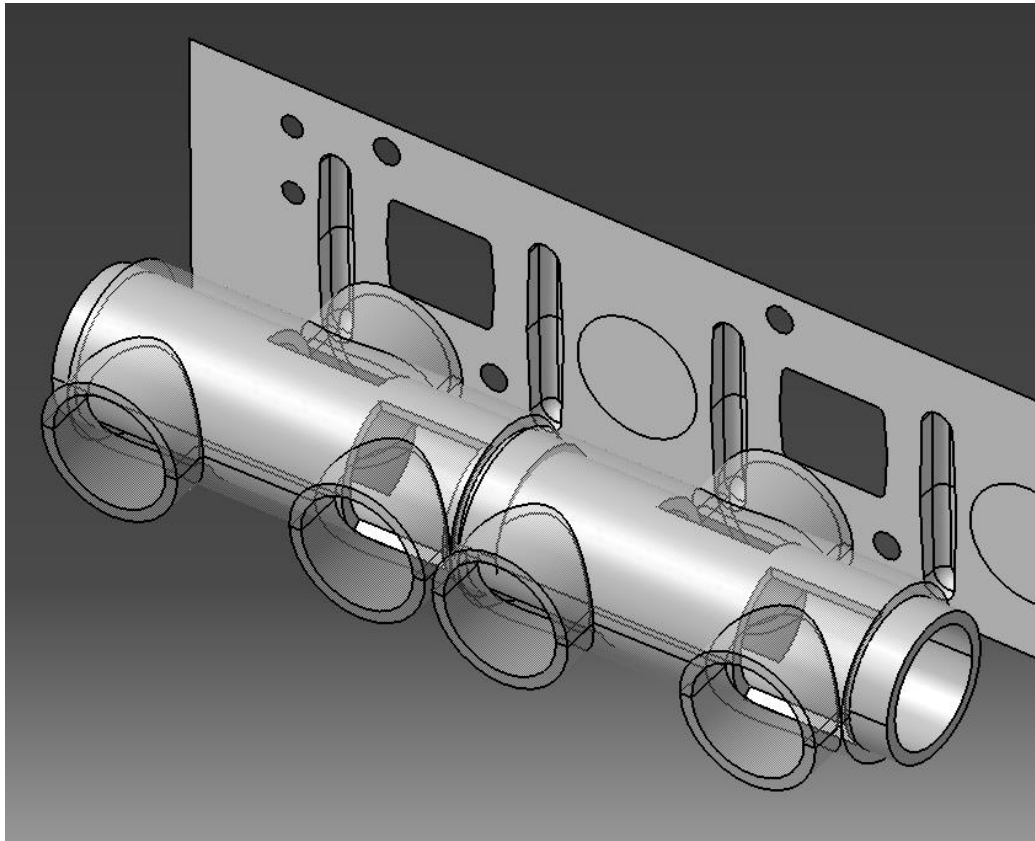


Figure 2-10 Interference in valve rotors

Also further simulations of ExDEP showed the need for independent lift timings and open durations to obtain best results at different operating points of the engine. This would necessitate a complex rotary valve with a moving stator port or one where the dimensions of the stator window can be varied during operation. These challenges along with the lack of accurate flow data for such a model meant that the rotary valve idea had to be dropped midway through the project.

2.3.2 Fast-acting valves

The actuation of a conventional poppet valve completely independent of crankshaft rotation is a technology that is rapidly gaining popularity in the automotive sector. Actuation of fast valves can be implemented in several ways. One design currently being tested with positive results for passenger car applications is by a Swedish firm Freevalve AB (Cargine Engineering AB) [9]. The Freevalve design, as pictured in Figure 2-11, is an electronically controlled pneumatic-hydraulic actuator that can achieve rapid valve actuation using conventional poppet valves fully independent of crankshaft rotation [10].

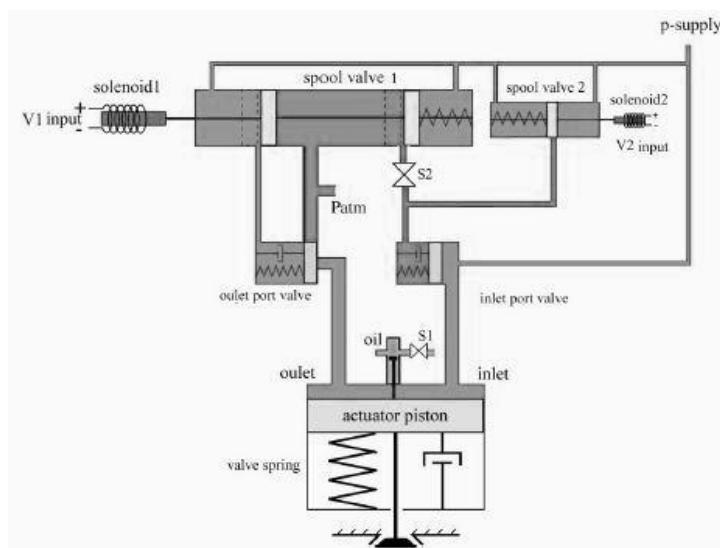


Figure 2-11 Cargine Freevalve system [10]

The Freevalve design is hydraulically damped and is hence free of the float and bounce problems associated with cam-driven poppet valves. They have several other benefits over conventional valves, including:

- Ability to instantly vary timing and lift for individual operating points
- Very fast actuation for almost stepped valve response, see Figure 2-12
- No drastic system redesign required. Cam-less actuation mechanisms can drive conventional poppet valves
- Ease of implementing in GT-SUITE using existing modelling objects

However, such a system comes with its own drawbacks, including;

- Higher energy consumption than cam technology, as the pressurised air from the actuating circuit is exhausted into ambient air [11].
- Extreme variation in operating conditions due to exhaust temperatures could cause unpredictable and unstable behaviour of such valves due to variation of the viscosity of hydraulic fluid with temperature [10]. However, this instability is of reduced significance with ExDEP applications compared to in-cylinder exhaust valves.
- Such a system would also require the design and implementation of a dedicated electronic control system.

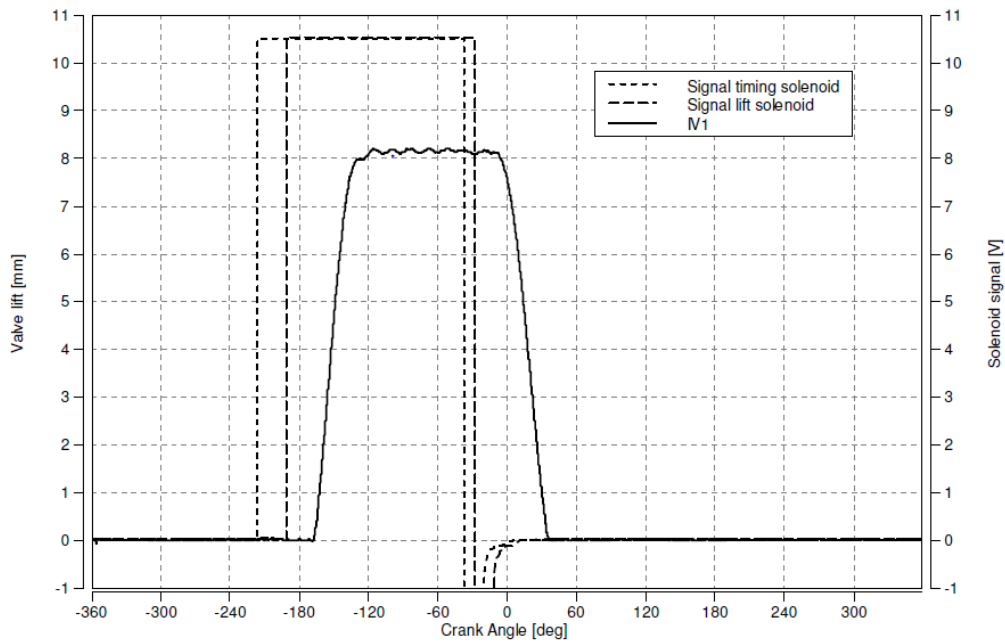


Figure 2-12 Typical fast valve solenoid signals and valve movement [10]

The fast valve is modelled in GT-SUITE using the existing *ValveCamPRConn* object (same as the intake and exhaust valves), as seen in Figure 2-13. This implies that the flow data for the valves was already available from the existing engine model. The flow data has been obtained through static pressure differential flow tests conducted previously. However, this data is sufficiently accurate for the model and has already been used in the exhaust valves. The valves could be resized in GT-SUITE as necessary, in combination with the available flow data and lift profiles to simulate fast pneumatic poppet valves.

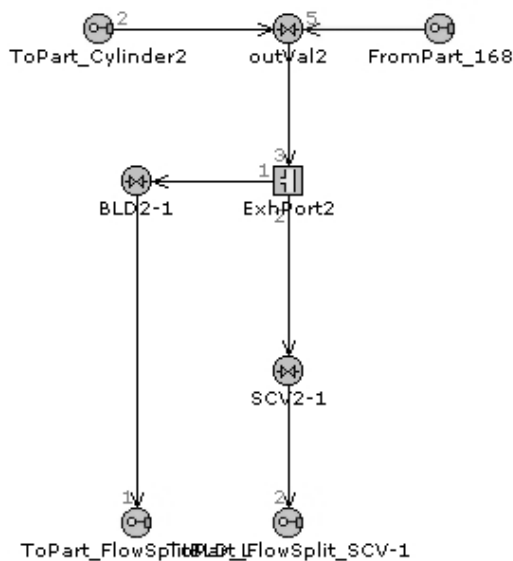


Figure 2-13 ExDEP valves modelled using *ValveCamPRConn* objects in GT-SUITE

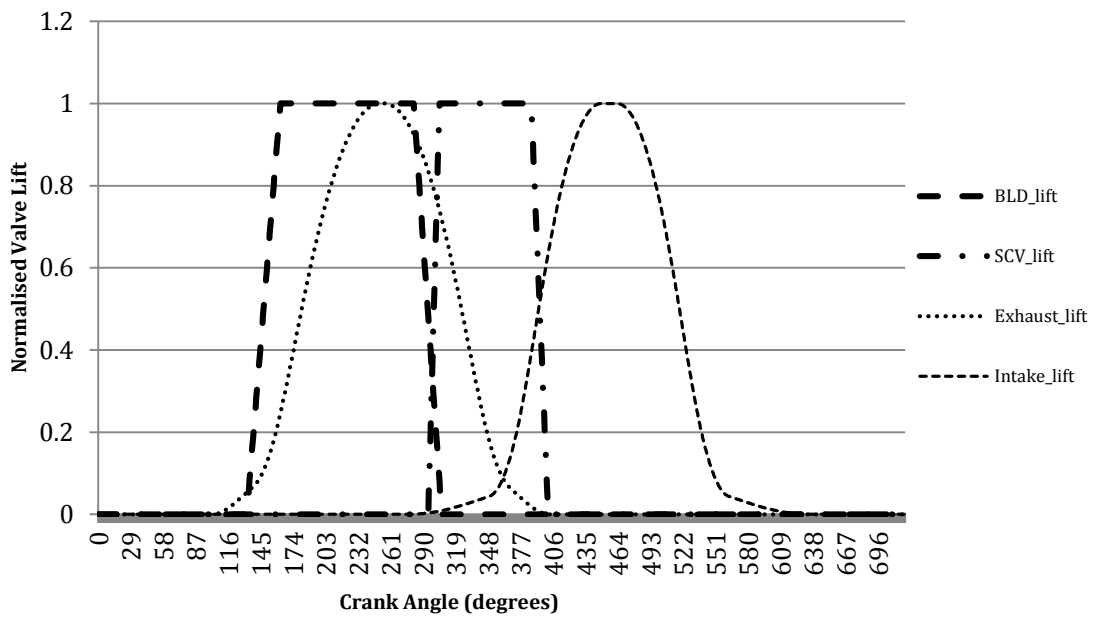


Figure 2-14 Lift profiles defined for different valves

Since the valves are described as fast pneumatic valves, they are driven completely independently of the crankshaft. The lift profiles defined are also idealised with minimal deviation from actual lift behaviour, as seen in Figure 2-14.

Fully independent timing and open duration could now be achieved more easily using these profiles. This concept comes with its own packaging requirements, which was again checked by preparing simple CAD models of the concept in CATIA, as in Figure 2-16.

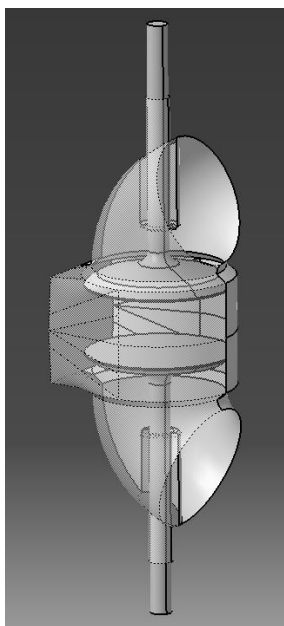


Figure 2-15 CAD of independently actuated poppet valves

From some prior experience of engineers at Volvo it is known that the energy consumption of current pneumatic valve mechanisms is slightly higher than that of cam-driven mechanisms. Though this was not modelled due to a lack of actual data, energy consumption can be easily implemented in the model when data becomes available.

A normal cam-driven poppet valve system is difficult to implement for ExDEP due to the short duration in which the valve is required to open fully, achieve sufficient flow through area for the required duration, and then close. The problem is compounded when some type of variable valve actuation/timing (VVA/VVT) mechanism is required.

Fast-acting poppet valves can also be modelled in GT-SUITE using the object *ValveCamUserConn*. This object implements a user subroutine which allows control over the valve timing by parameterisation rather than having to change the entire valve lift array for each experiment. However, creating this subroutine requires knowledge of FORTRAN programming, and was thus not performed under the limited time frame of this project. This method is utilised in another Master's thesis work [12] conducted at Chalmers University of Technology.

2.4 Flow path modelling

Re-design of the exhaust manifolds and flow path objects upstream of the HP turbine was necessitated due to the introduction of ExDEP, this constitutes flow path modelling. The only change made to flow paths downstream of HP turbine was connection of the scavenging flow to the LP turbine inlet. Minimal changes to the system ensure simplicity and translate to minimum redesign/re-manufacture cost in reality.

Modelling of these components helps to understand the volume sensitivity of the specific engine model under investigation. After the volumes of manifolds (with sufficient cross-sectional areas) are obtained through initial simulations and after the ExDEP valves are sized to accommodate flow under the studied operating points the dimensions obtained are used to prepare surface models in CAD in conjunction with packaging requirements. All CAD modelling is done using CATIA (V5-6 R2012 build 22) that allows easy modelling and visualisation of surfaces.

The models are then discretised in the GEM3D tool of GT-SUITE to obtain accurate flow components models, which are then implemented in the object. GEM3D is able to compute cross-sections and bends accurately, hence improving the accuracy of the model. The difficulty with this however is that even the simplest changes in geometry imply that the CAD model will have to be edited/updated, discretised again and then included in the model. This consumes a significant amount of time, but reduces the risk of having an overly simplified and unrealistic simulation model.

2.4.1 Exhaust port and valve body

The exhaust port object in the existing model is a straight pipe object, whose length and diameter are parameterised to understand their effects on performance. During initial stages of this project the ExDEP valve body, flow split and associated manifolds were visualised as an add-on system as in that could be bolted onto the cylinder head at the ports, as in Figure 2-17a. However at a later stage it was decided that integration of the valve bodies into the cylinder head would yield best performance due to reduction of dead volumes in the exhaust ports, as in Figure 2-17b.

This meant that the exhaust ports had to be redesigned to accommodate a valve body based on the size and lift of each valve. GEM3D allows these changes to be accurately represented in the model rather than having a simple pipe object with defined length and diameter.

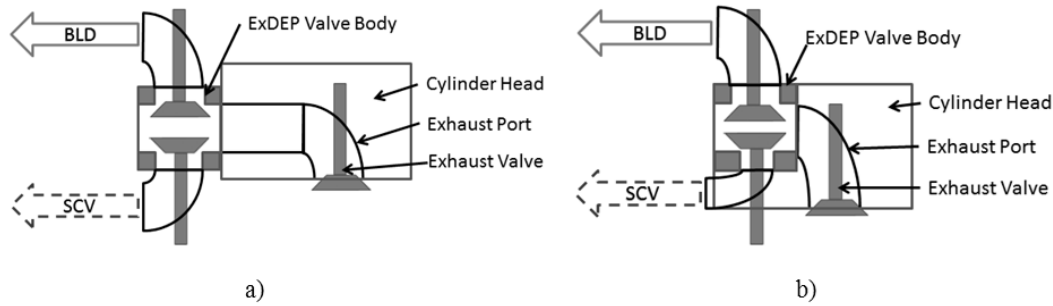


Figure 2-17 Valve bodies a) at exhaust port; b) integrated into exhaust port

Depending on the placement of each valve actuator the valve body may need to be angled so that it may not interfere with the cylinder itself. Though this might affect the performance it will have minimal effect on the volume itself and requires further study.

2.4.2 Blowdown manifold

The blowdown manifold in Figure 2-18 is comprised of two distinct halves based on the original exhaust manifold, where each half feeds flow from its corresponding cylinders into one entry of the twin scroll HP turbine.

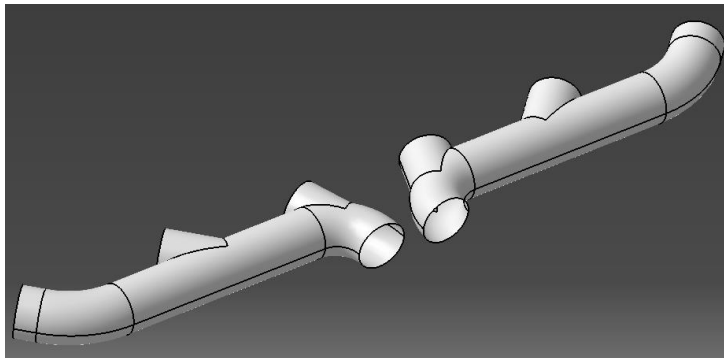


Figure 2-18 Blowdown manifold with two outlets to high pressure turbine

Reduction in volume of this manifold is complicated as it requires sufficient cross-sectional areas based on the diameters of adjacent flow components while each of its sections simultaneously must have the required length based on the spacing between cylinders/exhaust ports. Figure 2-19 shows the manifold imported from CATIA into GEM3D to be discretised for use in the engine model. The discretised model of the manifold is seen in Figure 2-20.

Redesign of the exhaust port to accommodate the valve body allows each blowdown outlet to now be angled towards the HP turbine inlet as in Figure 2-21 in an effort to reduce the volume of the blowdown manifold.

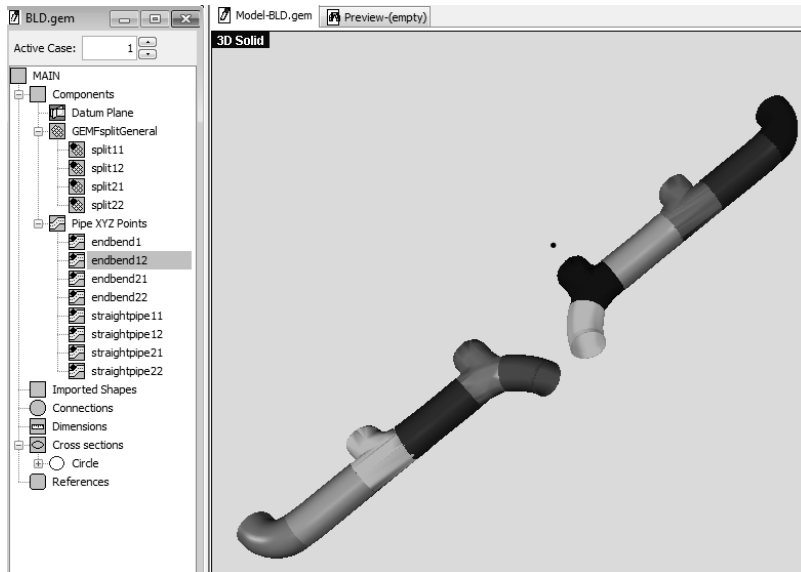


Figure 2-19 Blowdown manifold in GEM3D

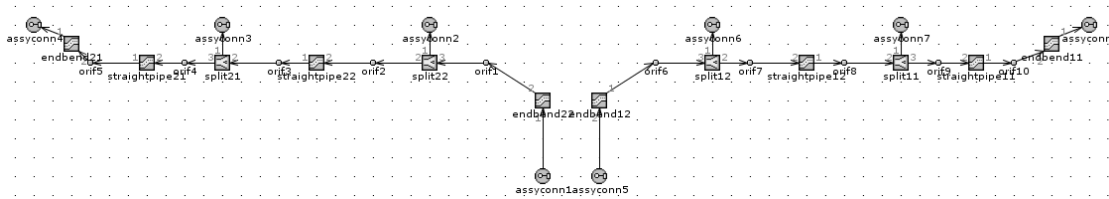


Figure 2-20 Discretised flow model of blowdown manifold

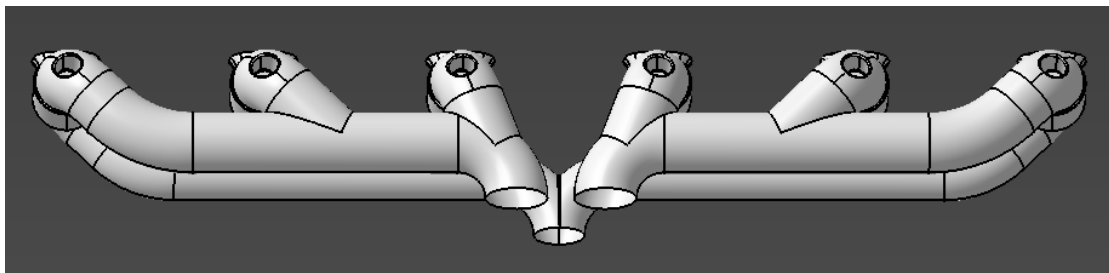


Figure 2-21 Redesigned manifolds with angled exhaust ports

2.4.3 Scavenging manifold

The scavenging manifold seen in Figure 2-22 is comprised of just one section, feeding flow from all six cylinders to the single entry LP turbine. With progressive simulations showing that the necessary scavenging flow is smaller than the blowdown flow at all operating points, the scavenging valve and flow path is now comparatively downsized resulting in a manifold with ~60% cross sectional area of the blowdown manifold. Angling the scavenging flow outlet of the valve body toward the LP turbine inlet further minimises the volume.

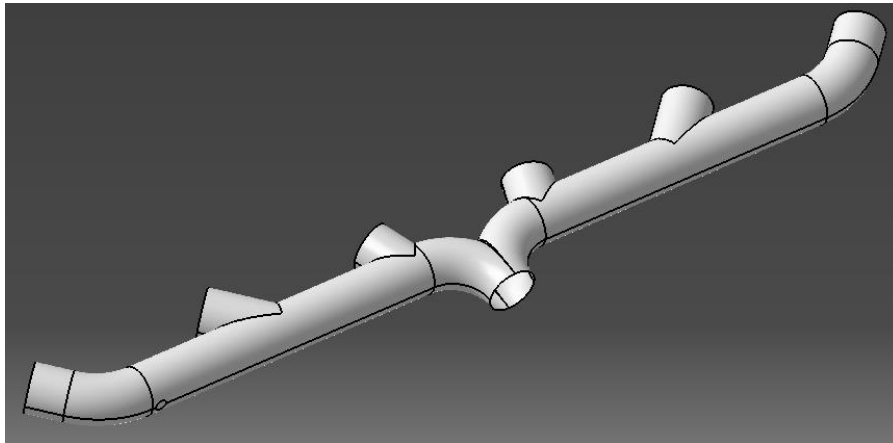


Figure 2-22 Scavenging manifold with single outlet to low pressure turbine

2.5 Single entry turbocharger

The valve timing optimisation being carried out resulted in local minima in BSFC, where the duration of exhaust pulses from each cylinder were distinctly spaced at each inlet to the HP turbine. After a discussion with engineers at Volvo GTT, it was proposed that these pulses could be overlapped, as in Figure 2-23, using a single blowdown manifold having only one outlet to a single entry turbocharger.

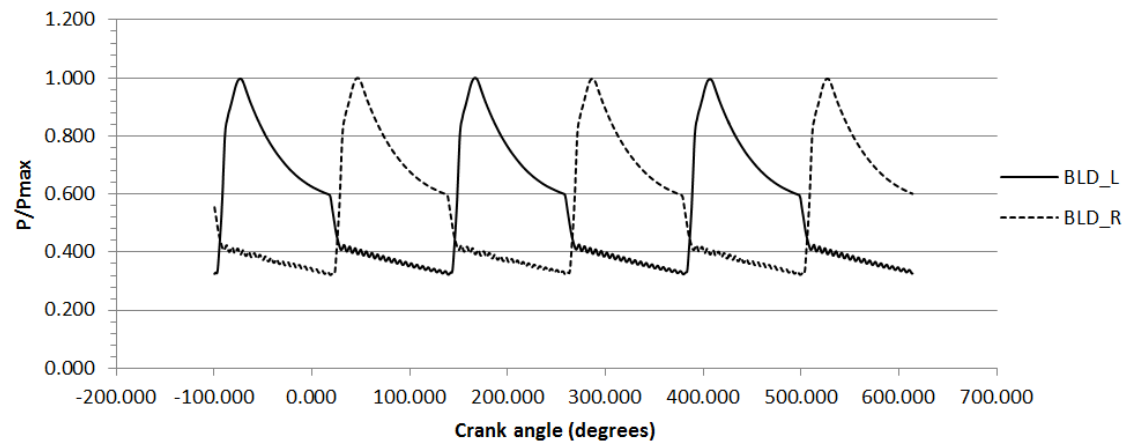


Figure 2-23 Pressure pulses in both halves of blowdown manifold

To further decrease the pressure fluctuation/pulse amplitude, an experiment was conducted with a diffuser placed after each blowdown valve. In order to keep volumes at a minimum, the diffuser length was maintained at 21.5% of the exhaust port length with a cone angle of 8° . At the entry of the diffuser, the exhaust gas velocity is so high that it does not possess sufficient time for diffusion using such a short diffuser. However, an increase in diffuser length contributed more to increase in volume than any perceivable pressure recovery in the blowdown manifold. Hence the idea of a diffuser was dropped.

It was thought that such a manifold would create a more constant pressure flow that could be utilised better by a single entry turbocharger, leading to larger performance gains. A single entry turbocharger was implemented in GT-SUITE by resizing the existing turbine and using existing data. This was tested in conjunction with a simple diffuser/venturi added to the flow path just downstream of the blowdown valves. The cone angle of the diffuser was restricted to 7 degrees [13] to have maximum efficiency without flow separation, which may not be simulated properly in GT-SUITE. The length of the diffuser was also kept to a minimum (nearly equal to its inlet diameter) in order to minimize volume.

The investigation revealed benefits at two of the five chosen operating points. However, further investigation with a calibrated model of a single entry turbocharger is required to verify possible benefits.

3 Simulation

All simulations are performed using GT-SUITE v.7.2 flow simulation tool used at the Advanced Technology and Research centre of Volvo GTT. This is a one-dimensional fluid dynamics software that uses the Navier-Stokes equation in conjunction with empirical data, maps and look-up tables to compute averaged flow parameters across flow direction [3]. The following sections describe the method in which simulations were conducted on the ExDEP model.

3.1 Operating points

A total of five operating points of the engine were chosen for all simulations: three at low engine speeds and two at moderately higher engine speeds. The points chosen are described in Table 1.

Table 1 Engine operating points chosen for simulation

Point	Speed [rpm]	Load [%]	Comment
A	1100	37	Road-load conditions
B	1100	56.6	
C	1100	100	Max. Torque demand for gradeability, etc.
D	1600	59	Gear shifting
E	1600	100	

3.2 Simulation method

For the initial simulations on each model, the dimensions of all additional flow components (which do not exist in the base model) such as diameters, lengths, volumes and surface areas were approximated based on necessary flow areas and dimensions of adjacent flow components. Many of these dimensions were parameterised and varied in sweeps to observe their individual influence on the performance of the system.

Despite the actual engine using two exhaust valves per cylinder, the original engine model contained only one exhaust valve per cylinder, using a flow multiplier to simulate the two-valve setup. However during the later stages of this thesis when the exhaust port geometry was altered and the port object was updated in the model from CAD, an additional valve was added per cylinder. The base model with one exhaust valve was also updated to have two valves at first to eliminate discrepancy in simulation results. However, the accuracy of the exhaust port itself was improved in the ExDEP models compared to the simple pipe object used in the base model.

Simulations are performed to get each parameter's optimum at each operating point. Optimum turbine mass multipliers are found for each point. However, such localised optimisation of turbine mass multipliers is unrealistic. The turbine is thus resized uniformly based on the rescaling at the operating point that shows maximum gains.

A general simulation methodology consists of the procedure below:

- Parameterise dimension/geometry of existing upstream flow components
- Vary these parameters individually in sweeps to find optimum
- Investigate closest realistic geometry in CAD
- Create CAD
- Update parameters in simulation model and reiterate
- Find suitable geometry that yields benefits at all points

3.3 Parameters

The following parameters were varied independently to study their influence on the performance of the system:

- BLD open (start of EVO to fully open, steps of 5 crank angle degrees)
- BLD close (exhaust valve fully open to EVC, steps of 5 crank angle degrees)
- SCV open (exhaust valve fully open to EVC, steps of 5 crank angle degrees)
- SCV close (exhaust valve fully open to EVC, steps of 5 crank angle degrees)
- BLD diameter (100-160% of exhaust valve diameter, steps of 30%)
- SCV diameter (100-160% of exhaust valve diameter, steps of 30%)
- Exhaust port length (100-60% of exhaust port length, steps of 10%)
- HP Turbine mass multiplier (50-200% of original turbine size)
- LP Turbine mass multiplier (50-200% of original turbine size)

3.4 Performance parameters

The BSFC of the engine model is monitored for all simulations as this is a good gauge of the efficiency of any engine. Brake specific fuel consumption is the mass flow rate of fuel used per unit brake power, as in equation (3.1).

$$BSFC \left[\frac{g}{kWh} \right] = \frac{\dot{m}_f}{BP} \left[\frac{g/h}{kW} \right] \quad (3.1)$$

Though the BSFC of the engine model is mainly observed to gauge its performance, other parameters are recorded in an attempt to fully understand the effects of ExDEP. These include:

- Crankshaft attachment power– power obtained from turbocompound shaft
- Mean effective pressures (BMEP, PMEP, AMEP)
- Cylinder pressure

4 Results

4.1 Observations

Before discussion of the main results the following observations made during experiments will help understand why the necessary changes were made to the model/architecture.

4.1.1 Volume sensitivity of the model

Increase in the flow path volume upstream of the HP and LP turbines proportionally deteriorates the fuel consumption, seen in Figure 4-1. Hence volumes were minimized wherever possible. The variation of pressure and velocity with changing these volumes is shown in Figure 4-2. This proved especially challenging at the manifolds since a lower volume is desirable without having lower cross section (which will reduce flow through area and affect the mass flow rates). Also around the ExDEP valve body this is particularly challenging to obtain sufficient flow area for the valves, but not have them so compact that flow chokes.

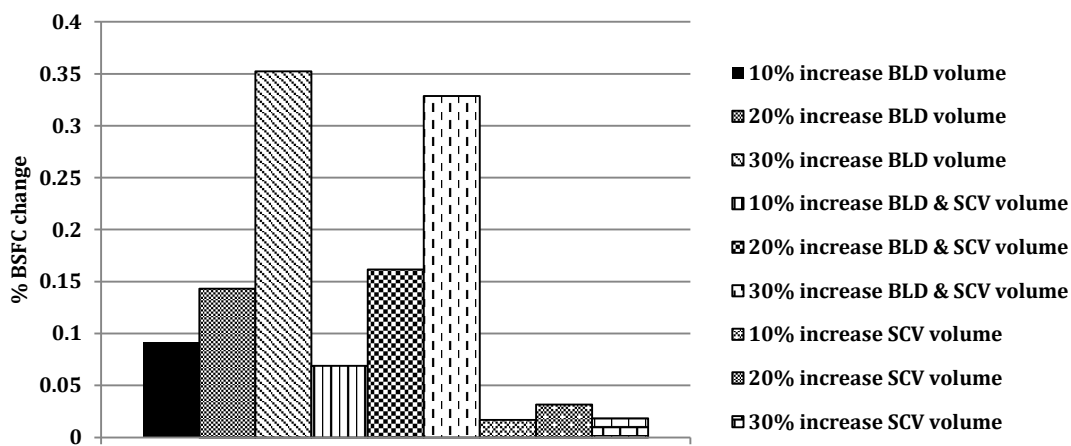


Figure 4-1 Change in BSFC with ExDEP manifold volumes

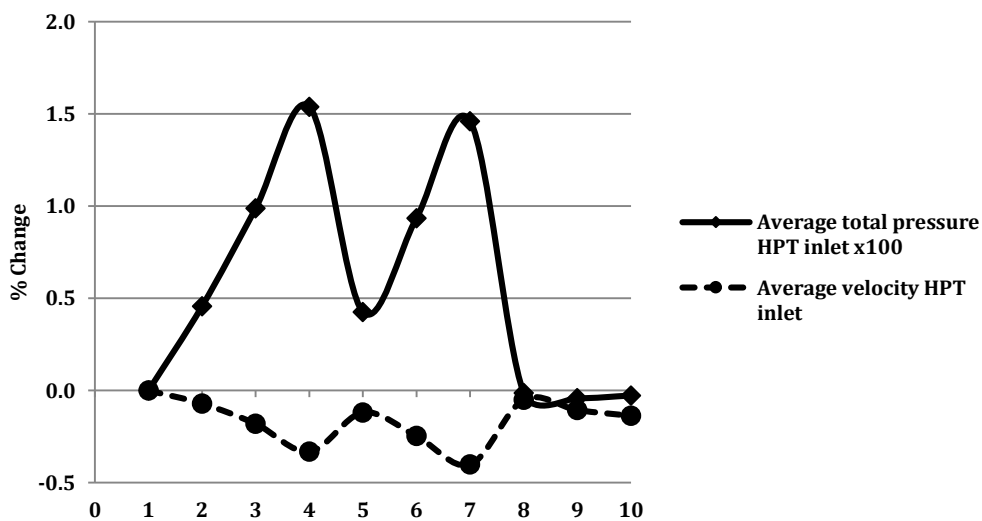


Figure 4-2 Variation of exhaust pressure and velocity at inlet of HP turbine

4.1.2 Exhaust port length

Reducing the length of the exhaust port improves the engine performance as in Figure 4-3, which is again a consequence of reduction in volumes upstream of the turbines. The effect of exhaust port length is verified by parameterizing the length of the exhaust port object and varying it with all other parameters kept constant. This led to the idea of having the ExDEP flow split and valve body within the exhaust port itself. This brings about some more new packaging challenges within the cylinder head and will require redesign of the cylinder head.

Figure 4-4 shows the variation of rate of convective heat transfer with changing exhaust port length, relative to the base model. This implies that the exhaust gas exiting the port contains a larger fraction of thermal energy that can be utilized for expansion in the turbine.

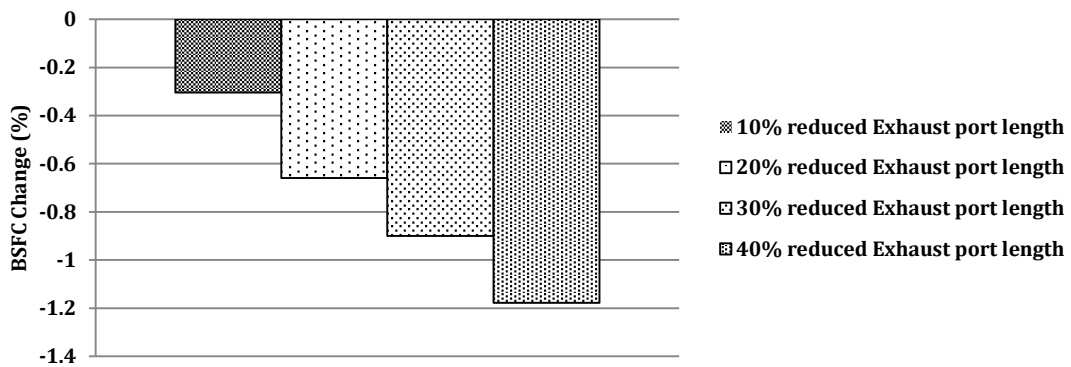


Figure 4-3 Variation in BSFC with exhaust port length

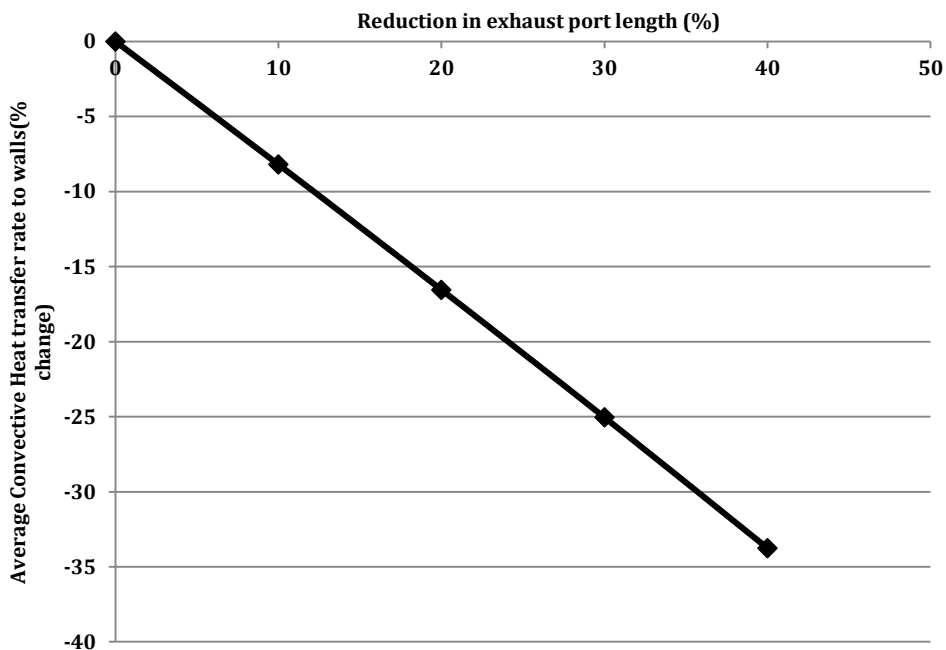


Figure 4-4 Variation in rate of convective heat transfer with exhaust port length

4.1.3 Routing of scavenging flow

When the scavenging exhaust flow is directed to the LP turbine, a substantial gain in shaft power is obtained at the expense of increased back-pressure, seen in Figure 4-5. Discussions with Volvo engineers revealed that this increase in shaft power by diverting some part of the expansion to the LP turbine of the model is not always accurate and the actual gain may be as low as 50% of calculated increase, but this is still a large gain. This led to a change in model architecture where the scavenging flow was then fed to the LP turbine instead of directly being exhausted.

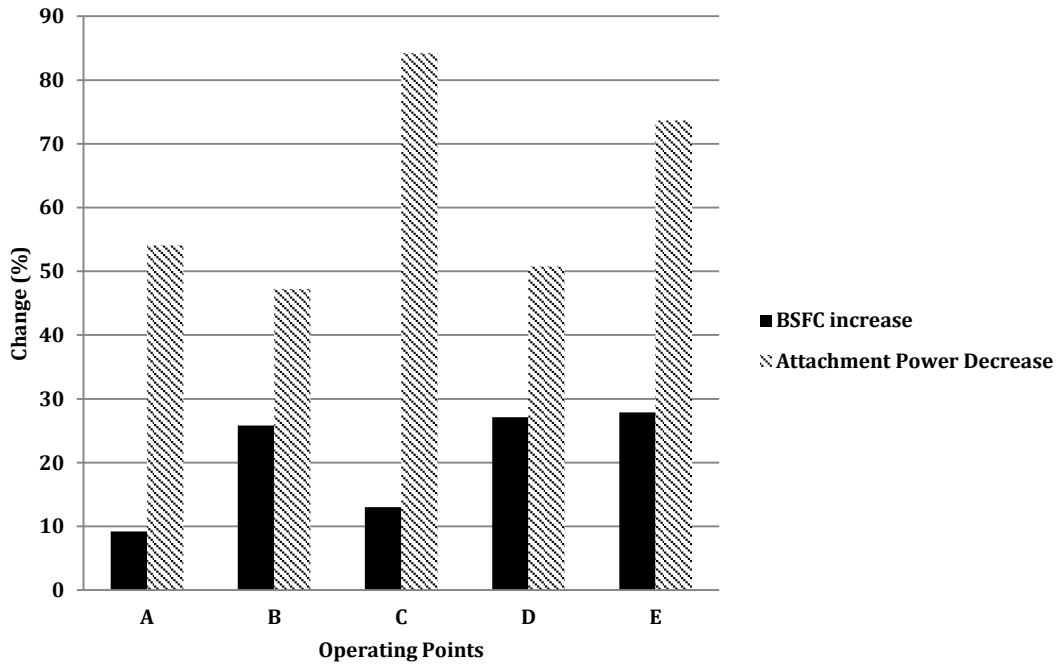


Figure 4-5 Variation of BSFC and attachment power with SCV flow diversion to exhaust

4.1.4 ExDEP valve diameters

To begin with the valve diameters on the ExDEP valves were 1.6 times the diameter of the exhaust valves as this provided the best flow characteristics. However during simulation, a 10% increase in the diameters of the ExDEP valves over the diameter of the exhaust valve decreased the BSFC by nearly 0.3g/kWh. The valve diameters were progressively reduced to obtain a compromise between performance and packaging requirements. The valve diameters in Figure 4-6 and Figure 4-7 are expressed as a percentage of the exhaust valve diameter.

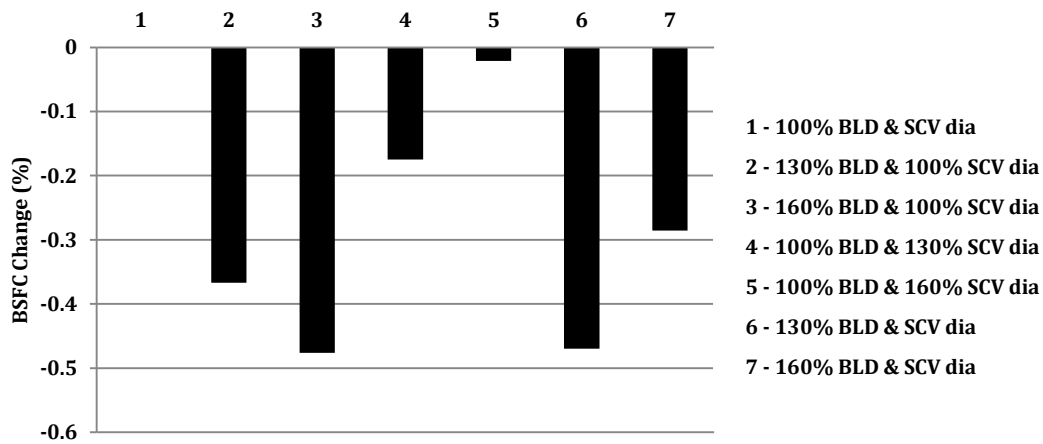


Figure 4-6 Variation of BSFC with ExDEP valve diameters

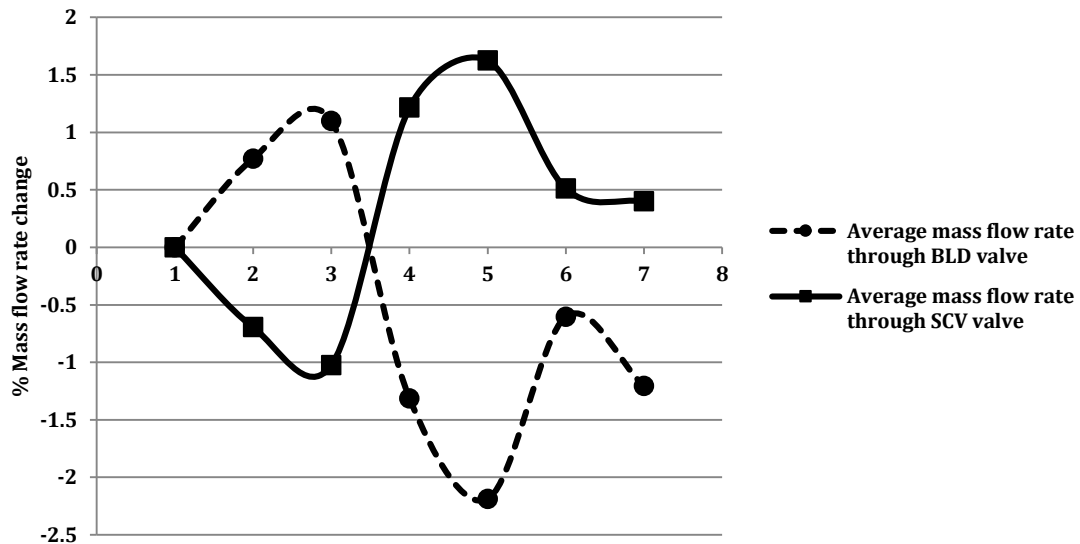


Figure 4-7 Variation of mass flow rate through ExDEP valves with valve diameters

4.2 Simulation results

This section presents the results of the final ExDEP model implemented on the Volvo HDE13 engine. Parameter sweeps were focused at obtaining benefits primarily at operating points A and B, as these points are closest to averaged data of the European Transient Cycle (ETC) [14]. The ExDEP valve diameters used in the final simulations are 140% of the exhaust valve diameter.

4.2.1 Brake Specific Fuel Consumption (BSFC)

Figure 4-8 shows that an improvement in BSFC of the ExDEP architecture is obtained at all chosen operating points. Though primary gains are at medium loads for both the operating speeds chosen, there exist minor gains at low and high loads as well. A significant observation is that the existing engine components were designed to target gains at these points. Resizing of components (e.g.: exhaust manifolds, exhaust valve diameters) could shift the points of maximum gains towards the lower end of the load range.

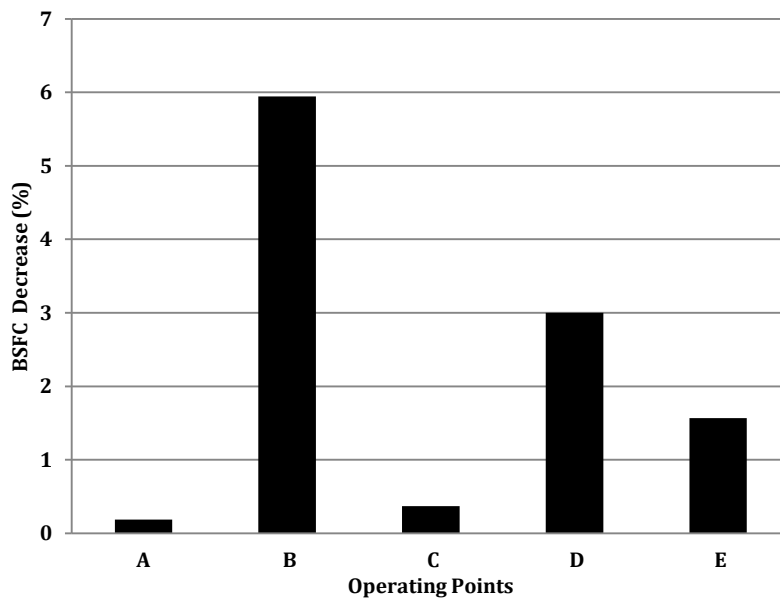


Figure 4-8 BSFC improvements of studied load points of ExDEP architecture over base engine

4.2.2 Attachment Power

The attachment power or the power obtained at the crankshaft from the turbocompound shaft is increased at all operating points, with larger gains obtained at part-load. The results are normalised against the largest gain since at operating point A, the original engine had negative attachment power, implying the LP turbine was drawing power off the crankshaft. The ExDEP model reverses this direction of power flow, the large gain at this point in Figure 4-9 is a result of this reversal. The overall increase in attachment power is due to the increased flow pressure to the LP turbine.

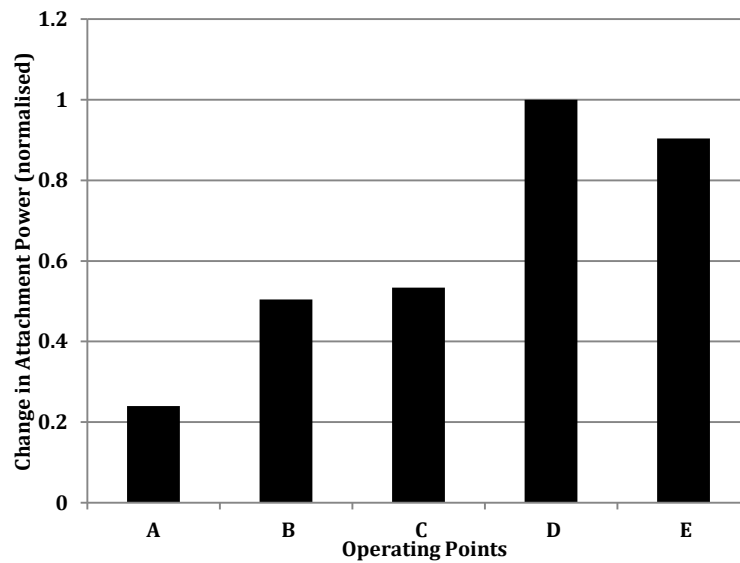


Figure 4-9 Normalised gain in crankshaft attachment power of the ExDEP model over the base model

4.2.3 Mean Effective Pressures

The pumping work of the ExDEP model has increased over the original engine. This is indicated by a larger negative pumping mean effective pressure (PMEP). The increase is shown in Figure 4-10. With the current engine architecture, exhaust flow is routed to the turbocompound via the HP turbine. Any attempt to reduce pumping loss through ExDEP would result in reduced flow to the HP turbine, leading to lower boost and hence output power. Though previous studies on ExDEP demonstrate a reduction in back-pressure, this is not applicable to the Volvo HDE13 due to the architecture of the turbocompound.

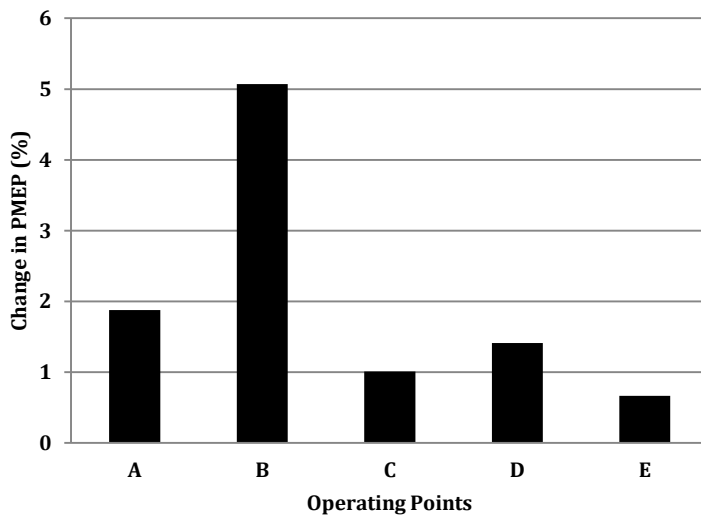


Figure 4-10 Change in negative PMEP of the ExDEP model over the base model

The increase in the attachment power in terms of MEP (illustrated as Attachment-MEP or AMEP) of the ExDEP model is illustrated in Figure 4-11. The combined effect of PMEP and AMEP results in an overall BMEP effect at the crankshaft, seen in Figure 4-12. When considered together with the reduced fuel flow rate from Figure 4-13 it provides a net benefit in fuel consumption.

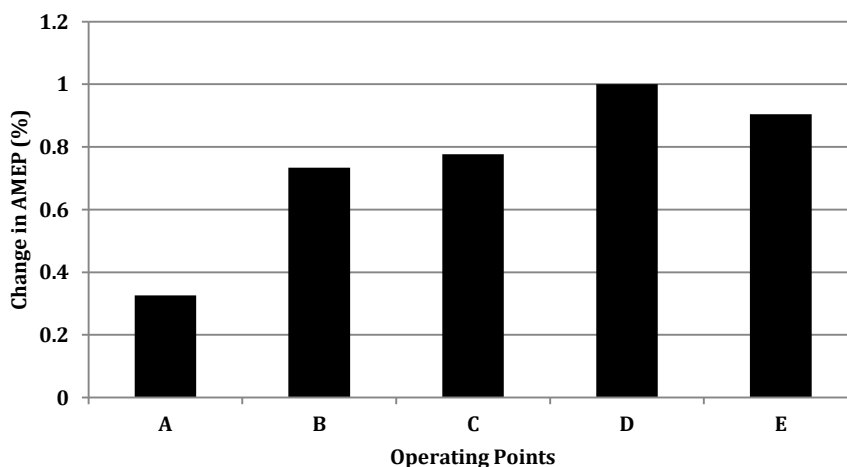


Figure 4-11 Change in AMEP of the ExDEP model over the base model

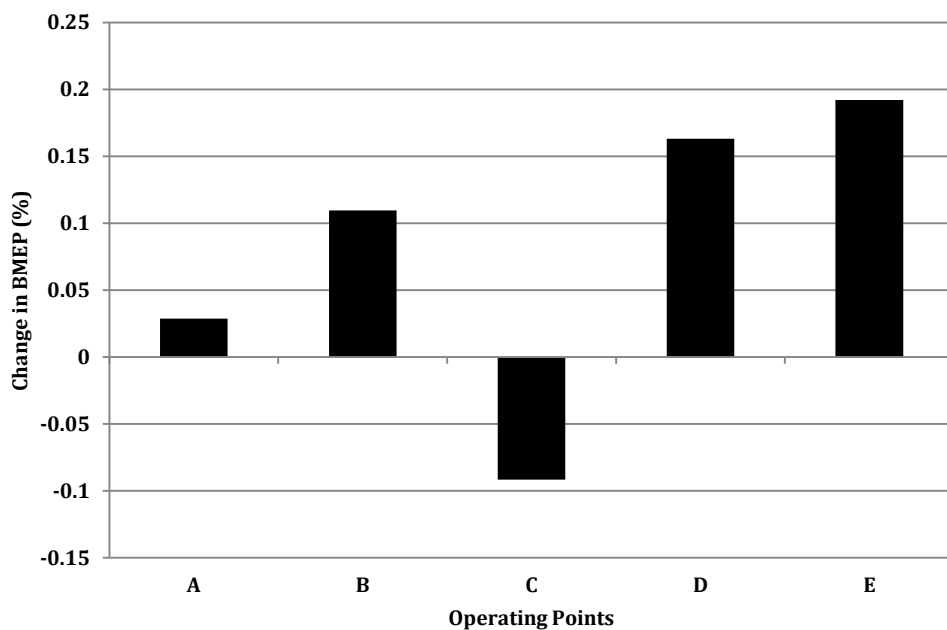


Figure 4-12 Change in BMEP of the ExDEP model over the base model

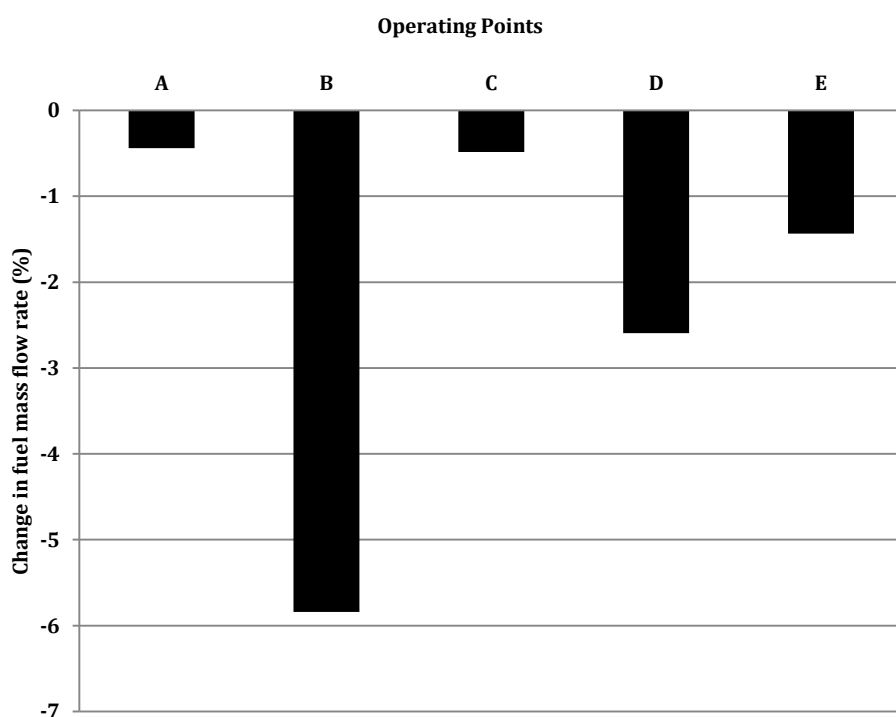


Figure 4-13 Decreased fuel mass flow rate of the ExDEP model over the base model

4.2.4 Cylinder pressures

It is observed that peak cylinder pressures are reduced in the ExDEP model at four out of five operating points, as in Figure 4-14. This decrease is due to the reduced flow to the HP turbine and consequent reduced boost pressures. Some of this lost boost can be recovered by resizing the compressor.

The reduced cylinder pressure could enable the engine to be run at higher compression ratios and consequently increase output. It also implies a longer engine life since the stress on engine components is reduced.

The reduction in peak cylinder pressures results in a reduced pressure differential across the exhaust valves at low engine speeds, as in Figure 4-15. This enables the cylinder to empty better and reduces the duration of choked flow (Mach number =1) through the exhaust valve. This point is illustrated for the operating point B in Figure 4-16.

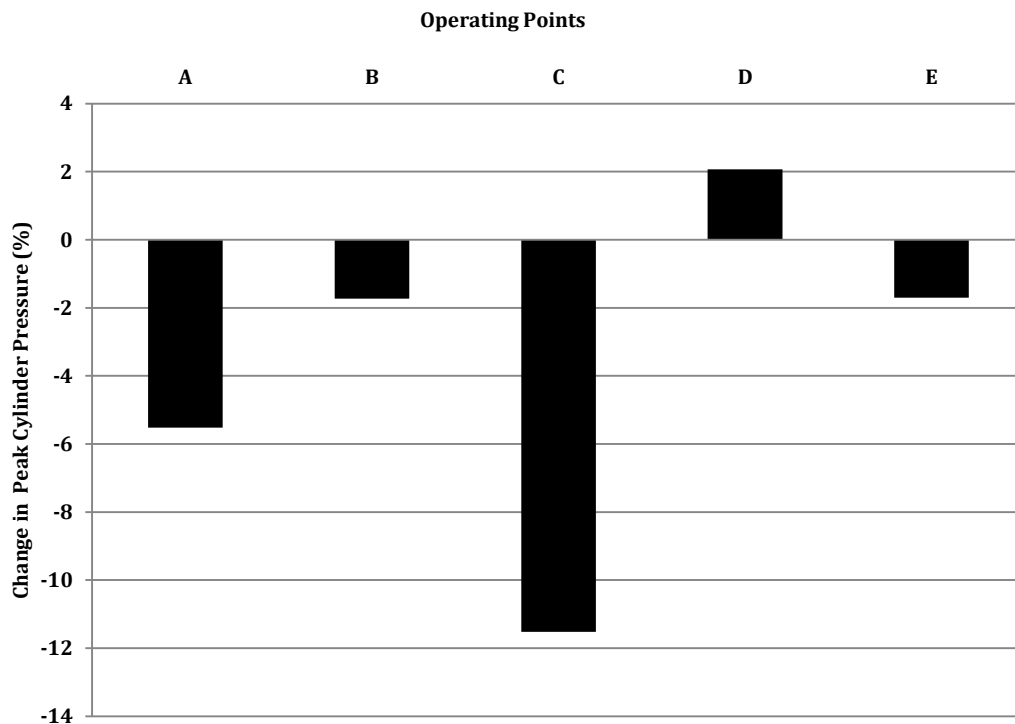


Figure 4-14 Change in peak cylinder pressures with ExDEP

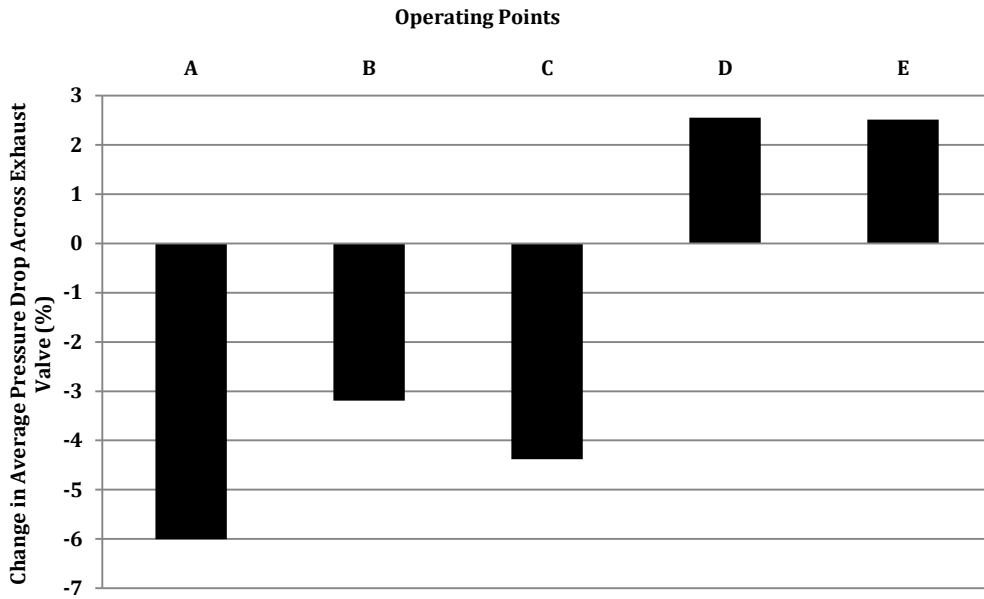


Figure 4-15 Change in average pressure drop across exhaust valves with ExDEP

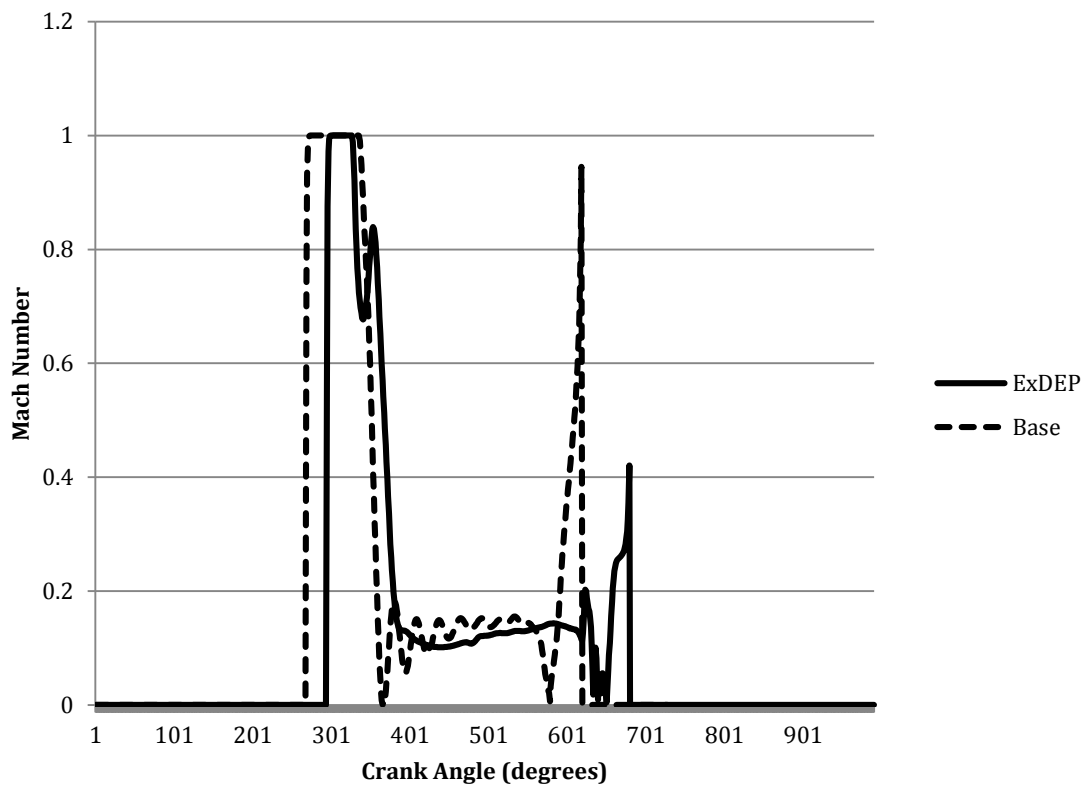


Figure 4-16 Variation of Mach number at exhaust port

5 Conclusions

The modelling and simulation carried out as a part of this project provide conclusions that ExDEP benefits the studied turbocompound engine at the studied operating points. The major gain, obtained at lower load and speed ranges, is from added power at the turbocompound shaft. This gain must be verified through further work.

Routing exhaust flow at higher pressure directly to the LP turbine of the present architecture causes a reduction in flow to the HP turbine. This results in reduced boost and hence less cylinder output. Prior work [3] has avoided this issue by providing constant boost using a compressor driven directly off the crankshaft. However, preserving system architecture and parameters to the largest extent possible implies that such modifications are not possible in this project. Yet the current ExDEP architecture suggested requires modifications to the cylinder head and exhaust manifolds, and selection of suitably sized turbines.

The cam-less valve system used in this model allows valve timing to be varied continuously during transient operation of the engine. However, the studied operating points reveal that not much variability is necessary. A full transient simulation with varying valve lifts and durations will provide a better understanding of whether such a system can be replaced by a simpler actuation mechanism.

The system provides overall benefits over a conventional turbocompound engine while avoiding the drawbacks of DEP, i.e.: reduced flow area at exhaust valves and highly choked flow at high engine speeds which greatly impedes cylinder emptying. However, the currently implemented system causes a larger pumping loss due to increased exhaust back pressure caused by routing flow at higher pressure to the LP turbine. This is offset by the gains in power obtained from the turbocompound shaft. An overall improvement in fuel consumption is a consequence of conservation of the high pressure in the exhaust and better utilisation of both turbines through rescaling.

6 Future work

Transient operation

Though the implemented ExDEP architecture shows benefits at the five studied operating points, an increase in resolution and transient engine simulations could provide a better understanding of the real-world operation of this system.

Refinement of valve profiles

The ExDEP valve profiles used in this project are idealised for simplicity. However, actual data of fast-acting valves can be utilised together with scripting to refine and automate the simulation and obtain more realistic results.

Exhaust gas recirculation

Discussions with engineers at Volvo GTT showed that the ExDEP model carried sufficient exhaust pressure to drive the EGR circuit.

Emission benefits

A cursory glance at simulation results showed promising reduction in NO_x, Hydrocarbon and CO₂ emissions. However, this was not the primary objective of this project, and can be analysed in greater detail.

Variable geometry turbine

Investigation of running a fixed geometry turbine (lower cost) using ExDEP valves to vary the flow instead.

Exhaust valve timing

During this project, the timing of the exhaust valves was retained as in the base model. The effect of varying this timing along with ExDEP could reveal further benefits.

Engine braking

Though the base model used for this project was equipped with a cam-driven engine brake, the use of ExDEP valves for engine braking can be investigated.

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