

AN M DWARF COMPANION TO AN F-TYPE STAR IN A YOUNG MAIN-SEQUENCE BINARY

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Abstract

Only a few well characterized very low-mass M dwarfs are known today. Our understanding of M dwarfs is vital as these are the most common stars in our solar neighborhood. We aim to characterize the properties of a rare F+dM stellar system for a better understanding of the low-mass end of the Hertzsprung-Russel diagram. We used photometric light curves and radial velocity follow-up measurements to study the binary. Spectroscopic analysis was used in combination with isochrone fitting to characterize the primary star. The primary star is an early F-type main-sequence star with a mass of $(1.493 \pm 0.073) M_{\odot}$ and a radius of $(1.474 \pm 0.040) R_{\odot}$. The companion is an M dwarf with a mass of $(0.188 \pm 0.014) M_{\odot}$ and a radius of $(0.234 \pm 0.009) R_{\odot}$. The orbital period is $(1.35121 \pm 0.00001)d$. The secondary star is among the lowest-mass M dwarfs known to date. The binary has not reached a 1:1 spin-orbit synchronization. This indicates a young main-sequence binary with an age below ~ 250 Myrs. The mass-radius relation of both components are in agreement with this finding.

Subject headings: binaries: eclipsing, binaries: close, stars: low-mass, stars: evolution

1. INTRODUCTION

Understanding stellar evolution requires a knowledge, to high precision, of the fundamental parameters of stars in different stages of their evolution. The study of detached eclipsing binaries offers us a unique method of determining the bulk parameters of stars and to compare these measurements to the predictions from stellar models. Stellar models succeed in predicting the mass-radius relation to an accuracy of a few percent for main-sequence stars with $M_{\odot} < M_{\star} < 5 \cdot M_{\odot}$ (e.g. Andersen 1991). Systematic discrepancies between model and observation in the mass-radius relation for a given age have been associated with the amount of convective core overshoot by Clausen et al. (2010), but these are below 1%. Low-mass stars with $M_{\star} < M_{\odot}$ are the most common stars in the solar neighborhood, but only a very limited number of these are well-characterized (Torres 2013). For these stars, stellar models also show systematic discrepancies in the observed mass-radius relations, but on a larger scale. Over 30 eclipsing very low-mass stars (VLMSs) with masses below $0.3M_{\odot}$ and radii known to better than 10% have been observed so far (e.g. Parsons et al. 2012; Pyrzas et al. 2012; Nefs et al. 2013; Gómez Maqueo Chew et al. 2014; Zhou et al. 2014; Kraus et al. 2015; David et al. 2016). However, only eight have radii known to a precision better than 2%. Additionally, a few VLMSs have been characterized by inter-

ferometric observations (Lane et al. 2001; Ségransan et al. 2003; Berger et al. 2006; van Belle & von Braun 2009; Demory et al. 2009; Boyajian et al. 2012) with accuracies up to a few percent.

When evaluating detached eclipsing binaries (DEBs) and single star observations, the highest discrepancies between models and observations have been found for stars with masses between $0.3M_{\odot} < M_{\star} < 1M_{\odot}$ which are not fully convective (e.g. López-Morales 2007; Ribas 2006; Boyajian et al. 2015). For VLMSs with masses below $0.3M_{\odot}$, which have a fully convective interior, current models seem to systematically underestimate the radii by up to 5% percent compared to observations of detached binaries (e.g. Torres et al. 2010; Boyajian et al. 2012; Spada et al. 2013; Mann et al. 2015). Interferometric radius determinations of single VLMSs show even larger discrepancies to the models for some stars (Boyajian et al. 2012; Spada et al. 2013), but in general agree with the above findings. Currently there is no satisfying explanation for the discrepancy between models and observed radius estimates. Mann et al. (2015) characterized a large set of low-mass stars using spectrometric observations. They found similar discrepancies to the stellar similar to what was seen in the sample of characterized DEBs. Using data from over 180 stars they confirmed that stellar models tend to underestimate stellar radii by $\sim 5\%$ and overestimate effective temperatures by $\sim 2.2\%$. Although a large influence of metallicity on the $R_{\star} - T_{eff}$ correlation was found, neither this correlation nor any other could explain the observed discrepancies to current stellar models.

All state-of-the-art stellar evolution models (e.g. Baraffe et al. 1998; Dotter et al. 2008; Bressan et al. 2012) give comparable mass-radius relations for stars with masses below $0.7M_{\odot}$ and older than a few hundred Myrs. The differences among various stellar evolution models are well below a few percent.

On the other hand, for young main-sequence VLMSs with ages well below 250 Myrs, the differences between the models are much larger. Older low-mass stars require a precision better than 2% in the bulk parameters in order to test stellar evolution models (Torres 2013), but with young systems it is suf-

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ficient to characterize these with a much lower precision. This makes young main-sequence objects ideal for testing stellar evolution models. Unfortunately the number of known young main-sequence low-mass stars is very limited. Recently two such young systems with ages below ~ 10 Myrs have been characterized (Kraus et al. 2015; David et al. 2016).

Ages of main-sequence stars are estimated by different methods. Besides using stellar evolution models which correlate basic observables (e.g. mass, radius, luminosity, and temperature) with the age of the star, gyrochronology allows one to correlate the rotational period and color index with the stellar age of cool stars (e.g. Barnes 2010). For close binaries this method is limited by dynamical interactions that might have influenced the rotational period of the stars. For stars with uninterrupted high precision photometric observations we can use asteroseismology to determine the age of a star (e.g. Aerts et al. 2010). The accuracy of the age determination with gyrochronology is $\sim 10\%$ (Delorme et al. 2011). The ages determined with different stellar model can deviate by $\sim 10\%$ for young stars and from 50% up to 100% for older stars (Lebreton et al. 2014a). Only asteroseismology in combination with stellar evolution models can provide the age of main-sequence stars with an accuracy better than 10% (Lebreton et al. 2014b). If the observed system is a cluster member, the age of the star can also be inferred from the age of the cluster. For close binary stars whose orbits are not yet synchronized, the upper limit of the age of the system might also be given by the time scale of synchronization (e.g. Drake et al. 1998).

We present a possibly young F+dM SB1 binary system with a short orbital period and a low eccentricity. We characterize the system and both components using photometric and spectroscopic data. To characterize the primary star we use spectral analysis and compare the results to stellar evolution models. We model the light curve of the primary eclipse and in combination with the radial velocity measurements determine the mass-radius relation of the low mass companion. This enables us to estimate an upper limit for the age of the unsynchronized system.

2. OBSERVATIONS

2.1. Photometric Observations

Photometric observations were taken during surveys for transiting planets with the *Berlin Exoplanet Search Telescope* (BEST; Rauer et al. 2004) and the *Tautenburg Exoplanet Search Telescope* (TEST; Eigmüller & Eislöffel 2009). With both telescopes the same circumpolar field close to the galactic plane was observed for several years. Technical details on the surveys are given in Table 1. For both surveys typically between a few tens of thousands up to a hundred thousand stars have been observed simultaneously within the field of view. In Table 2 the observing hours per year for this field are listed.

The eclipsing binary presented in our work was detected in both surveys (Voss 2006; Eigmüller 2012) as planetary candidate. The object was published as an uncharacterized Algol type binary in Pasternacki et al. (2011) with the identifier BEST F2_06375 after its planetary status was excluded. First estimates of the mass-radius relation gave hints on a possibly inflated very low mass star, which led to further follow-up observations.

The observations with the BEST were taken between 2001 and 2006, with a relocation of the BEST in 2003/2004 from

TABLE 1
TECHNICAL PARAMETERS OF THE BEST AND TEST SURVEYS.

	BEST Survey	TEST Survey
Site	TLS (2001 - 2003) OHP (2005-2006)	TLS
Aperture	200 mm	300 mm
Camera	AP 10	AP16E
Focal ratio	f/2.7	f/3.2
Pixel scale	5.5 arcsec/pixel	1.9 arcsec/pixel
Field of view	$3.1^\circ \times 3.1^\circ$	$2.2^\circ \times 2.2^\circ$
Readout Time	$\sim 90s$	$\sim 30s$
Exposure Time	240s	120s
No. of frames on target	800	6000

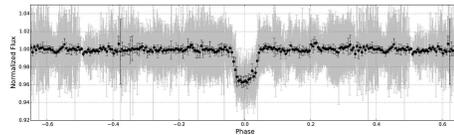


FIG. 1.— The phase-folded light curve. Black points denote data binned to 10 minutes in phase, while the gray points show the original data. Vertical lines show the uncertainties for single measurements.

TABLE 2
LIST OF THE PHOTOMETRIC OBSERVATIONS OF THE ECLIPSING BINARY. FOR EACH TELESCOPE THE YEAR, THE NUMBER OF OBSERVING NIGHTS, AND THE OBSERVING HOURS PER YEAR ARE GIVEN.

BEST			TEST		
Year	Nights [#]	Observing hours	Year	Nights [#]	Observing hours
2001	3	3.8	2008	7	18.7
2002	10	18.6	2009	31	95.9
2005	4	10.0	2010	3	6.3
2006	6	11.0	2011	34	88.1

the Thüringer Landessternwarte Tautenburg (TLS) in mid-Germany to the Observatoire de Haute Provence (OHP) in southern France. The survey with the TEST was carried out between 2008 and 2011 at TLS. Over 250 hours of photometric data were gathered between 2001 and 2011 in nearly 100 nights with these two surveys (cf. Table 2). The standard deviation of the unbinned light curve is typically better than 10 mmag.

The data gathered with both telescopes were reduced and analyzed with the pipelines designed for the respective instruments. The pipeline used for the TEST data is described in Eigmüller & Eislöffel (2009). The methods used to analyze the BEST data set have been applied to various published BEST data sets (e.g. Fruth et al. 2012, 2013; Klagyivik et al. 2013). The data reduction included standard bias and dark subtraction as well as a flat field correction. The detrending for both data sets was done using the *sysrem* algorithm (Tamuz et al. 2005). Effects present in only a few thousands of stars have been corrected. A detrending of the individual light curves was not performed.

For our study we combined both data sets giving us a light curve with over 6800 data points (TEST: ~ 6000 , BEST: ~ 800). For the phase folded light curve we measure a standard deviation below 2 mmag in the out-of-transit region using values binned by up 10 minutes. The whole phase folded light curve is shown in Figure 1.

2.2. Spectroscopic Observations

TABLE 3
CATALOG INFORMATION OF THE ECLIPSING BINARY INVESTIGATED HERE. VMAG AS GIVEN IN UCAC4 CATALOG (ZACHARIAS ET AL. 2013).

Parameter	Value
Position	02 ^h 40 ^m 51.5 ^s + 52 ^d 45 ^m 07 ^s
UCAC4 ID ^a	UCAC4 714-021661
2MASS ID ^b	02405152+5245066
Bmag (UCAC4)	12.287 ± 0.02
Vmag (UCAC4)	11.769 ± 0.02
Jmag (2MASS)	10.771 ± 0.028
Hmag (2MASS)	10.618 ± 0.032
Kmag (2MASS)	10.564 ± 0.026
pmRA (UCAC4)	-1.7 ± 0.8 mas/yr
pmDE (UCAC4)	-5.6 ± 1.0 mas/yr

^a Zacharias et al. (2013)

^b Skrutskie et al. (2006)

Spectroscopic follow-up observations were performed with the Tautenburg 2-m telescope using the Coudé-Echelle spectrograph with an entrance slit that projected to 2'' on the sky. The observed wavelength range covered 4700Å and 7400Å with a resolving power ($\lambda/\Delta\lambda$) of 32,000. For the wavelength calibration, spectra of a Thorium-Argon lamp were taken directly before and after the observations. Stellar spectra were taken with exposure times of 1800 seconds which resulted in a typical S/N of 20-35. In 2010 a few spectra of the binary system were taken between January and September to get an initial characterization of the transiting system. In November/December 2012 additional spectra were obtained primarily for radial velocity (RV) measurements needed to constrain the orbital motion. For the data reduction, standard tools from IRAF were used including bias subtraction, flat-field correction, and wavelength calibration. The RV was determined using the IRAF *rv* module.

3. SYSTEM PARAMETERS

The catalog information of the system is given in Table 3.

3.1. Modeling of the Photometric and Radial Velocity data

A simultaneous fit of the radial velocity and photometric data was performed. The out-of-eclipse part of the light curve did not show any sign of ellipsoidal variation at the level of precision of our observations (Figure 1). Therefore we decided to use the spherical model of Mandel & Agol (2002) for the light curve modeling. The expected signal of the secondary transit would have an amplitude of ~0.1 mmag which would be undetected given our red noise error of 2 mmag. To optimize the fit, we used a genetic algorithm (Geem et al. 2001) to search for the best match between the observed and the modeled light curve. One thousand individuals were used in the population and 300 generations were produced. The best fit found by this procedure was further refined using a simulated annealing chain (Kallrath & Milone 2009). The error was estimated using 10^4 random models with values within $\chi^2 + 1\sigma$ of our best solution. Figure 2 shows 1σ error bars (for details of the code and implementation of the algorithms see Csizmadia et al. 2011). For the light curve modeling we used the unbinned data. The effect of the exposure time was taken into account by using a 4-point Simpson-integration (e.g. Kipping 2010).

Free parameters were the scaled semi-major axis ratio a/R_s , the inclination i , the radius ratio of the two stars R_2/R_1 , the epoch, the period, the γ -velocity, the semi amplitude

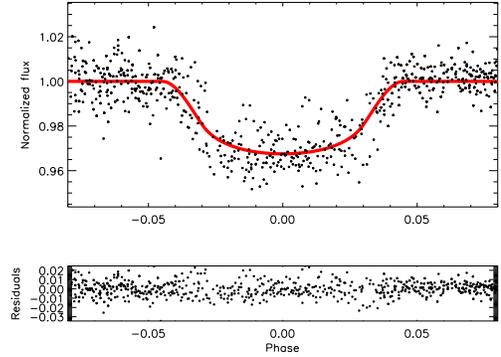


FIG. 2.— The phase-folded light curve of the eclipse. Black points denote single measurements, while the red line shows the best fit.

TABLE 4
MODELING PARAMETERS. THE GIVEN ERRORS CORRESPOND TO THE 1σ UNCERTAINTIES. a/R_1 ; THE IMPACT PARAMETER b (b WAS CALCULATED VIA $b = \frac{a(1-e^2)}{1+e\cos\omega} * \sqrt{1 - \sin^2 i \cdot \sin^2 v_0}$ WHERE $v_0 = 90^\circ - \omega + \theta$ THE MEAN ANOMALY AT THE MID-TRANSIT MOMENT, SEE GIMENEZ & GARCIA-PELAYO (1983)); THE INCLINATION i OF THE SYSTEM; THE RADIUS RATIO R_2/R_1 ; THE LIMB DARKENING COEFFICIENTS u^+ AND u^- ; THE ECCENTRICITY e OF THE SYSTEM; THE PERIOD P ; THE EPOCH OF THE SYSTEM AND THE RADIAL VELOCITY SEMI AMPLITUDE K .

Parameter	Value
a/R_1	4.12 ± 0.06
b	0.45 ± 0.03
i	84.1° ± 0.3°
R_2/R_1	0.1601 ± 0.0017
u^+	1.05 ± 0.07
u^-	-0.02 (fixed)
e	0.070 ± 0.063
ω	227° ± 13°
P	1.35121d ± 1·10 ⁻⁵ d
Epoch	2452196.1196 ± 0.0032 HJD
γ - velocity	(30.50 ± 0.50) km/s
K	(26.10 ± 0.76) km/s

of the radial velocity K , the eccentricity e , the argument of periastron ω , and the combination $u_+ = u_a + u_b$, where u_a and u_b are the linear and the quadratic limb darkening coefficients of the quadratic limb darkening law. The parameter $u_- = u_a - u_b$ was fixed at the value found by interpolation of the R-band values of Claret & Bloemen (2011). When we performed a fit using free limb darkening combinations as a check, we got $u_- = +0.08 \pm 0.17$, compatible with the previous theoretical value. The other parameters were also within the error bars. The results of the fit are presented in Table 4. Figure 2 shows the phase-folded light curve over-plotted by the fit along with the residuals. Although the noise in single photometric measurements is large, the combined data allow us to reach a precision of ~2 mmag in 10 minute bins in the phase folded light curve. The radial velocity data with the best fit are shown in Figure 3.

3.2. Stellar Parameters

To determine the atmospheric parameters of the primary component we created a high quality spectrum by adding all the single observations after applying an RV shift to account for the orbital motion. This resulted in a co-added spectrum with S/N over 90. The analysis was performed over the wavelength range 4740Å to 6400Å. using the GSSP pro-

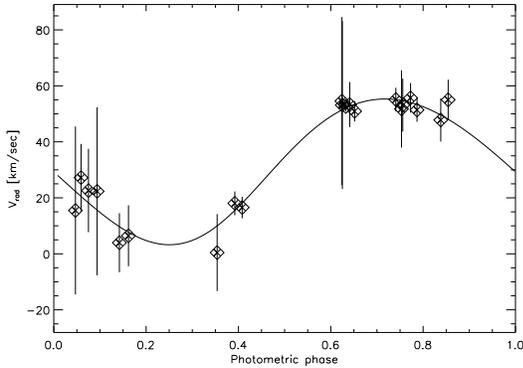


FIG. 3.— Radial velocity measurements of the system. The best fit gives a γ -velocity of (30.5 ± 0.5) km/s and a semi-amplitude of $K = (26.1 \pm 0.8)$ km/s.

gram (Grid search in Stellar Parameters; Lehmann et al. 2011; Tkachenko et al. 2012).

The normalization of the observed spectra during the reduction is difficult and the results strongly depend on the accuracy of the derived local continuum. We used the comparison of the co-added spectrum with the synthetic ones for an additional continuum correction. The analysis was done in three ways: a) without any correction, b) by multiplying the observed spectrum by a factor calculated from a least squares fit between observed and synthetic spectrum, and c) with a re-normalization applied on smaller scales to get a better fit to the wings of the Balmer lines (mainly $H\beta$) and with regions excluded for which the analysis showed distinct deviations of the continuum from the calculated continua. Most of the atmospheric parameters obtained with the three different approaches agreed to within 1σ . However, approach c) gave a significantly higher value of the effective temperature, $T_{eff} = 7350 \pm 80$ K, which differed by almost 2σ from the results of the other two methods. This demonstrates the sensitivity of T_{eff} caused by small changes in the $H\beta$ wings.

The parameters T_{eff} , $\log g$, v_{urb} , $[Fe/H]$, and $v \sin(i)$ and their errors were derived using a grid. Thus, the errors include all interdependencies between the parameters. All other metal abundances and their errors were determined separately, fixing all atmospheric parameters to their best fitting values. The formal 1σ error on T_{eff} (80 K) based on error statistics is probably too small due to systematic errors stemming from the continuum normalization. We use a larger error that includes the systematic error introduced by this normalization.

As determining the stellar parameters is crucial and a possible source of systematic errors in the characterization of the companion, the results have been verified using another method described in Fridlund et al. (2010). Stellar parameters of both methods are in agreement with each other. Only for T_{eff} we found a larger uncertainty of ± 200 K. This error agrees with our previous finding that the normalization of the spectrum can result in an underestimate in the error of the effective temperature and thus the spectral classification. In Table 5 the results for the different approaches are given. For the estimates of mass and radius of the primary star we used the results from the GSSP approach with the small-scale re-normalization (c). For the error estimate of T_{eff} we used 250 K which corresponds to $\sim 3\sigma$ uncertainty in approach (c).

For the primary star we found an effective temperature $T_{eff} = (7350 \text{ K} \pm 250)$ K, a surface gravity of $\log g = (4.16 \pm 0.39)$ cgs, and a metallicity of $[Fe/H] = (-0.05 \pm 0.17)$ dex.

TABLE 5
RESULTS OF STELLAR ANALYSIS WITH THE GSSP PROGRAM AND THE METHOD DESCRIBE IN FRIDLUND ET AL. (2010). FOR THE FORMER ANALYSIS THREE DIFFERENT NORMALIZATIONS OF THE SPECTRUM WERE TESTED: A) WITHOUT ANY CORRECTION, B) BY MULTIPLYING THE OBSERVED SPECTRUM BY A FACTOR CALCULATED FROM A LEAST SQUARES FIT BETWEEN OBSERVED AND SYNTHETIC SPECTRUM, AND C) WITH A RE-NORMALIZATION APPLIED ON SMALLER SCALES.

Parameter	GSSP			Method 2
Parameter	a)	b)	c)	
T_{eff} / K	7150 ± 80	7130 ± 80	7350 ± 80	7300 ± 200
$[Fe/H] / \text{dex}$	-0.02 ± 0.15	-0.2 ± 0.2	-0.15 ± 0.17	0.0 ± 0.2
$\log g / \text{cgs}$	3.98 ± 0.38	3.96 ± 0.34	4.16 ± 0.39	4.1 ± 0.3
$v \sin(i) / \text{km/s}$	127 ± 9	126 ± 10	130 ± 10	125 ± 10

TABLE 6
BULK PARAMETERS FOR BOTH STARS. T_{eff} , Fe/H , AND $\log g$ WERE DETERMINED USING A GRID SEARCH. FOR THE PARAMETERS DERIVED FROM SPECTRAL ANALYSIS THE 1σ ERROR IS GIVEN. FOR T_{eff} A 3σ ERROR IS LISTED. MASSES AND RADII INCLUDING THEIR ERRORS, WERE DETERMINED USING THE ACCORDING ISOCRONES, THE RESULTS FROM LIGHT CURVE MODELING, AND THE FITTED RADIAL VELOCITY MEASUREMENTS.

Parameter	Value
T_{eff} / K	7350 ± 250
$[Fe/H] / \text{dex}$	-0.05 ± 0.17
$\log g / \text{cgs}$	4.16 ± 0.39
$v_{urb} / \text{km/s}$	$1.74^{+0.62}_{-0.41}$
$v \sin(i) / \text{km/s}$	130 ± 10
M_1 / M_{\odot}	1.493 ± 0.073
R_1 / R_{\odot}	1.474 ± 0.040
M_2 / M_{\odot}	0.188 ± 0.014
R_2 / R_{\odot}	0.234 ± 0.009

The mass of the primary star M_1 was derived using PARSEC1.2S isochrones (Bressan et al. 2012; Chen et al. 2014; Tang et al. 2014; Chen et al. 2015) in combination with the stellar parameters and 2MASS color information (Cutri et al. 2003). The radius of the primary is given by its mass and surface gravity. From the mass function $f(m)$ we derived the mass of the secondary object as $M_2 = (0.188 \pm 0.014)M_{\odot}$. The radius of the secondary was calculated using the radius of the primary and the ratio R_2/R_1 that comes from the light curve modeling $R_2 = (0.234 \pm 0.009)R_{\odot}$. The resulting system mass ($M_1 + M_2$), radius of the primary (R_1), semi major axis a/R_1 , and orbital period were tested for satisfying Kepler's third law.

We compared our results using the PARSEC1.2S model with those using the Y2 stellar models (Yi et al. 2001; Demarque et al. 2004) and the Dartmouth model (Dotter et al. 2008). All three models are in agreement and give us the similar results (within 1σ) for the mass and radius of the binary components. The Dartmouth model results in binary components that are a bit smaller and less massive, whereas the Y2 model suggests larger and more massive stars.

The atmospheric and bulk parameters of both stars are listed in Table 6.

3.3. Synchronization of the System

In order to assess whether the system is synchronized we computed the synchronization factor comparing the rotational period of the star with the orbital period. If a 1:1 spin-orbit synchronization and alignment has taken place the rotation period of the primary star is equal to the orbital period of the system. We assume the orbital inclination to be nearly the same as the rotational inclination. The rotational velocity

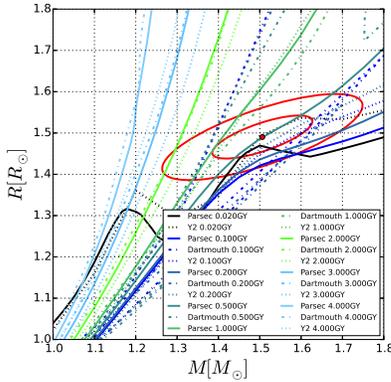


FIG. 4.— Parsec1.2S isochrones for different ages are plotted with continuous lines. Y2 isochrones are plotted with dotted lines. The Dartmouth model is plotted with dashed lines. Only isochrones with solar metallicity are displayed. The primary star is shown by the red marker, circles represent 1σ and 2σ error bars.

of the primary star derived from the spectral line broadening is $v_{\text{sin}i} = (130 \pm 10) \text{ km/s}$. We know the inclination of the orbital plane to be $i = 84.1^\circ \pm 0.3^\circ$ from the light curve modeling. With the radius of the primary star and its real rotational velocity $V_{\text{rot}} = \frac{v_{\text{sin}i}}{\sin i}$ we derive the rotational period $P_{\text{rot}} = 2 * \pi * R_1 / V_{\text{rot}} = (0.58 \pm 0.06) \text{ d}$. This gives the synchronization factor of $P_{\text{rot}} / P_{\text{orb}} = 0.43 \pm 0.05$.

The system is clearly not in a 1:1 synchronization, but the rotational period of the primary star and the orbital period are close to a 2:1 commensurability. Even if the orbital inclination would not be the same as the rotational inclination our conclusion would still stand as the synchronization factor would only decrease for smaller inclinations.

Normally, we expect close binary stars to evolve into a 1:1 spin-orbit resonance if the eccentricity is close to 0. As shown by Celletti et al. (2007); Celletti & Chierchia (2008) for examples of the solar system the 2:1 resonances are very unlikely for objects in low eccentricity orbits. Our light curve and radial velocity modeling suggest an eccentricity close to 0. This makes it unlikely for the system to be in a dynamically stable 2:1 resonance. The observed commensurability is likely not to be a stable resonance, but a mere coincidence. As shown in the analysis by Béky et al. (2014), the assumption that every commensurability is due to stable dynamical resonances is implausible.

If the binary is not yet synchronized this can only mean that it is younger than the time scale of synchronization. This time scale for the system, $< t_{\text{sync}} >$, was computed according to Zahn (1977) and Hilditch (2001). Using the stellar models grids by Claret (2004), we determined the radius of gyration and the tidal torque constant of the primary star. For this system the time scale of synchronization lies in the range between 120 Myrs and 250 Myrs. If no third body is preventing the system from synchronization, this system looks younger than 250 Myrs.

For the age of the primary star we get no conclusive result, but Parsec1.2S isochrones suggest ages below 1.4 Gyr. In Figure 4 the mass and radius of the primary star is plotted along with various isochrones.

4. DISCUSSION

The mass-radius relations given by the stellar evolution models of Baraffe et al. (1998) and Bressan et al. (2012), indicate that the low mass companion has an inflated radius.

The empirical mass-radius relations of Mann et al. (2015) and Boyajian et al. (2012) suggests that stellar evolution models systematically underestimate the stellar radius of very low-mass stars by $\sim 5\%$. For VLMSs with masses below $0.3M_\odot$ the data presented in Mann et al. (2015) also shows discrepancy in the mass by $\sim 4\%$ compared to the Dartmouth model. However, Mann et al. (2015) suggest that the model inferred masses are more reliable than the empirically derived ones. It thus is more suited to compare our results with model isochrones that are corrected for the underestimated radius. These corrected isochrones show that the M dwarf is slightly inflated. Such an anomalous radius could be explained by the youth of the star.

Figure 5 shows our M dwarf in relation to other known systems with masses and radii below $0.3M_\odot$ and $0.3R_\odot$, respectively. Crosses represent eclipsing binaries and single stars studied with interferometry. Circles represent spectroscopically characterized VLMSs. The lines show isochrones by Baraffe et al. (1998) with metallicity $[M/H] = 0.0$ of different ages. The dashed lines show the isochrones corrected for a radius underestimated by 5%. The green dashed line shows a polynomial fit of third order to the mass-radius relation for the data presented in Mann et al. (2015). Discrepancies between the empirical data from Mann et al. (2015) and the adjusted isochrones are due to the underestimate in masses for VLMSs. The empirical mass-radius relation for low-mass stars is based on objects typically of several Gyrs in age. Due to the limited number of young VLMSs it is not clear whether stellar models also underestimate the radius by 5% for young stars. Nevertheless, taking into account the underestimate in the radius by the stellar models as it is known for older stars, the mass-radius relation of the M dwarf agrees best with the isochrones for ages between 100 Myrs - 200 Myrs.

Comparison of the stellar parameters for the primary star with isochrones do not allow us to constrain further the age of the system, but our results hint towards a young system. Isochrones from different stellar models all suggest an age below 1 Gyr. Furthermore, the system is not in a 1:1 spin-orbit resonance, which we would expect for such binary system with an eccentricity close to 0.

The stellar rotation of the primary star is close to a 2:1 commensurability with the orbital period. Similar commensurabilities were found in some exoplanetary systems (see Béky et al. 2014) and in the brown dwarf system CoRoT-33 (Csizmadia et al. 2015), but have not yet been reported for binary systems.

It is unlikely that these 2:1 resonant systems of low eccentricities are dynamically stable (Celletti & Chierchia 2008). As pointed out in the study by Béky et al. (2014) there are good reasons to believe that such commensurabilities are a statistical phenomena and not a stable resonance.

We see two possibilities why this system is not tidally locked. Either the system is younger than the time scale of synchronization, which is below 250 Myrs, or a third body is present that perturbs the system. However, we find no evidence for this third body in the photometric or RV data. Long-term high precision RV monitoring, or AO imaging of this star may reveal a third body. At the present time, all the available evidence from the dynamical analysis of the system combined with the mass-radius relationship of both components point to a system that is younger than 250 Myrs.

In contrast to M dwarfs older than 500 Myrs, where the differences between stellar evolution models are small compared to observational errors, isochrones of ages below

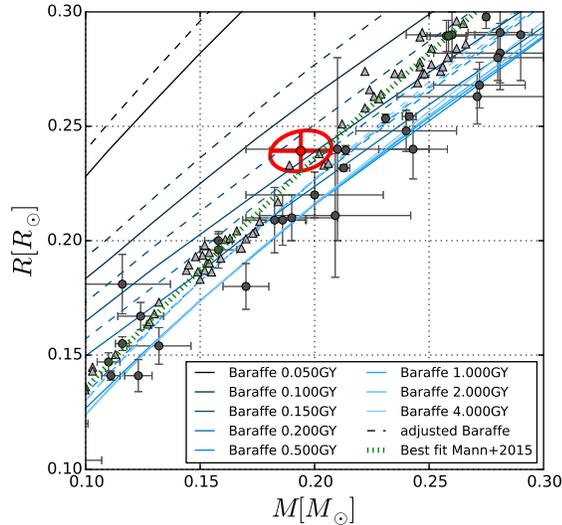


Fig. 5.— Mass radius relation of very low-mass stars. Plotted are stars in eclipsing binaries (gray circles) (Ségransan et al. 2003; Bouchy et al. 2005; Pont et al. 2005; Hebb et al. 2006; Pont et al. 2006; Beatty et al. 2007; Maxted et al. 2007; Blake et al. 2008; Fernandez et al. 2009; Morales et al. 2009; Vida et al. 2009; Dimitrov & Kjurkchieva 2010; Parsons et al. 2010; Hartman et al. 2011; Irwin et al. 2011; Carter et al. 2011; Parsons et al. 2012; Pyrzas et al. 2012; Nefs et al. 2013; Tal-Or et al. 2013; Gómez Maqueo Chew et al. 2014; Zhou et al. 2014) and spectroscopic characterized single low mass stars (gray triangles) (Mann et al. 2015). The best fit to data from Mann et al. (2015) is given by the green dashed line. The data is over plotted with isochrones for different ages. Continuous lines show isochrones by Baraffe et al. (1998) and the dashed lines the same isochrones corrected for a radius underestimation of 5%. In red the characterized M dwarf companion with the according 1σ error is shown.

250 Myrs differ significantly between models. Given the uncertainties in the stellar parameters it is not yet possible to distinguish between different stellar models for this M dwarf. But with the expected age of the system below the time scale of synchronization, which is in agreement with the mass-radius relation of the low mass companion, this system is a unique test object for stellar evolution models. It is one of the youngest studied M dwarfs in an eclipsing binary. Better values of the stellar parameters, particularly the stellar age of the primary star, will allow to test different stellar evolution models. Additionally this system can serve as an interesting test object for rotational evolution of low-mass stars in presence of a close companion and possibly strong stellar wind (c.f. Ferraz-Mello et al. 2015).

5. CONCLUSION

We characterized a detached eclipsing binary system with unequal mass components comprised of a very low-mass M dwarf orbiting an early F-type main-sequence star. The system was investigated combining photometric data and radial velocity measurements. Using stellar evolution models we determined the bulk properties of the primary star. Using different stellar models for the characterization of the primary star did not lead to significant changes in the mass-radius relation of either of the stars.

The orbital period is 1.35121 ± 0.00001 days. The mass of the M dwarf is $M_2 = 0.188 \pm 0.014 M_\odot$. With a radius of $R_2 = 0.234 \pm 0.009 R_\odot$ the M dwarf is slightly inflated even when taking into account that current stellar models underestimate the radii of low-mass stars by $\sim 5\%$.

The low density of the M dwarf star could be explained by an age of the system between 100 Myrs and 250 Myrs. The spectral characterization of the primary star does not allow us to further constrain the age of the system. However, the system has not yet reached the 1:1 spin-orbit resonance, which we would expect for such a close binary with a nearly circular orbit. This supports the conclusion that the age of the system is below 250 Myrs.

The M dwarf thus is one of the youngest characterized main-sequence M dwarfs in an eclipsing binary system. Additionally, it is one of the very few VLMSs which allows us to estimate the age estimate without isochrone fitting. It might play a crucial role in further understanding of the mass-radius relation for young very low mass objects. The system is also of high interest with regard to the dynamical interactions in such close binaries.

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Facility: TLS (2m Coude, TEST)

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