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A 3D/2D Comparison between Heterogeneous Mesoscale Models of Concrete

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Abstract. A model for 3D Statistical Volume Elements (SVEs) of mesoscale concrete is presented and employed in the context of computational homogenization. The model is based on voxelization where the SVE is subdivided into a number of voxels (cubes) which are treated as solid finite elements. The homogenized response is compared between 3D and 2D SVEs to study how the third spatial dimension influence the over-all results. The computational results show that the effective diffusivity of the 3D model is about 1.4 times that of the 2D model.

1 Introduction

Computational homogenization is a well known technique to account for material heterogeneities while keeping computational costs at a moderate level. One benefit of this technique is that it enables to determine bulk properties of a material *a priori* in the case of linear subscale properties. This is beneficial if the macroscopic behaviour of a material is sought and the subscale features is highly complex. In case of non-linear material behaviour the subscale response needs to be determined concurrently during the computations in a nested fashion using a FE²-approach. Furthermore, the technique opens up to "virtual testing" of new materials.

Concrete has a highly heterogeneous and random material structure at multiple length scales. Thus, considerable computational work on the effects of its heterogeneity has been done for this material, see eg. Kim and Al-rub [10], Idiart et al. [9] and Wang and Ueda [13].

However, most computational work reported in the literature deals with 2D models of concrete and any 3D feature that might be of importance is naturally not accounted for in these instances. A natural evolution in the development of computational homogenization is thus to account for all three spatial dimensions to obtain numerical results that potentially better reflect the real material behaviour.

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This paper presents a 3D heterogeneous mesoscale model of concrete and compares computational homogenization between 2D and 3D models to study how the third spatial dimension contributes to the homogenized results. This is done in the context of mass diffusion; thus, the effective diffusivity of concrete is the studied material property in this work.

2 Mesoscale SVE

The concept of Statistical Volume Element (SVE) is fundamental to computational homogenization techniques as it is the foundation on which all computational work is built. The SVE is expected to contain all material heterogeneities in a statistical manner and tends to become an Representative Volume Element (RVE) only when it is sufficiently large, i.e. when the influence of boundary conditions are sufficiently small, see Ostoja-Starzewski [12]. The RVE, in turn, is used to extract the sought macroscopic material properties.

In this work, the mesoscale material constituents are the cement paste matrix, aggregates and Interfacial Transition Zone (ITZ). The aggregates are modelled as spheres with random spatial distribution enfolded by an interface layer of ITZ. The cement paste matrix is considered homogeneous, i.e. cracks are not accounted for.

2.1 Sieve Curve

The aggregates in the SVE can be of arbitrary size and quantity. The volume fraction of aggregates is defined as

$$n_a = \frac{V_a}{V_{\text{SVE}}} \quad n_a \in [0, 1], \quad (1)$$

where V_a is the volume and sub-index 'a' denotes aggregate. The SVE model implementation allows for any realistic n_a to be used as input. Any sieve curve is possible to have as input for the SVE realization and we have the requirement that

$$\sum_{i=0}^N n_{a,i} = n_a, \quad (2)$$

where $n_{a,i}$ denotes the volume fraction of aggregate size i and N denotes the total number of particles sizes included in the specified sieve curve. Both N and $n_{a,i}$ can be chosen freely given that the constraint in Eq. (2) is fulfilled.

2.2 Algorithm for Generating SVEs

The algorithm for generating SVEs is given below as pseudo-code and has been implemented in MATLAB. The algorithm assures that no aggregates

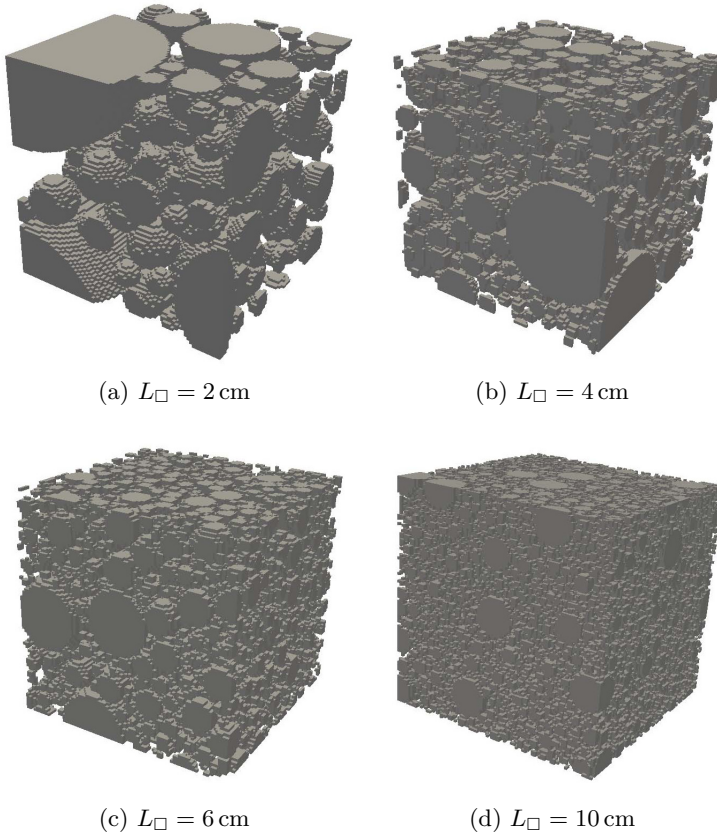


Fig. 1 Example SVEs all having the same sieve curve with $n_a \approx 0.45$. L_{\square} refers to the side length of the SVE.

Algorithm 1 Generating SVE

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1: while the volume fraction of aggregate inside  $\Omega_{\square}^1 < n_a$  do
2:   Generate aggregate from given sieve curve
3:   Place the new aggregate at a random point in  $\Omega_{\square}$ 
4:   if new particle overlap already existing particle then
5:     Remove the new aggregate
6:   end if
7:   add area of the new aggregate to the accumulated aggregate volume
8: end while

```

overlap once the algorithm has completed. In Figure 1, four example SVEs produced by the algorithm are shown.

¹ The SVE domain is denoted Ω_{\square} .

3 FE Discretization of SVE

The spatial discretization technique is based on voxelization to create a structured grid of equally sized voxels. The concept is to subdivide a cubic body into a number of smaller cubes (voxels) which are considered solid finite elements. This approach was used by Bentz et al. [2] and Garboczi [5] in the context of analytical homogenization of heterogeneous concrete and later adapted by Hain and Wriggers [6, 7] for elasticity problems and computational homogenization. Other discretization approaches for 3D domains have been devised in the literature: both Caballero et al. [4] and Asahina and Bolander [1] used Voronoi tessellation where the aggregates were based on a polyhedron representation to generate 3D SVEs.

Material properties of the finite elements are determined by looping over all elements and for each element measure its distance to the center of all aggregates (spheres). If the distance is greater than the radius of any of the aggregates then the element is located in the cement paste matrix and can be assigned its proper material property. If the distance is smaller than the radius then the element sits inside an aggregate.

4 ITZ Implementation

Experimental results by Hedenblad [8] indicate that the effective, or volume average, diffusivity of concrete slightly increase with increasing aggregate content, alternatively remains unchanged. This fact implies that the ITZ has a non-negligible effect on the diffusivity of concrete.

As the SVEs are discretized into a structured grid, a certain number of voxels end up right at the interface between the cement paste matrix and aggregate, see Figure 2.

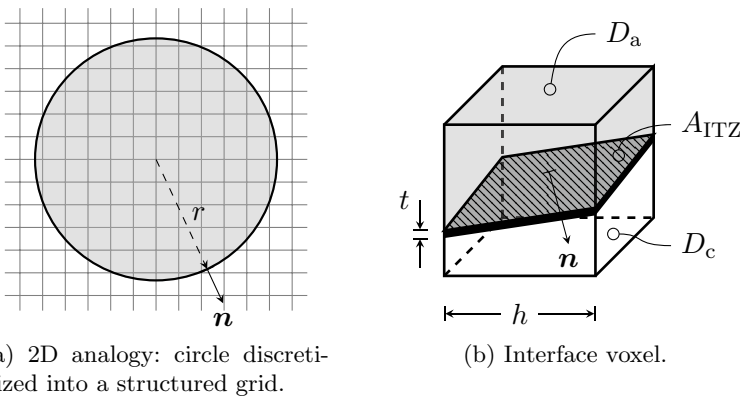


Fig. 2 Interface voxel (right) containing all three mesoscale constituents located at the surface of an aggregate (left)

Consequently, these interface voxels will contain all three mesoscale materials; cement paste, aggregate and ITZ. For these voxels, we employ an anisotropic Voigt assumption on the over-all diffusivity, expressed as

$$\bar{D} = \frac{V_a D_a + V_c D_c}{V_a + V_c} \mathbf{I} + \frac{A_{\text{ITZ}} D_{\text{ITZ}} t}{V_a + V_c} (\mathbf{I} - \mathbf{n} \otimes \mathbf{n}), \quad (3)$$

where D_\bullet , are material diffusivities¹. Generally, we have that $D_a \ll D_c \ll D_{\text{ITZ}}$ and for this work we assume that $D_a = 0 \text{ cm}^2/\text{s}$ and we set $D_c = 1 \text{ cm}^2/\text{s}$. The unknown parameters in Eq. (3) are the thickness, t , and diffusivity, D_{ITZ} , of the ITZ. Computationally, it is the product of these two, $D_{\text{ITZ}} \times t$, that become the model parameter.

There are several ways in which the aggregate interface surface, A_{ITZ} , can cut through the voxel and the intersection points between the surface and the line segments of the voxel can range from 3 to 6. The gray and white aggregate and cement paste volumes in Figure 2b become convex hulls, see Berg et al. [3], spanned by these intersection points and corner nodes, and are computed by utilizing this geometrical property. The interface area, A_{ITZ} , is determined in a similar fashion.

5 First Order Homogenization

We wish to determine the difference between 3D and 2D SVEs in terms of homogenized response. This is done by starting from the fully resolved, stationary, boundary value problem

$$\nabla \cdot \mathbf{J} = 0 \quad \forall \mathbf{x} \in \Omega, \quad (4)$$

for which all material heterogeneities are embedded in $\Omega \subset \mathbb{R}^3$. Here, ∇ is the nabla operator and $\mathbf{J}(\mathbf{x})$ is the flux of some generic physical quantity. The corresponding weak form reads

$$\int_{\Omega} \nabla \delta \phi \cdot \mathbf{J} = \int_{\Gamma_N} \delta \phi \mathbf{J} \, d\Gamma, \quad (5)$$

for suitable test function $\delta \phi$ that is sufficiently regular.

Homogenization implies that the integrands of the volume integrals in Eq. (5) are replaced by space-averages on RVEs, i.e.

$$\int_{\Omega} \nabla \delta \phi \cdot \mathbf{J} \, d\Omega \longrightarrow \int_{\Omega} \langle \nabla \delta \phi \cdot \mathbf{J} \rangle_{\square} \, d\Omega, \quad (6)$$

where $\langle \bullet \rangle_{\square}$ denotes the volume average

$$\langle \bullet \rangle_{\square} \stackrel{\text{def}}{=} \frac{1}{|\Omega_{\square}|} \int_{\Omega_{\square}} \bullet \, d\Omega_{\square}, \quad (7)$$

¹ "a" = aggregate, "c" cement paste

on the RVE that occupies the domain Ω_\square centered at the macroscale position $\bar{\mathbf{x}} \in \Omega$; hence, $\langle \mathbf{x} - \bar{\mathbf{x}} \rangle_\square = 0$.

We assume first order homogenization defined by the split of a scalar field ϕ within Ω_\square into the macroscale and fluctuation parts² as follows:

$$\phi(\mathbf{x}; \bar{\mathbf{x}}) = \phi^M(\mathbf{x}; \bar{\mathbf{x}}) + \phi^s(\mathbf{x}). \quad (8)$$

The macroscale part varies linearly as

$$\phi^M(\mathbf{x}; \bar{\mathbf{x}}) = \bar{\phi}(\bar{\mathbf{x}}) + \bar{\mathbf{g}}_\phi(\bar{\mathbf{x}}) \cdot [\mathbf{x} - \bar{\mathbf{x}}] \quad \forall \mathbf{x} \in \Omega_\square, \quad (9)$$

with $\bar{\mathbf{g}} \stackrel{\text{def}}{=} \nabla \bar{\phi}$. Hence, we obtain $\nabla \phi^M(\bar{\mathbf{x}}; \bar{\mathbf{x}}) = \bar{\mathbf{g}}(\bar{\mathbf{x}})$ constant within Ω_\square . We then obtain for any macroscale point $\bar{\mathbf{x}} \in \Omega$ the identity

$$\langle \nabla \delta \phi \cdot \mathbf{J} \rangle_\square = \delta \bar{\mathbf{g}} \cdot \bar{\mathbf{J}} \quad \text{with} \quad \bar{\mathbf{J}}_\phi = \langle \mathbf{J} \rangle_\square. \quad (10)$$

In order to compute the homogenized flux quantity $\bar{\mathbf{J}}$, it is necessary to compute the fluctuation field ϕ^s as well as the spatial gradient on the subscale: $\mathbf{g}^s \stackrel{\text{def}}{=} \nabla \phi^s$. This is done on each RVE with given prolongation conditions. Here, we choose Dirichlet boundary conditions, i. e. $\phi^s = 0$ on Γ_\square , whereby the pertinent RVE-problem becomes: For given values of the macroscale variables $\bar{\phi}$ and $\bar{\mathbf{g}}$, compute the subscale field ϕ^s that satisfy the system

$$\langle \nabla(\delta \phi^s) \cdot \mathbf{J} \rangle_\square = 0, \quad (11)$$

for all possible $\delta \phi^s$ that are sufficiently regular and which vanish on Γ_\square . We note that the macroscale prolongations ϕ^M are completely defined (varies linearly) on Ω_\square .

Our objective is to determine the mapping

$$L_\square \mapsto \langle \mathbf{J} \rangle_\square(L_\square) \quad (12)$$

and to study how this mapping differs between 3D and 2D SVEs of mesoscale concrete models. This is done by solving Eq. (12) given a macroscale gradient $\bar{\mathbf{g}} = [-1 \ 0 \ 0]^T$ for SVEs of varying L_\square .

6 2D SVEs

The 2D SVEs are generated from cutting a 3D SVE into a number of 2D slices, see Figure 3. The same boundary conditions are applied to the 3D and 2D SVEs. The mean values of all slices are then compared to the single result obtained for the corresponding 3D SVE. In this way, the 2D/3D comparison becomes meaningful since comparison is made on the same topology.

² Superscripts M denotes macroscale, whereas s denotes subscale.

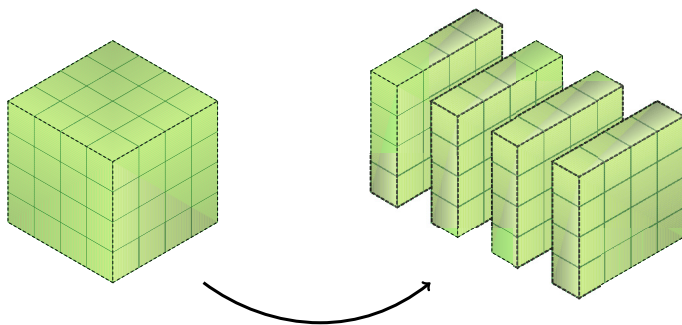


Fig. 3 3D SVE cut into 2D slices

7 Numerical Examples

7.1 3D/2D Comparison

The numerical example compares the first component of the homogenized flux tensor, $\langle \mathbf{J} \rangle_1$, as a function of the SVE size³ denoted L_\square . The RVE size based on the numerical results becomes $L_{\text{RVE}} \stackrel{\text{def}}{=} 10 \text{ cm}$ since convergence has been reached for this value of L_\square . The cement paste was assigned a unit diffusivity of $D_c = 1 \text{ cm}^2/\text{s}$, for simplicity, and $D_a = 0 \text{ cm}^2/\text{s}$. The ITZ layer is omitted in the example.

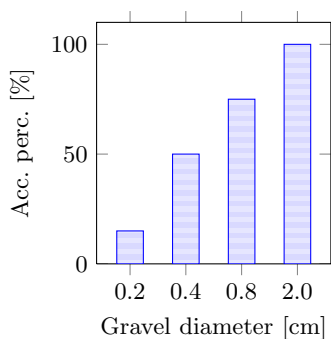


Fig. 4 Sieve curve SVEs used in the numerical example

Forty 3D SVEs were generated for each L_\square all having an aggregate volume fraction, n_a , of 0.45 with the sieve curve shown in Figure 4. Each 3D SVE was cut into 69 2D slices. Thus, μ_{2D} is the mean value of $40 \times 69 = 2760$ SVE slices for each L_\square .

³ "size" refers to side length of the cube.

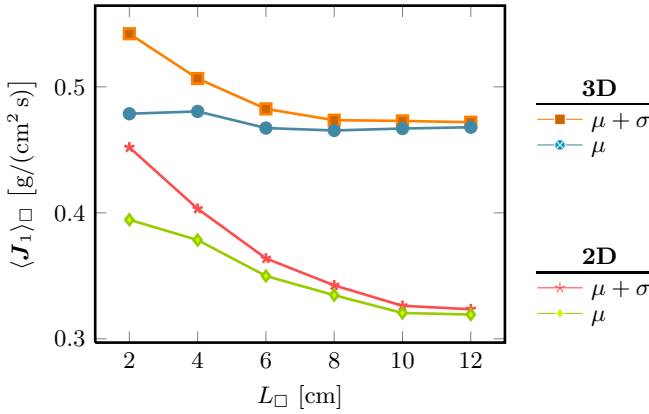


Fig. 5 Homogenized flux versus size of SVE. Average values denoted μ and corresponding standard deviations denoted σ .

The results are shown in Figure 5; they show that the 2D results in general are lower than the corresponding ones for 3D. The reason for this is probably that the out of plane solution in the 2D case is locked; hence, for the 2D case the diffusion substance has only two directions (over or under) to bypass an aggregate but in the 3D case a third direction (around) is enabled. For $L_{\square} = 10$ cm, $\mu_{2D} \approx 0.7\mu_{3D}$; i.e. the 2D SVE homogenized diffusivity is about 70 % of the corresponding 3D value.

7.2 The Effect of ITZ

The same computations as \bullet and \blacksquare in Figure 5 were carried out again now including the ITZ in the mesoscale model and the results are shown in Figure 6.

The results in Figure 6 show that it is possible to increase the effective diffusivity by utilizing the ITZ implementation as a model parameter. The results also show the robustness of the implementation as the mean values, \blacksquare , in practice become independent of the SVE size, L_{\square} . Only the spread in results, \bullet , varies and decreases with increasing L_{\square} , as expected.

The value $D_{ITZ} \times t = 0.15D_c$ has manually been calibrated such that $\langle J_1 \rangle_{\square}$ gets close to a value of 1 g/(cm² s), i.e. corresponding to a diffusivity of pure cement paste. The outcome of this numerical example is that the over-all effect of the aggregates is that they do not change the diffusivity of the bulk material. This is achieved by the implementation of ITZ in the model. In this way, the product $D_{ITZ} \times t$ becomes a useful tool for calibrating the model with experimental data.

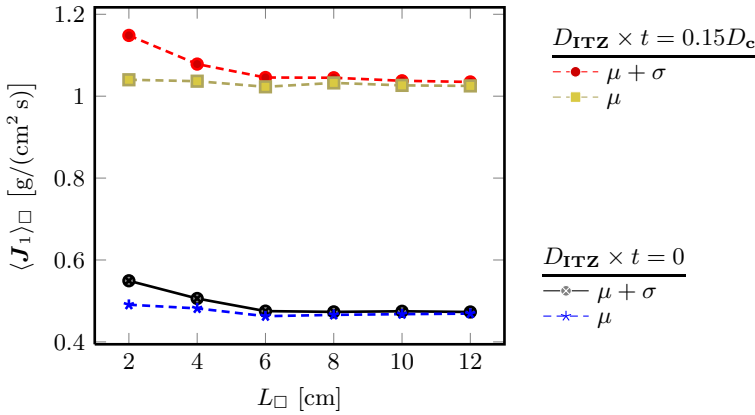


Fig. 6 Numerical results with ITZ included in the SVEs. The results for $D_{\text{ITZ}} \times t = 0$ are the same as those presented in Figure 5. $\langle J_1 \rangle = 1 \text{ g}/(\text{cm}^2 \text{ s})$ corresponds to an effective diffusivity equal to that of pure cement.

7.3 Computational Time

The computational work for this paper has been carried out on a standard laptop machine having 4 GB of RAM with a dual-core processor running Windows 7. The implementation is made in MATLAB and is parallelized to reduce computational time.

The average computational time for one 3D SVE is approximately 20 min, and approximately 0.5 min for one 2D SVE, but since the multiple SVEs can be run in parallel the total time is governed by the number of processors available.

8 Conclusions and Outlook

A 3D model of heterogeneous mesoscale concrete was presented and employed in the context of computational homogenization. The algorithm on which the model is based generates a random structure of aggregates embedded in cement paste. Any sieve curve is possible as input for the algorithm and any (realistic) aggregate content is possible to obtain.

The numerical examples presented in the paper shows that the difference between a 3D and 2D model in terms of effective diffusivity differ approximately by a factor 0.7. The numerical results further show that the ITZ implementation is robust and can be used to calibrate/adjust the effective diffusivity of cement with embedded aggregates in it, i.e. concrete. With the ITZ included in the model, it is possible to increase the effective diffusivity of concrete in an easy and consistent manner.

The next step is to use 3D SVEs to determine effective material properties as a function of aggregate volume fraction, as was done in previous work (in

2D), see Nilenius et al. [11]. The effect of ITZ on the numerical results will further be investigated so that the model can be calibrated with experimental data. Additionally, both Dirichlet and Neumann boundary conditions will be applied to obtain upper and lower bounds, respectively, on the effective material properties.

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