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Design, fabrication and measurements with a UV linear-variable optical filter microspectrometer

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ABSTRACT

An IC-Compatible Linear-Variable Optical Filter (LVOF) for application in the UV spectral range between 310 nm and 400 nm has been fabricated using resist reflow and an optimized dry-etching. The LVOF is mounted on the top of a commercially available CMOS camera to result in a UV microspectrometer. A special calibration technique has been employed that is based on an initial spectral measurement on a Xenon lamp. The image recorded on the camera during calibration is used in a signal processing algorithm to reconstruct the spectrum of the Mercury lamp and the calibration data is subsequently used in UV spectral measurements. Experiments on fabricated LVOF-based microspectrometer with this calibration approach implemented reveal a spectral resolution of 0.5 nm.

Keywords: Linear Variable Filter, microspectrometer, UV spectrometer

1. INTRODUCTION

Ultra-violet (UV) spectroscopy has many applications in pharmaceutical analysis [1], quantitative analysis of transition metals [2], atmospheric gas sensing [3] and bimolecular identification [4]. MEMS-based microspectrometers have huge potential in some of these applications, because of the small sample volume required and the fast response. Additional advantages emerge in case the fabrication of the MEMS-based optical microsystem is compatible with silicon IC technology. On-chip co-integration of the optical system with integrated circuitry enables in-system data pre-processing in the smallest possible system; the chip. Data storage provides opportunities for improving the use-interface and reducing the need for a laboratory with all the logistics associated with such a central infrastructure.

Microspectrometers operating in the UV spectral range require either a small feature size in the grating design, or an optical resonator design with a cavity width less than 200 nm (when operated in the 300-400 nm band). Fabrication and electronic modulation of a resonator with such a narrow air-gap between the two mirrors is severely hindered by capillary forces inside of the cavity. Also, electrostatic pull-in and subsequent sticking of the two mirrors limits the operating range of the device to one third of the initial air gap [5]-[6].

These problems are avoided in UV Linear Variable Optical Filters (LVOF) fabricated in post-processing steps after completion of the UV photodetector array and circuits in a standard IC technology [6]. Such a LVOF-based microspectrometer was reported for visible spectral range by combining a LVOF with a CMOS camera [7]. In this paper, we present the optical design, implementation and signal processing required for implementing of a LVOF microspectrometer in the UV spectral range. The general basic idea was presented earlier in [8].

2. DESIGN AND FABRICATION OF A UV LVOF

Figure 1 shows a tapered Fabry-Perot type of Linear Variable Optical Filter (LVOF). Collimated light is projected on the surface of the LVOF. The light passing through the LVOF is pass-band determined by the width of the local resonator, and thus by the spatial position along the length of the LVOF [9].





The LVOF is basically a one-dimensional array of many Fabry–Perot (FP)-type of optical resonators. Rather than a huge number of discrete devices, the LVOF has a center layer (the resonator cavity) in the shape of a strip and a thickness that changes over its length. Dielectric mirrors are on either side. Thus the narrow passband wavelength of the LVOF varies linearly along its length. A detector array positioned underneath the LVOF is used for recording the spectrum of the incident light.

The UV LVOF is intended to operate in the wavelength range in between 320 nm and 400 nm. The filter design critically depends on the choice of the materials used for the high-n and low-n layers. The ratio between the indexes of refraction should be maximum, whereas absorption in the materials should be minimum. A suitable choice for materials in the intended UV spectral range involves HfO_2 and SiO_2 as respectively high-n and low-n materials. Since the optical parameters of these materials do depend on the details of the deposition technique used, the refractive indexes have been measured by ellipsometry. Table 1 shows the designed thickness of the layers used for the multilayered LVOF, using HfO_2 and SiO_2 . Figure 2 shows the measured refractive indexes of HFO_2 and SiO_2 in the wavelength range between 280 nm and 1000 nm. The extinction coefficient in both materials is considered to be negligible for wavelengths above 270 nm.

Table 1. Layers thicknesses of multilayered UV Linear Variable Filter

Material	Thickness (nm)
HfO ₂	43.5
SiO ₂ /HfO ₂	59/43.5
SiO ₂	440-600
HfO ₂ /SiO ₂	43.5/59
HfO ₂	43.5



Fig. 2: Refractive indexes of HfO₂ and SiO₂

The thickness of the tapered cavity layer changes linearly from 440 nm to 600 nm to cover the spectral range of interest. The spectral response of the filter is simulated using TFCalc® 3.3 and the result is shown in Figure 3.



Fig. 3: Simulated spectrum of the LVOF for different values of the cavity thickness

It should be noted that the simulations at the designed values of the layers reveals two different wavelengths that are transmitted through the filter at any value of the cavity thickness (any position along the LVOF). These two wavelengths are from different resonance orders and their wavelength separation limits the Free Spectral Range (FSR). Increasing the thickness of the cavity from 440 nm to 600 nm (with transmission as indicted by the curves from bottom to top in Figure 3) covers the spectral range of 315 nm to 350 nm in one of the resonance orders, while the other covers the range between 350 nm and 400 nm.

The maximum reflecting bandwidth of a Bragg reflector, which is the basic element in the structure of the LVOF, can be calculated from Eq. (1).

$$\frac{\Delta\lambda}{\lambda_0} = \frac{4}{\pi} \operatorname{Arc} \sin\left(\frac{n_2 - n_1}{n_2 + n_1}\right) \tag{1}$$

In which $\Delta\lambda$ is the maximum reflecting bandwidth, λ_0 is the reference wavelength and n_2 and n_1 are refractive indexes of the dielectric materials. However, the maximum value of the FSR limits the bandwidth to $\Delta\lambda/2$. Increasing the thickness of the cavity layer implies a higher operation mode for the Fabry-Perot structure of the LVOF, which results in higher spectral resolution (smaller Full-Width-Half-Maximum, FWHM), but a smaller FSR. For HfO₂ and SiO₂ and a reference wavelength of $\lambda_0 = 350$ nm, the maximum stopband of the dielectric mirrors results from (1) as $\Delta\lambda = 84$ nm. Consequently, the FSR=42 nm. The transmission at two different resonance orders has been used for optical characterization of the LVOF and the results are shown in Section 4.

Fabrication involves an IC-Compatible reflow process [10]. Initially, layers 1-10 were sputtered on the substrate. Sputtering of the dielectric layers has been done in the FHR MS 150 sputtering machine. It is possible to achieve an optical thickness variation of the layers less than 2%. Photoresist was spin-coated and patterned by a special pattern optimized to produce a linear slope after reflow. The tapered resist pattern was transferred into a SiO_2 cavity layer by a dry-etching process that was optimized for minimum surface roughness.

Figure 4 shows a photograph of the fabricated UV LVOFs. The rainbow pattern on the LVOFs is the result of the slope of the structures. The IC-compatible process for fabrication of the tapered layers allows the possibility for fabrication of devices with a different slope with one lithography step. Because of smaller wavelength in the UV spectrum, as compared to visible spectra, the roughness is more critical in the UV spectral range. The roughness of the surface of the fabricated devices was measured by ellipsometry. Results show a roughness of 4 nm.



Fig. 4. Photograph of UV LVOFs fabricated on glass substrates.

The structure of an LVOF-based microspectrometer is shown in Figure 5. Light passes an aperture and collimating optics before being projected onto the LVOF, which is placed or deposited on the top of the detector.



Fig. 5. Structure of a LVOF microspectrometer

From Figure 5 it can be found: $f = \frac{D}{2NA}$, in which D is the length of the LVOF, f is the focal length of the lens and

NA is entrance numerical aperture. The Smith–Helmholtz invariant theorem, [11], results in $d \times NA=D \times \varphi$, which can be rewritten as: $d=D \times \varphi/NA$. In which, *d* is the diameter of the aperture and φ is maximum acceptable angle of incidence on the LVOF. Since *d* depends on φ , the transmission at the position with peak transmission at 349.5 nm simulated for different angles of incidence. The result is that a 5° deviation from the normal incident the spectral peak of transmission results in a spectral shift over about 0.4 nm. Therefore, the angle of incidence is limited to $\varphi_{max} = 5^\circ$ for a maximum spectral inaccuracy of 0.5 nm. The value $\varphi=5^\circ$ is inserted in equation (2). Considering a LVOF with a length of 5 mm

and assuming NA = 0.25 results in $f = \frac{D}{2NA} = 10$ mm for the focal length of collimating optics. The aperture size is

calculated as mentioned and yields: $d = \frac{D\varphi}{NA} = \frac{5\text{mm} \times 5^{\circ}}{0.25\text{rad}} \approx 1.7\text{mm}$. This determines the maximum value of the aperture

size, *d*. Therefore, the aperture size in an LVOF-based system is limited by the acceptable spectral shift. A further reduction of aperture improves spectral accuracy at the expense of optical throughput: the amount of light entering the optical system would decrease.

Collimating optics has been designed and implemented in a C-mount holder put on the top of the CMOS camera. Although a C-mount holder is relatively bulky, it is a convenient solution when parameters of collimating optics need to be changed for different experiments. In a final microspectrometer design the C-mount holder has to be replaced with a miniaturized version.

3. CHARACTERIZATION AND CALIBRATION OF UV LVOF

Collimated monochromatic light has been projected on the LVOF mounted on the CMOS camera. The wavelength of the projected light changes from 320 nm to 400 nm with 0.5 nm steps, using a programmed monochromator, and results in 161 spectral channels. Figure 6 shows the recorded image on the LVOF spectrometer for different wavelengths in the range from 315 nm to 400 nm. We can see the reoccurrence of illuminated regions on the images at increment of about 40 nm. This is due to 42 nm Free Spectral Range (FSR) as explained previously. The recorded intensity profile on the camera pixels is normalized at each wavelength by dividing it to the measured camera responsivity.



Fig. 6. Recorded image at several wavelengths.

The Half-Power-Line-Width (HPLW) of illuminated regions equals to 9 pixels, which is equivalent to 54 µm spatially and 1.2 nm in terms of resolution. The measured intensity profile recorded by the camera at each wavelength using this monochromator scan is imported (without normalization) into a signal processing algorithm to result in the LVOF microspectrometer calibration matrix, which can subsequently be used for calculation of any spectrum incident on the UV LVOF. The signal processing required is similar to that described in [12] and presented for a visible microspectrometer in [13]. The technique is summarized here.

Let us assume the spectral bandwidth of interest is divided into N spectral channels and there exists N spectrally different (independent) detectors. The element C_{ij} in matrix C is defined as the intensity of channel *i* of the detector to component *j* in the spectrum (*i*, *j* = 1...N). The matrix C can be directly constructed from the data of a calibration measurement process. The maximum value of N is the number of the pixels on the camera, but can be limited by the spectral capability of the calibrating instrument (a monochromator). Hence, the measured intensity on the detector channels can be described as: $D_{IN} = C_{NN}$. I_{IN} (3)

In which d_i denotes the measured intensity in channel *i* and I_i denotes the input spectrum intensity in channel *i* that has to be calculated. In other words, Matrix D_{IN} is the raw data recorded on the camera pixels, matrix I_{IN} is the spectrum of light that has to be calculated and matrix C_{NN} is the calibration matrix, which is determined during the calibration process. In the Calibration process, the light from a broadband source (Xenon lamp) is filtered by a monochromator and the selected wavelength is varied in the spectral range of interest for all the N spectral channels. For each spectral channel from the above equations, calibration is equivalent to deliberately having: $I = [0, 0, ..., 0, I_m = 1, 0, ..., 0]$ when channel *m* is selected from the monochromator. In this case the recorded intensities on the pixels give the values of column *m* of the

C matrix:
$$D_{IN} = C_{NN}$$
. $I_{IN} = [c_{1m}, c_{1m}, ..., c_{Nm}]$.

Repeating the procedure for all the N spectral channels, results in determination of C_{NN} matrix. For a properly designed and fabricated LVOF, Matrix C has no singularity and it is possible to take the inverse transform of the matrix. Therefore, matrix I can be calculated as $I_{IN} = C_{NN}^{-1}$. D_{IN} . However, since the measured matrix D is added with noise the above solution does not give the best answer. The sources of the disturbance (or noise) in the measured raw data include primarily insufficient collimation, out of the band signal and errors in the estimation of the Calibration matrix (due to inaccuracy in the monochromator instrument). If the disturbance in the system is not negligible as compared to the signal (low SNR) the above approach would result in negative values in some spectral channels, which is not physically acceptable. An iterative procedure needs to be implemented to calculate the matrix I by minimizing matrix E:

$$E = D_{IN} - C_{NN} \cdot \hat{I}_{IN} \tag{4}$$

In which matrix \hat{I}_{NN} is the estimate of *I*. The Least Mean Square (LMS) algorithm is implemented based on the following equations:

$$E_{n} = d - C.\hat{I}_{n}$$

$$\hat{I}_{n+1} = \hat{I}_{n} + \mu C.E_{n}$$
(5)

 E_n denotes the error and \hat{I}_n denotes the estimate of the spectrum at each recursive step. μ is the convergence coefficient. A higher value for μ results in faster convergence of the algorithm. However, it can also result in divergence (i.e. instability) of the algorithm. The goal of the algorithm is to decrease the mean square of E_n at each step. This results in the best possible estimate for the spectrum vector \hat{I} . The value of E_n remains non-zero, due to noise and disturbances in the measurements.

4. SPECTRAL MEASUREMENTS

This LVOF-based microspectrometer is intended for use in the spectral band in between 310 and 400 nm. The total number of channels is 201 each 0.5 nm wide. The data from the calibration measurement (characterization) is imported into the signal processing algorithm to construct the Calibration matrix, C_{NN} , as introduced in the previous Section.

The objective is to measure the spectrum of a Mercury lamp in the UV spectral range. The Mercury lamp has a high intensity in this spectral range and demonstrates a unique spectrum. The result is shown in Figure 7. Two Schott glass filters, types Ug1 and Ug11, have been used to eliminate the unwanted part of the spectrum. Ug1 has a passband in 300 nm -400 nm spectral range and Ug11 has the passband in between 250 nm and 390 nm. As is shown from the measurement with Ug11, the spectrum for wavelength longer than 380 nm is eliminated. Therefore, in our measurements with LVOF we have used Ug1 filter to selectively remove the unwanted part of the spectrum.



Fig. 7. Measured spectrum of the Mercury lamp, including the effect of the UG1 and UG11 filters.

Figure 8 shows the recorded image on the LVOF camera when illuminated by the Mercury lamp. The image shows three UV LVOFs with different sizes and slopes. We can note the distortions of the bright spectral lines at the sides of the structures, which are due to the reflow process step in the fabrication. This can be prevented in an optimized process. Moreover, data from these parts of the LVOF are neglected in the further calculations. The spectral peaks can be readily identified from the image.



Fig. 8: Image recorded by the UV LVOF microspectrometer when illuminated by a Mercury lamp.

The data from the image is imported to the signal processing algorithm to extract the spectrum. Figure 9 shows a comparison between the spectrum after applying the algorithm and the measurement with a TRIAX 180 monochromator.

The entire spectral range of the LVOF, 320 nm to 415 nm has been used in this spectral calculation. From the comparison we can note an extra spectral peak predicted by signal processing algorithm at 385 nm, which is not present in the measurement with the monochromator. This is most probably due to the strong spectral peak of the mercury lamp at 405 nm, which is not completely filtered by the UG1 filter. Considering the much higher sensitivity of the CMOS camera at 405 nm, we can expect that any out-of-band light at higher wavelengths can have a strong negative effect on the performance of the system. The other characteristic difference is the lower calculated baseline of spectral power in the calculated spectrum.



Fig. 9. Calculated spectrum from the LVOF compared with measurement by a monochromator. The spectral response of the CMOS pixels was taken into account in the calculation.

5. CONCLUSIONS

The design and implementation of a Linear-Variable Optical Filter (LVOF)-based microspectrometer for operation in the UV spectral range is presented in this paper. The IC-Compatible fabrication enables a very compact and rigid microspectrometer system.

The strength of the LVOF-based microspectrometer concept is the high resolving power in a relatively narrow band, which makes it particularly suitable in applications where the spectral analysis around an absorption or emission peak is required, such as in fluorescence. The designed operating range is between 320 nm and 415 nm. The spectral resolution of the basic microspectrometer is significantly improved by using signal processing to calculate the spectrum of light recorded by the image detector.

First prototypes are bulky because of the C-mount. However, the essential optical path is only 10 mm \times 5 mm. The spectral resolution of the basic LVOF is about 1.5 nm and is improved to 0.5 nm after application of signal processing.

The most significant limitation at this stage is the low sensitivity of the diodes in the imager in the UV part of the spectrum. The system will be further miniaturized by direct deposition of the LVOF on a customized CMOS imager that is sensitive in the UV range. Collimating optics need also to be miniaturized. The design procedure, fabrication and signal processing of the UV LVOF remain the same.

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